

# Fault weakness during seismic slip



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**29th Course of the INTERNATIONAL SCHOOL OF GEOPHYSICS**

**Erice, 26 September 2007, Italy**

**S'Venerina Earthquake (Sicily, 2002)**

# Outline

## 1. Rock friction

## 2. HV rock friction experiments (HVRFE)

- 2a. Silica gel lubrication

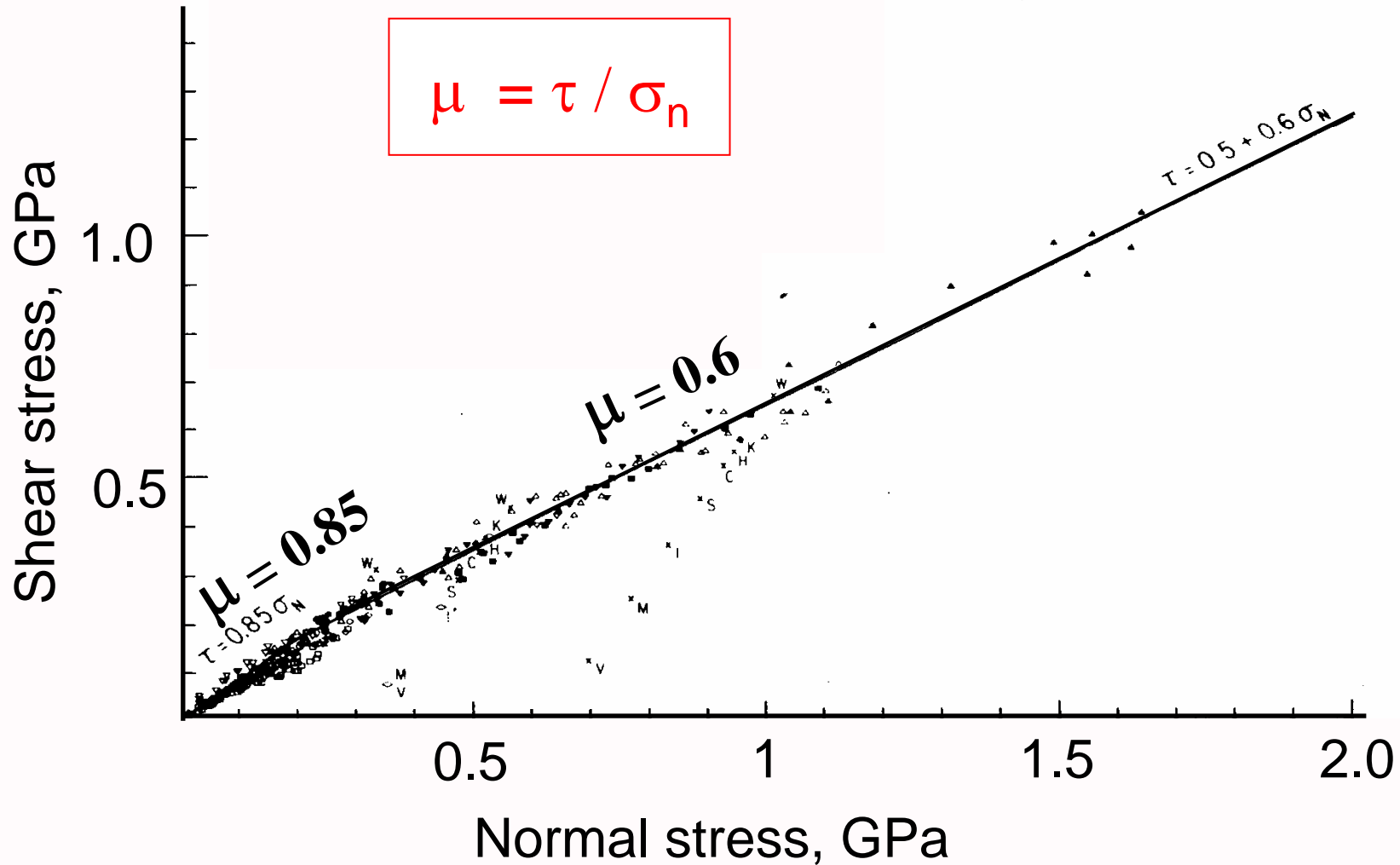
- 2b. Flash heating and dehydration weakening

- 2c. Thermal decomposition weakening

- 2d. Gouge-related weakening

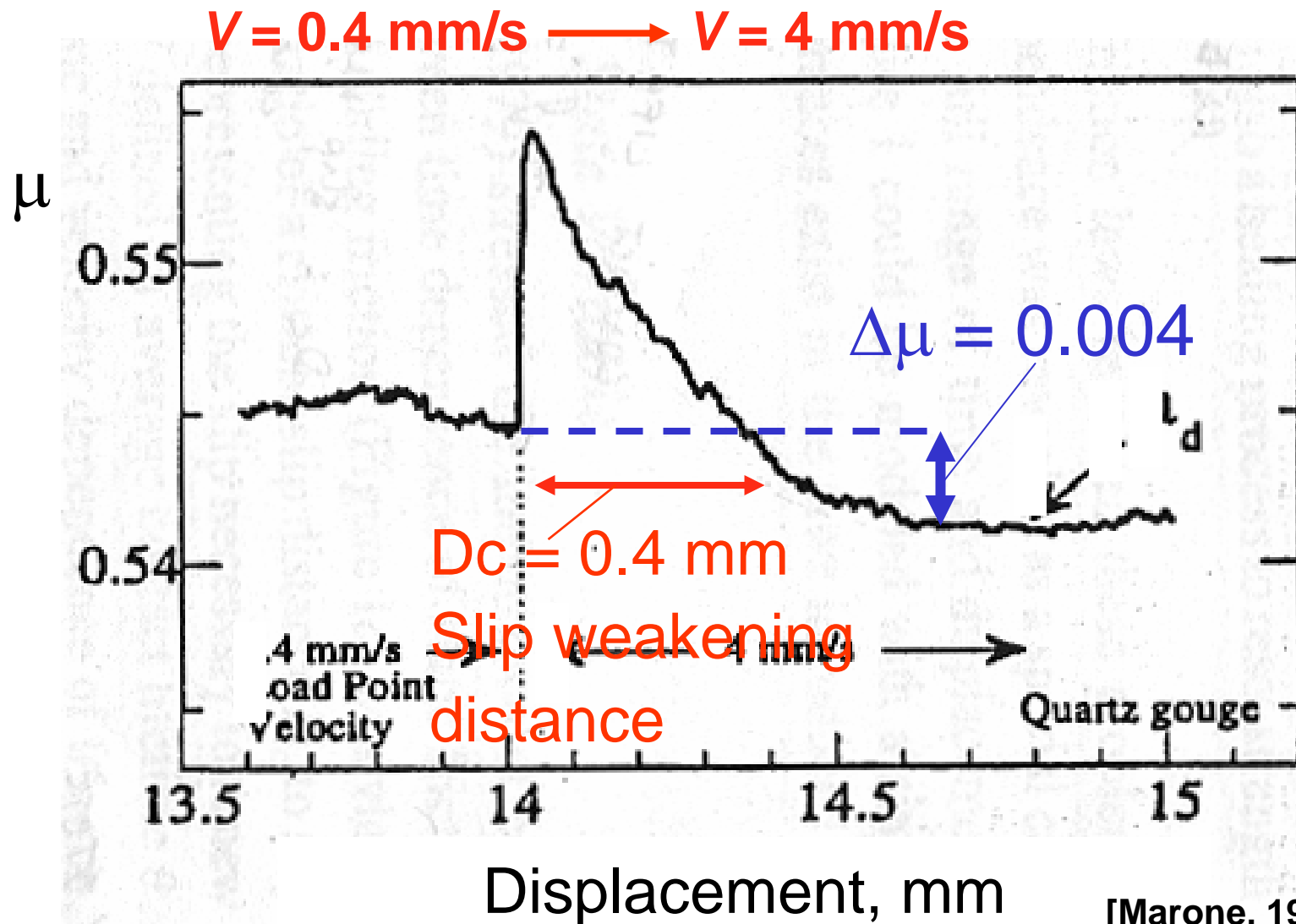
## 3. Extrapolation of experimental data to seismic slip: the case for melt lubrication

At slow slip rates ( $< 1$  mm/s) and for short displacements ( $< 1$  cm) rock friction ( $\mu$ ) is 0.6-0.8



[Byerlee, PAGEOPH, 1978]

For small changes in  $V$ ,  $\mu$  varies of few % and the slip weakening distance is few hundreds microns



[Marone, 1998]



These experimental results found broad application in EQ mechanics.

But during earthquakes

- Slip rates of **0.1- 4 m/s (or ~ 1 m/s)**
- Displacements **up to 20 m**
- Dc (estimated to be) of **0.5 - 4 m**

**Reduction in strength** during EQ might determine:

1. Whether dynamic stress drop is larger than static stress drop.
2. Rupture propagation mode: self-healing pulse vs. crack-like.
3. Increase in the ratio of radiated energy vs. seismic moment with EQ size.
4. Low heat production during coseismic slip.

# Fault weak. mech. proposed till 2001

$\mu$

1. **Thermal pressurization of pore fluids** **0.0?**  
[*Sibson, 1973*]
2. **Normal interface vibrations** **0.0?**  
[*Brune et al., 1993*]
3. **Acoustic fluidization** **0.0?**  
[*Melosh, 1996*]
4. **Frictional melting (?)** **0.6-0.5**  
[*Spray, 1993; Tsutsumi and Shimamoto, 1997*]
5. **Flash heating** **0.0?**  
[*Rice, 1999*]
6. **Elastohydrodynamic lubrication** **0.0?**  
[*Brodsky and Kanamori, 2001*]

experimental data for rocks in yellow

# Fault weak. mech. proposed 2002-2007

$\mu$

- |  |                 |
|--|-----------------|
| <b>1. Gouge-related weakening</b>                          | <b>&lt; 0.2</b> |
| <i>[Chambon et al., 2002; Mizoguchi et al., 2007]</i>      |                 |
| <b>2. Silica gel lubrication</b>                           | <b>0.2</b>      |
| <i>[Goldsby and Tullis, 2002]</i>                          |                 |
| <b>3. Melt lubrication</b>                                 | <b>0.1</b>      |
| <i>[field &amp; exper. evidence, Di Toro et al., 2006]</i> |                 |
| <b>4. Flash heating and dehydration weakening</b>          | <b>0.1</b>      |
| <i>[Hirose and Bystricky, 2007]</i>                        |                 |
| <b>5. Thermal decomposition weakening</b>                  | <b>0.1</b>      |
| <i>[Han et al., 2007]</i>                                  |                 |

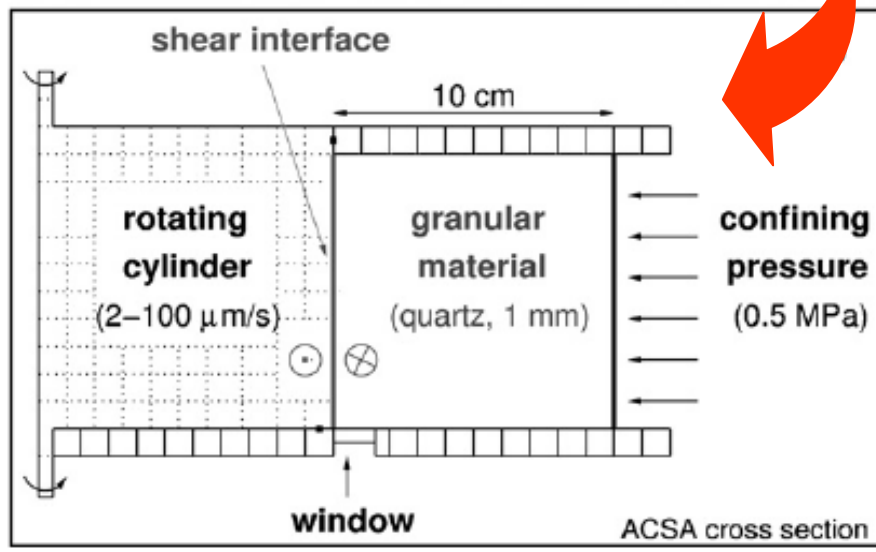
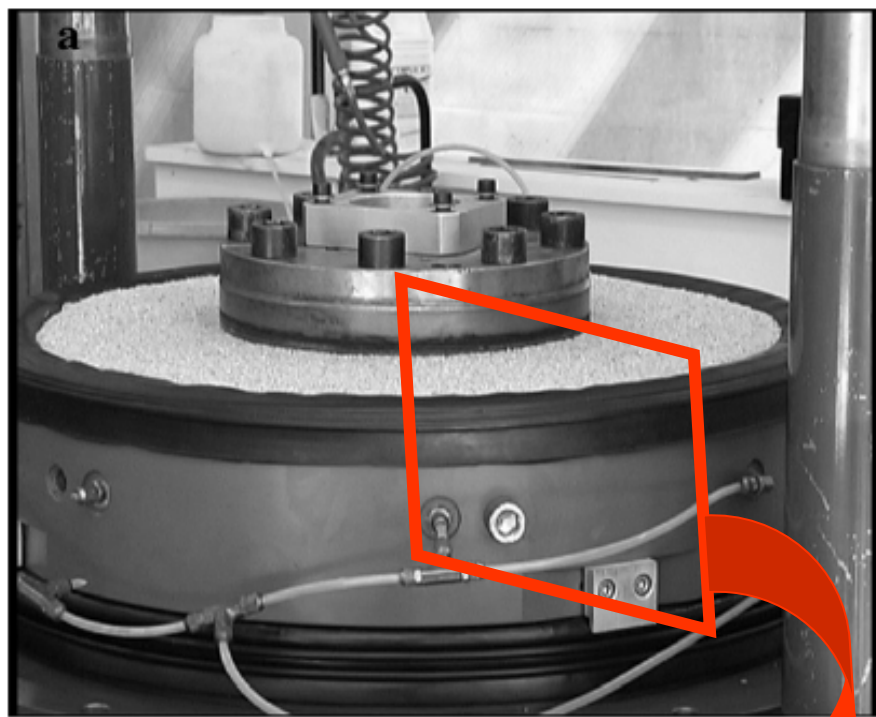
experimental data for rocks in yellow



Why all these new  
mechanisms?

New PhDs, new experiments  
and new machines...

# Annular Simple Shear Apparatus

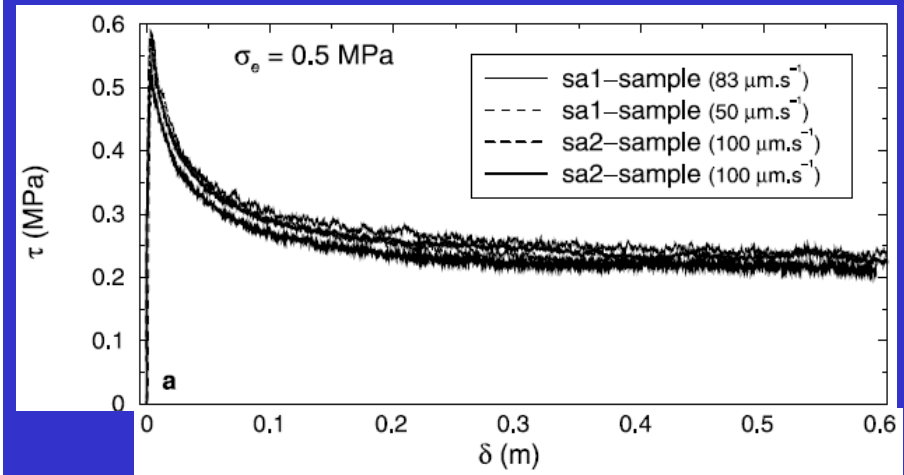


$$\sigma_n < 1 \text{ MPa}$$

$$v = 0.001 - 0.1 \text{ mm/s}$$

$$d < 50 \text{ m}$$

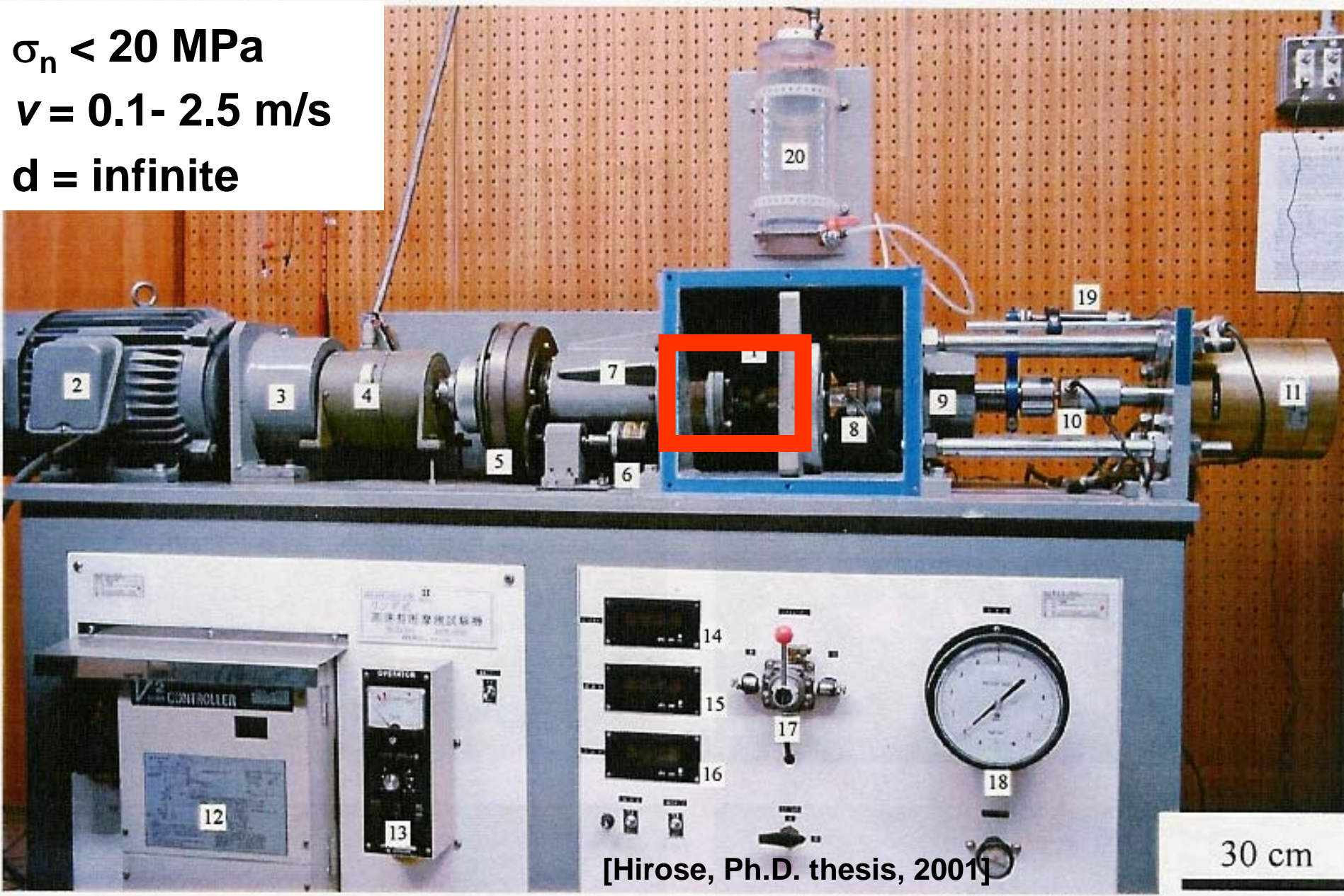
Non-cohesive rocks



[Chambon et al. JGR, 2006]

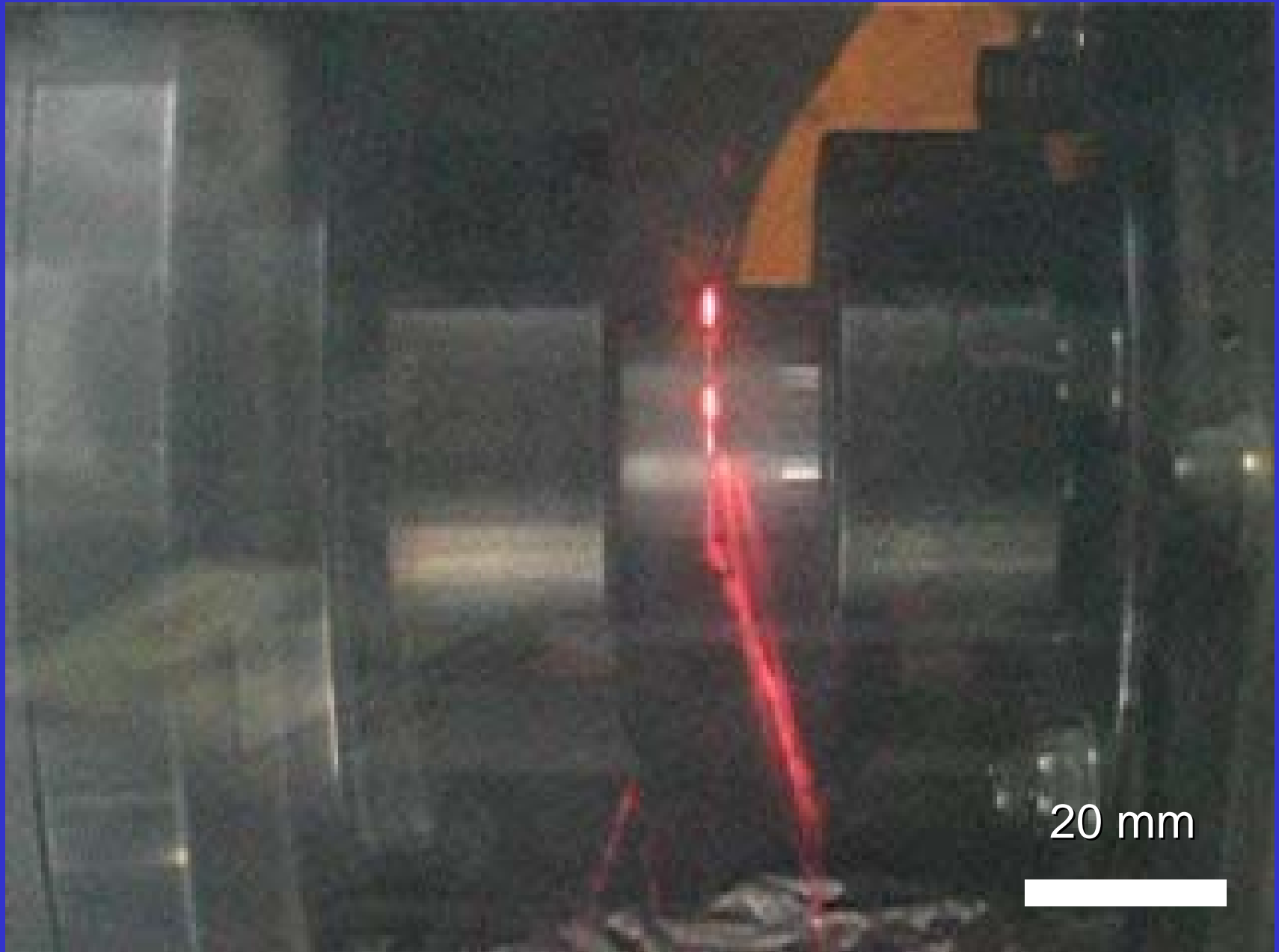
# HV rotary shear (1990, Kyoto) designed by Shimamoto

$\sigma_n < 20 \text{ MPa}$   
 $v = 0.1 - 2.5 \text{ m/s}$   
 $d = \text{infinite}$



[Hirose, Ph.D. thesis, 2001]

**Tonalite,  $v = 1.3$  m/s,  $\sigma_n = 20$  MPa**





Higher performing machines  
are under development  
nowadays...

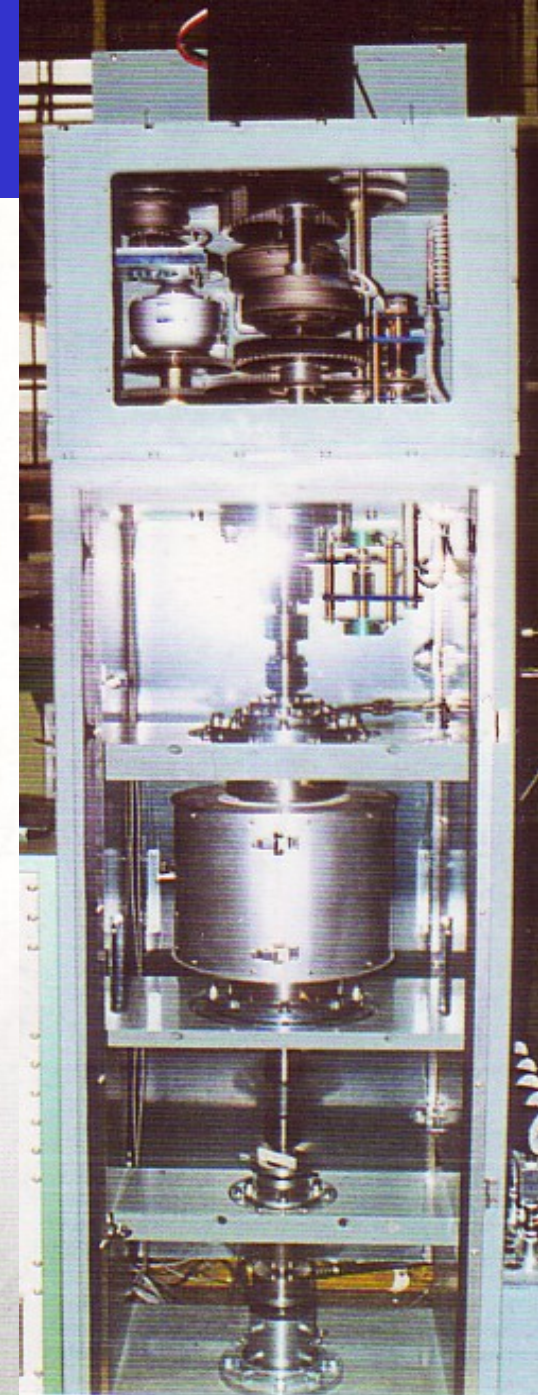
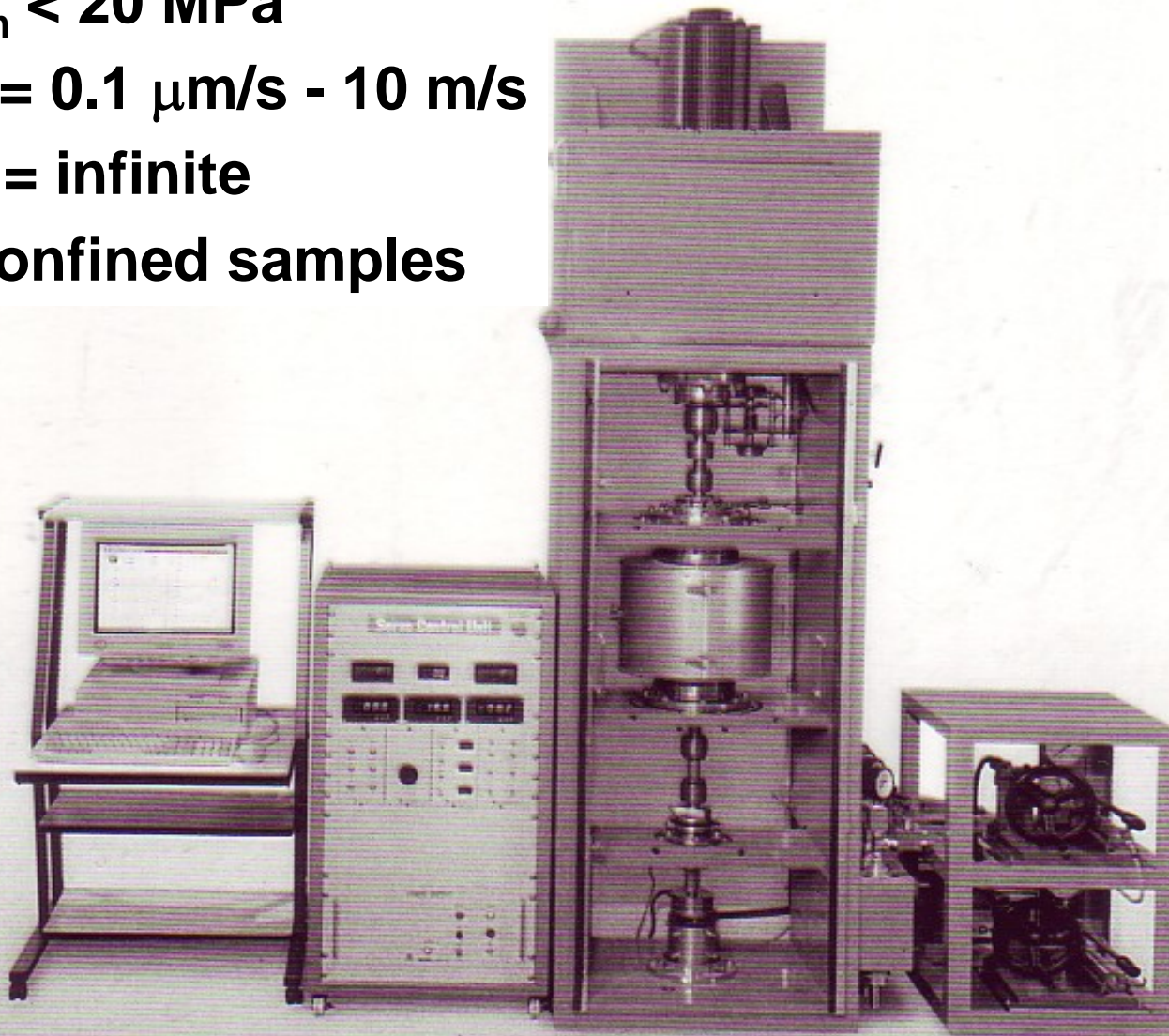
# HV-Rock Friction Apparatus (2000-07) designed by Shimamoto (Hiroshima, JPN)

$\sigma_n < 20 \text{ MPa}$

$v = 0.1 \text{ } \mu\text{m/s} - 10 \text{ m/s}$

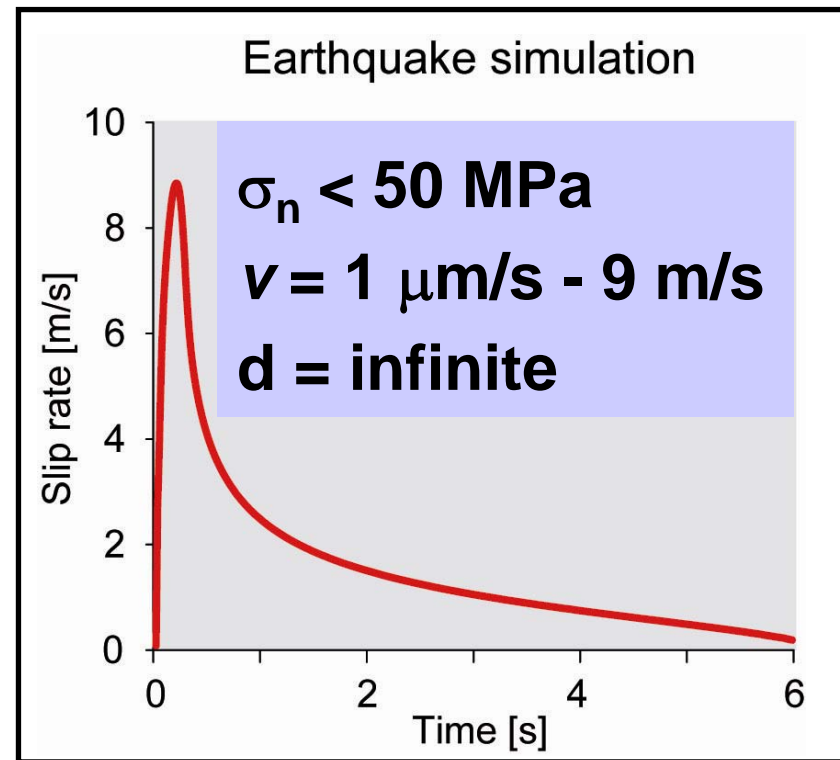
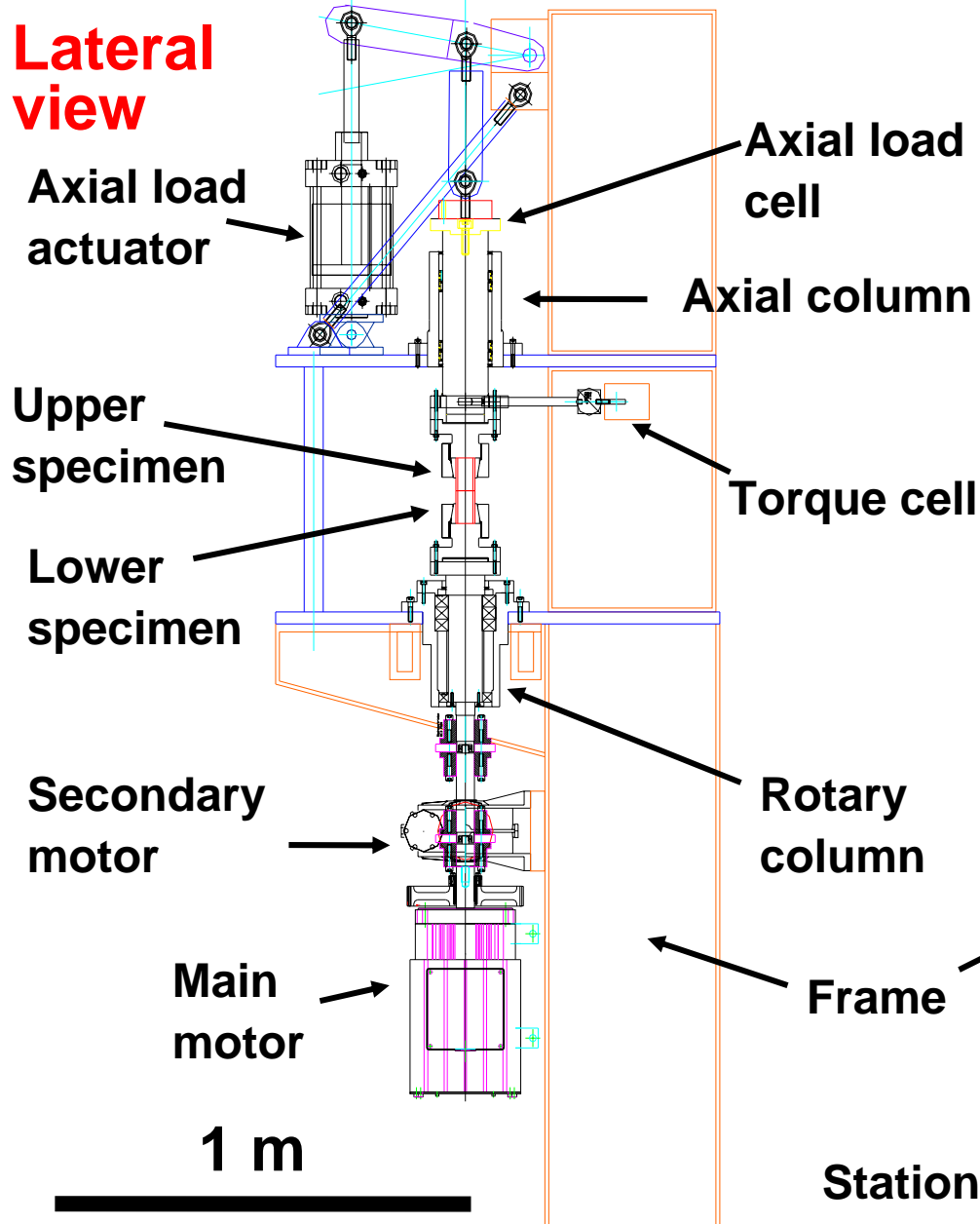
$d = \text{infinite}$

Confined samples

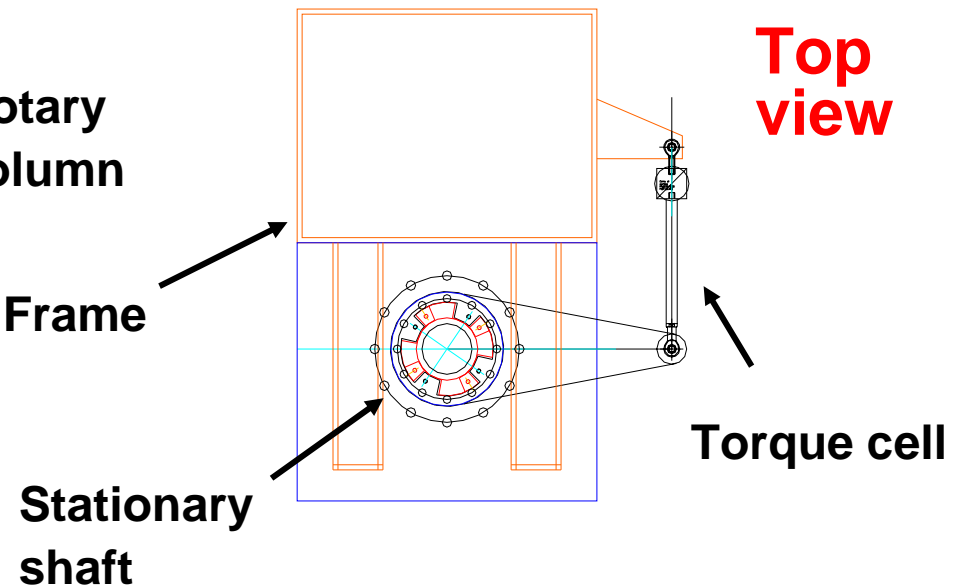


# INGV in Rome?

## Lateral view



## Top view



# Outline

## 1. Rock friction

## **2. HV rock friction experiments (HVRFE)**

### **2a. Silica gel lubrication**

2b. Flash heating and dehydration weakening

2c. Thermal decomposition weakening

2d. Gouge-related weakening

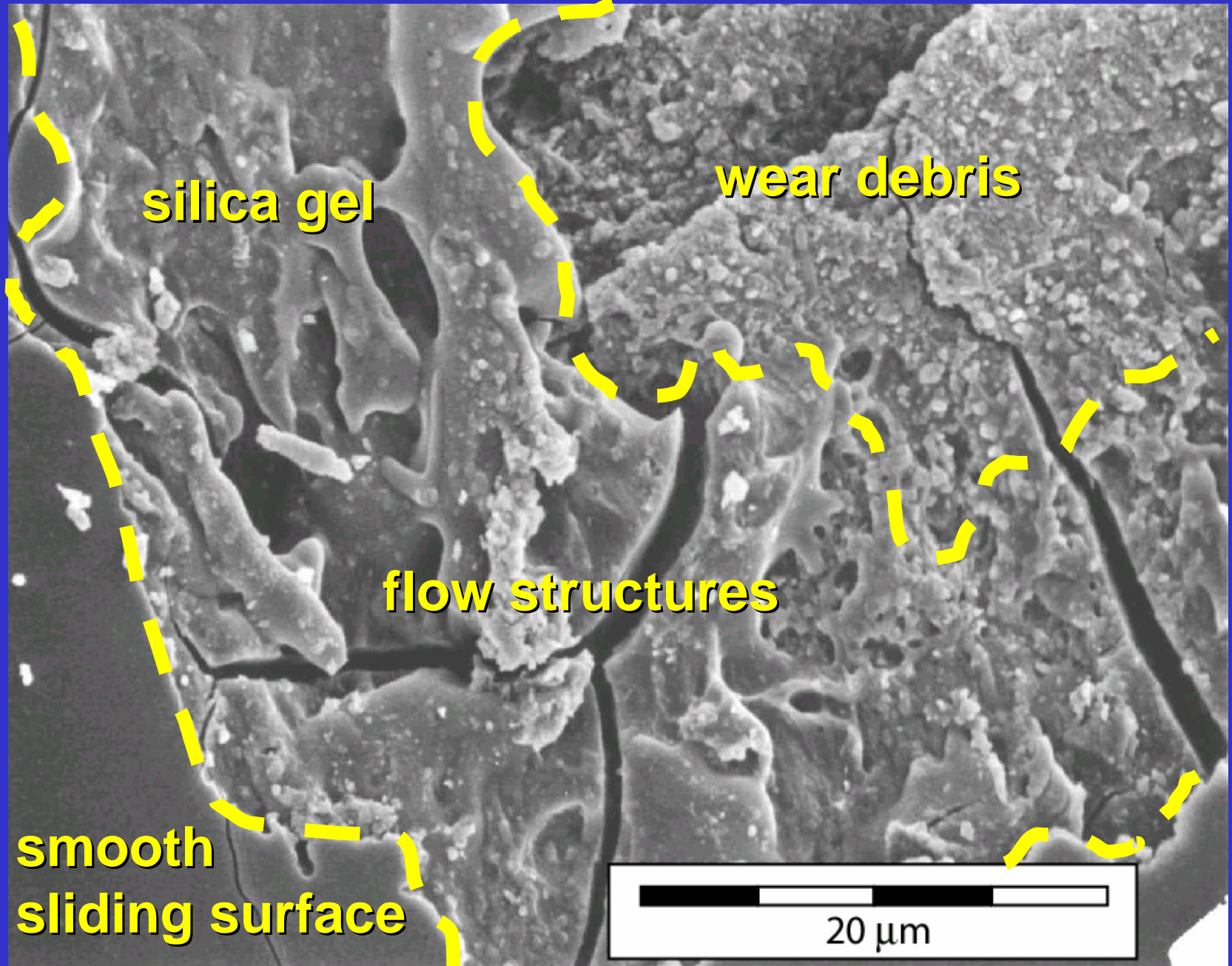
## 3. Extrapolation of experimental data to seismic slip: the case for melt lubrication



# Novaculite (= 100% quartz) sample after the high velocity experiment



# SEM image of the sliding surface after the exp.

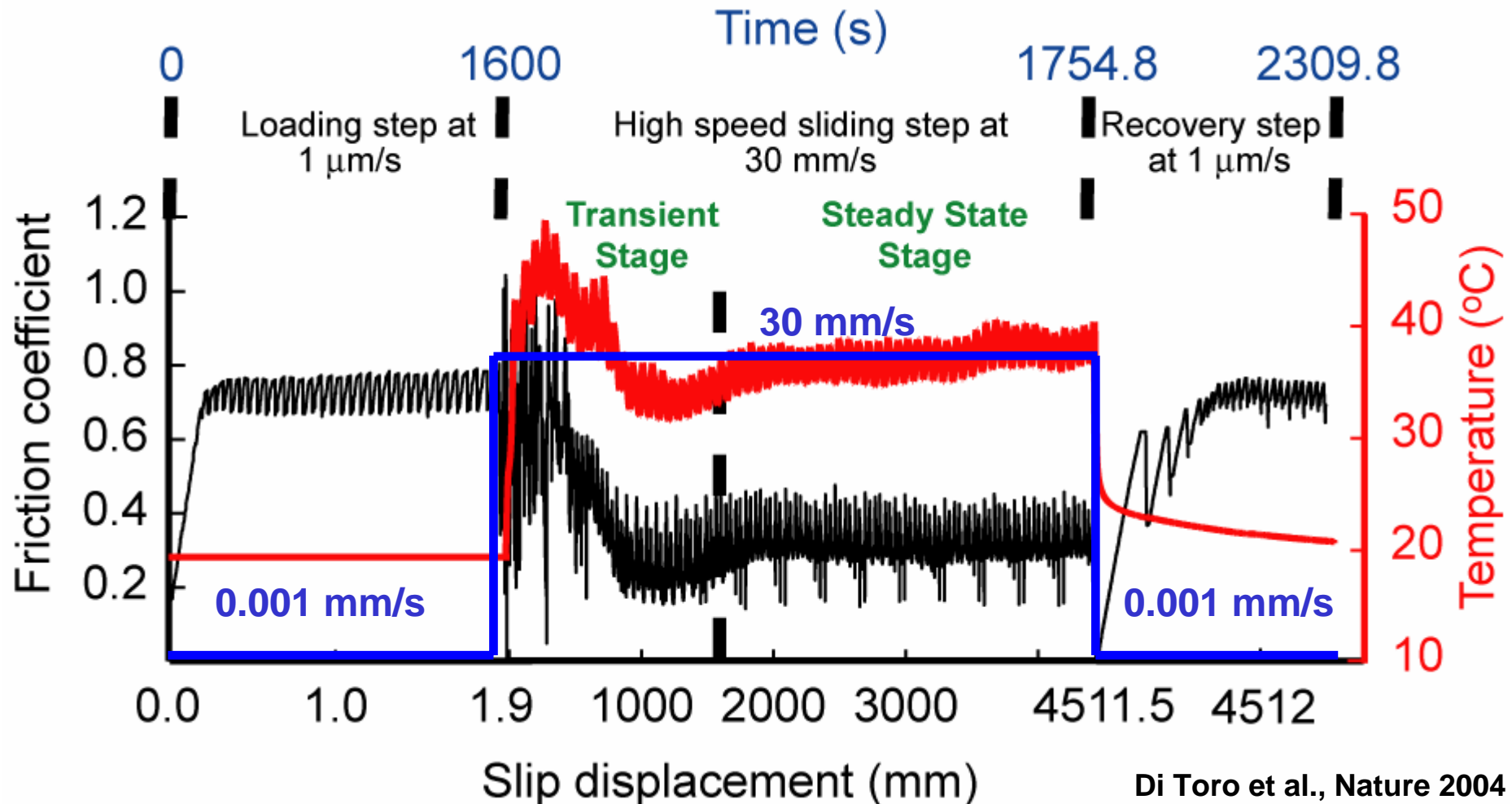




$\mu$  and T are low during slip:

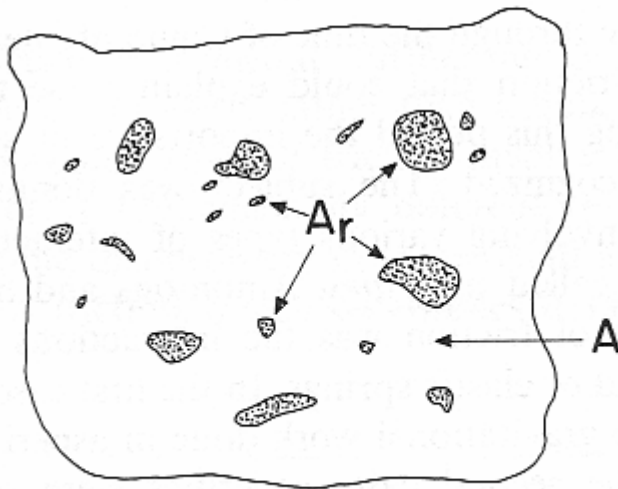
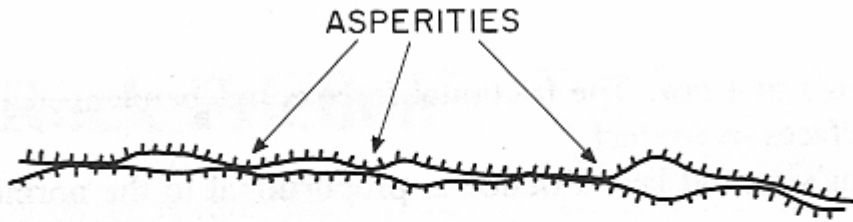


## SILICA GEL LUBRICATION



# Flash heating at the asperity contacts

[Archard, 1958/59]



[Scholz, 1990]

$$\Delta T \cong \mu_{ss} \frac{\pi r p_m}{4K} V$$

$r = 10 \mu\text{m}$  asperity radius

$p_m = 8.0 \text{ GPa}$  quartz yield press.

$K = 3.8 \text{ W m}^{-1} \text{ K}^{-1}$  thermal cond.

$$T_{max} \sim 300 \text{ }^{\circ}\text{C}$$

Quartz melts at  $1713 \text{ }^{\circ}\text{C}$   
[Richet et al., 1982]



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**2b. Flash heating and dehydration weakening**

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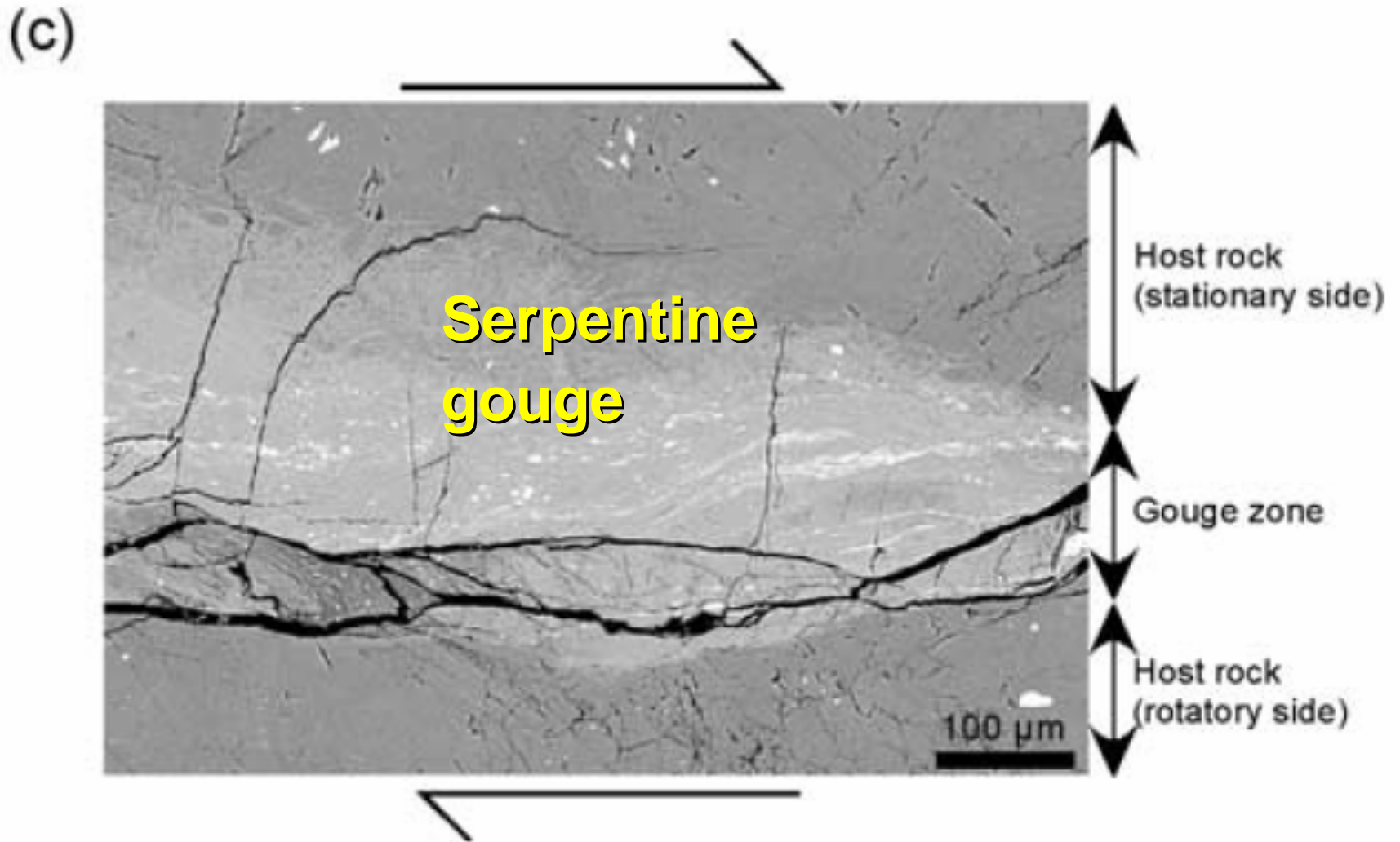
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# Serpentinite samples before the high-velocity exp.



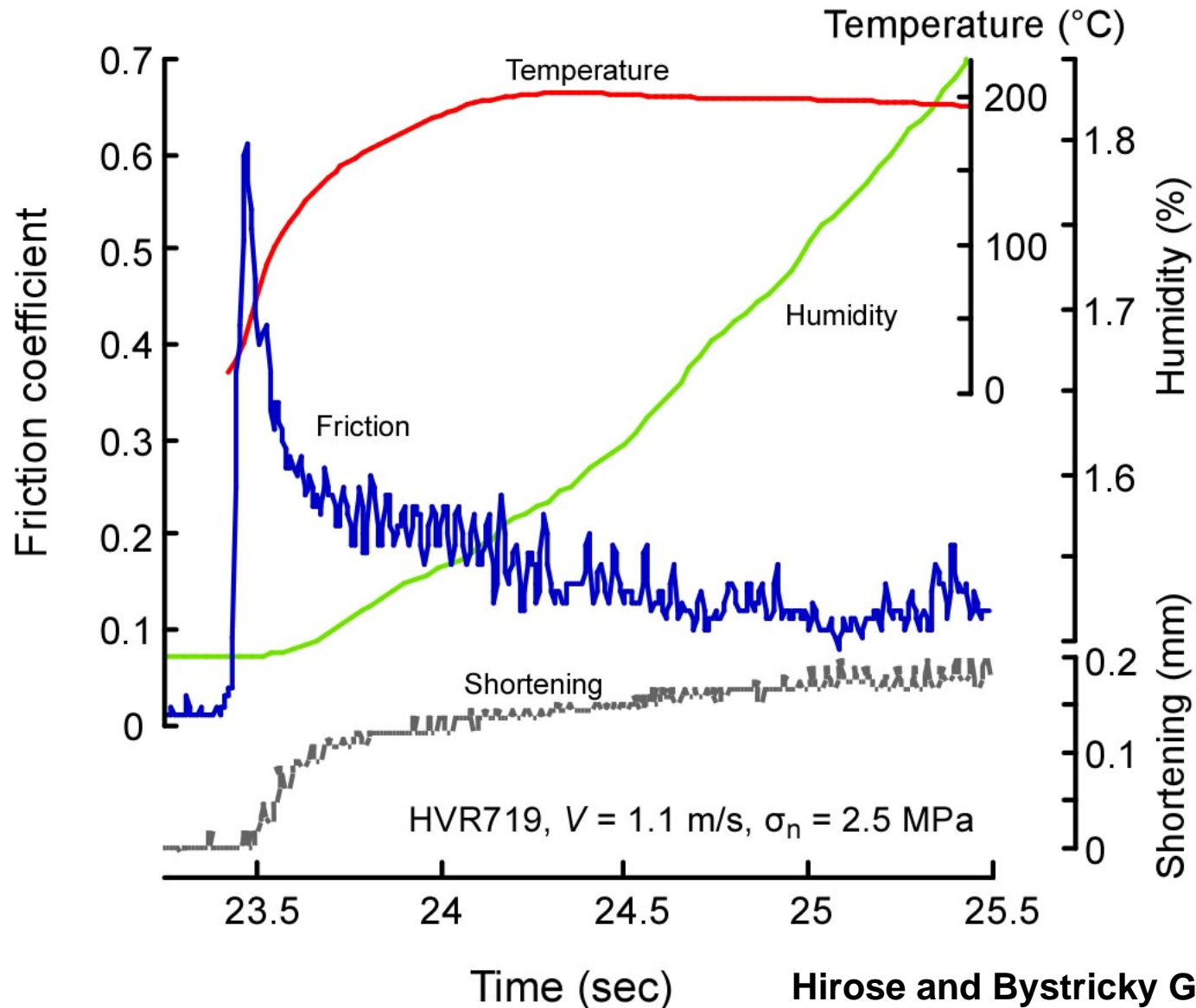
Courtesy of  
Hirose-san

# SEM image of the slipping zone after the exp.



$\mu$  is low; T increase = dehydration

# DEHYDRATION INDUCED BY FLASH HEATING



# Outline

## 1. Rock friction

## 2. HV rock friction experiments (HVRFE)

2a. Silica gel lubrication

2b. Flash heating and dehydration weakening

**2c. Thermal decomposition weakening**

2d. Gouge-related weakening

## 3. Extrapolation of experimental data to seismic slip: the case for melt lubrication

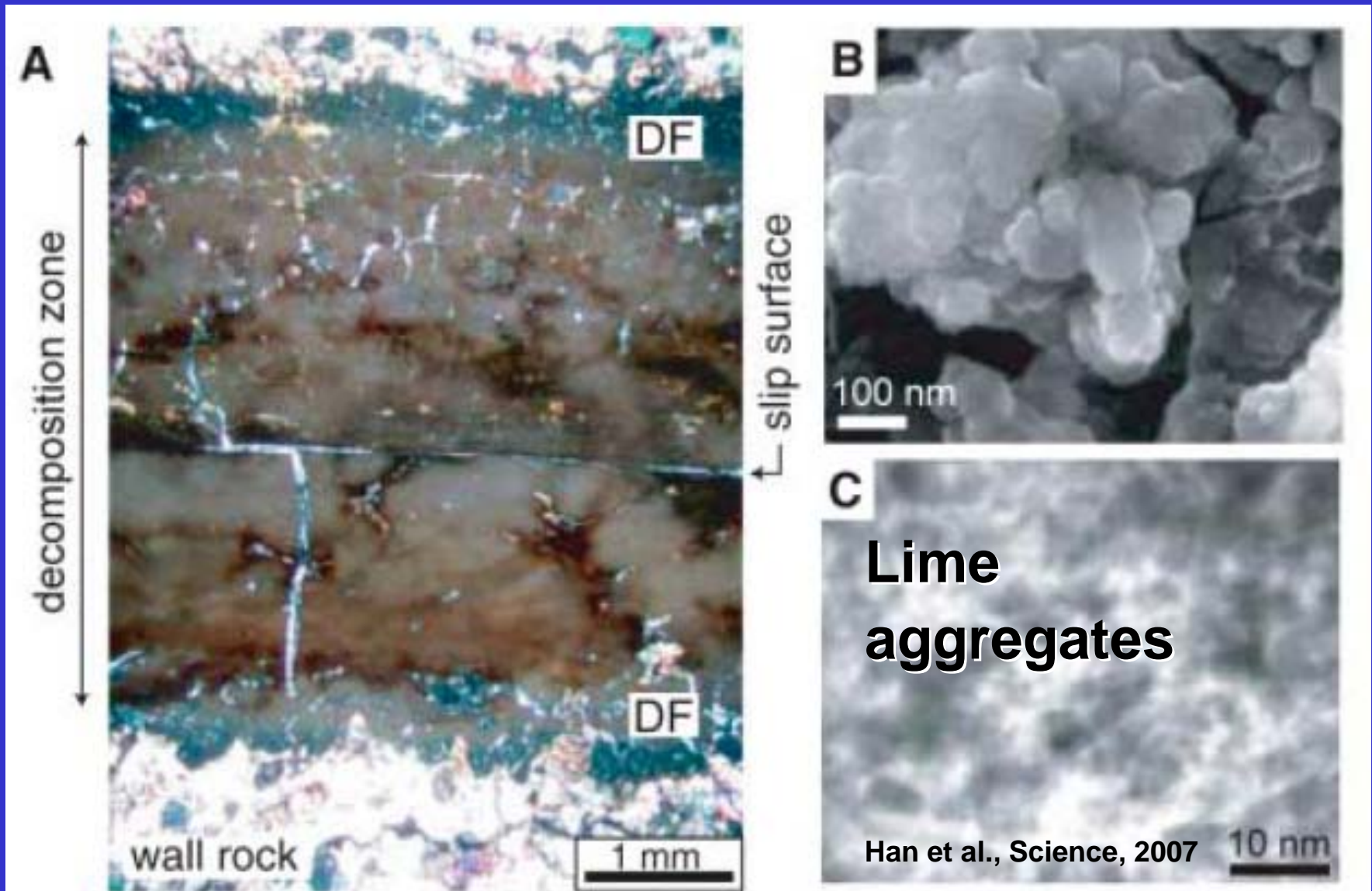
# Marble sample before the high-velocity experiment



Courtesy of Raehee Han

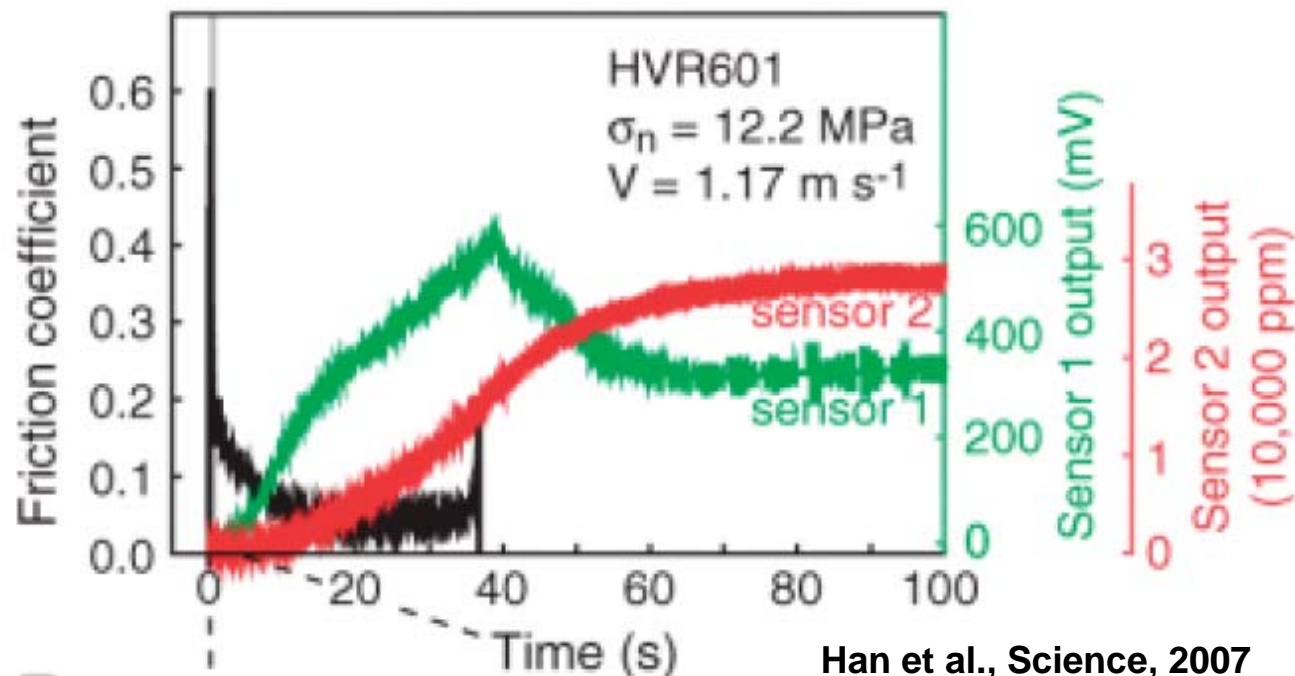
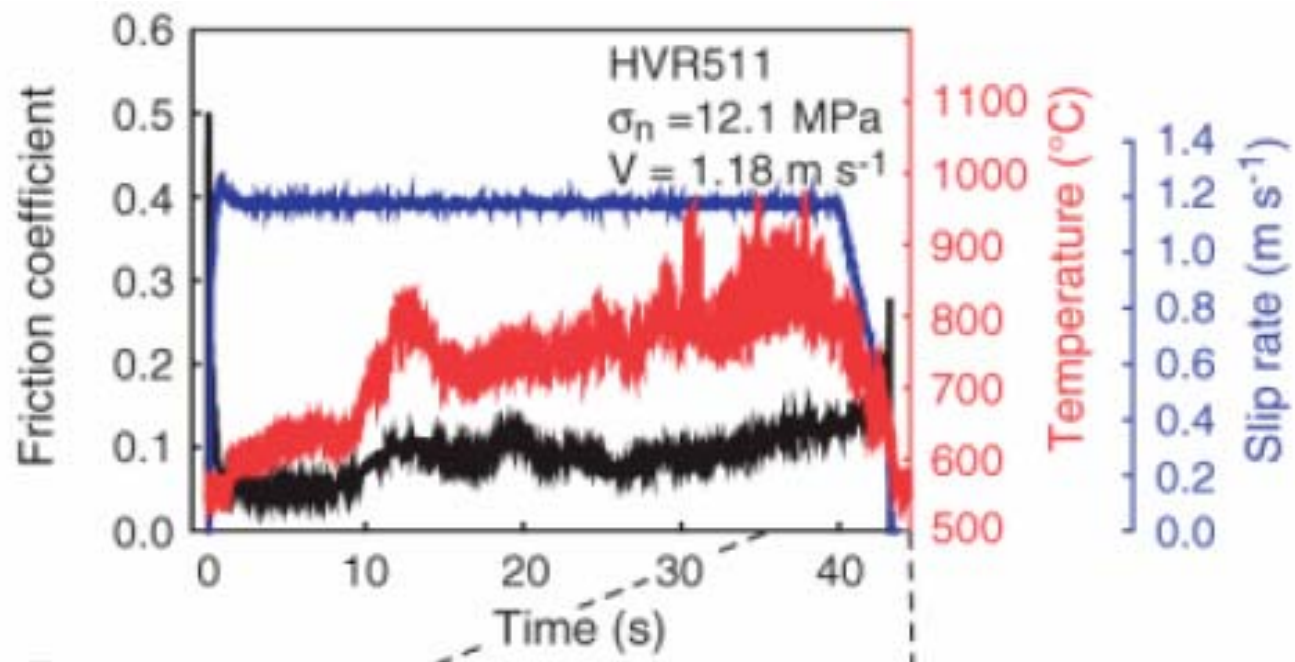


# Sample after the experiment (opt. and FE-SEM)





$\mu$  is low,  
high T  
CO<sub>2</sub> emission:  
**THERMAL  
DECOMP.  
WEAKENING**



# Outline

## 1. Rock friction

## 2. HV rock friction experiments (HVRFE)

2a. Silica gel lubrication

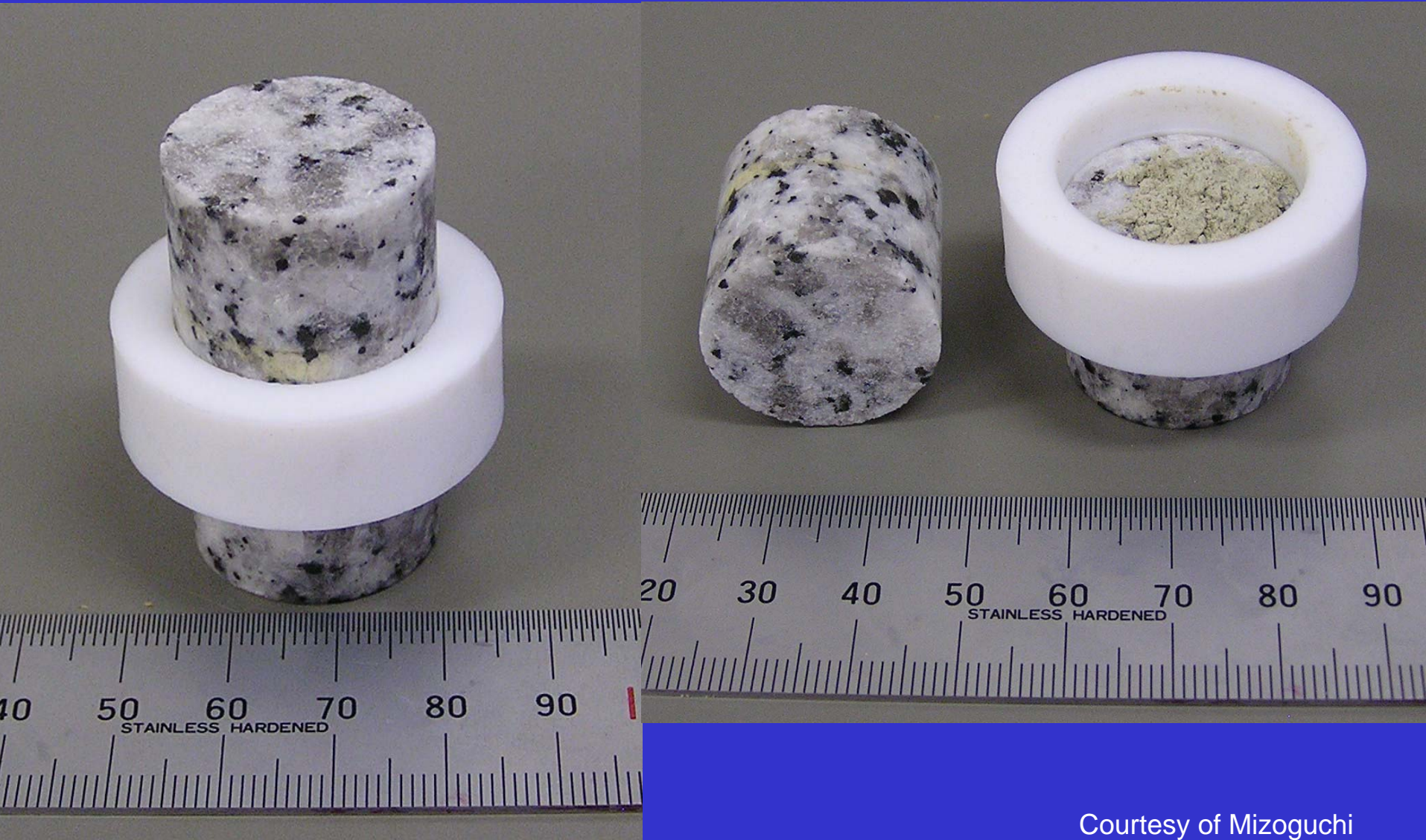
2b. Flash heating and dehydration weakening

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**2d. Gouge-related weakening**

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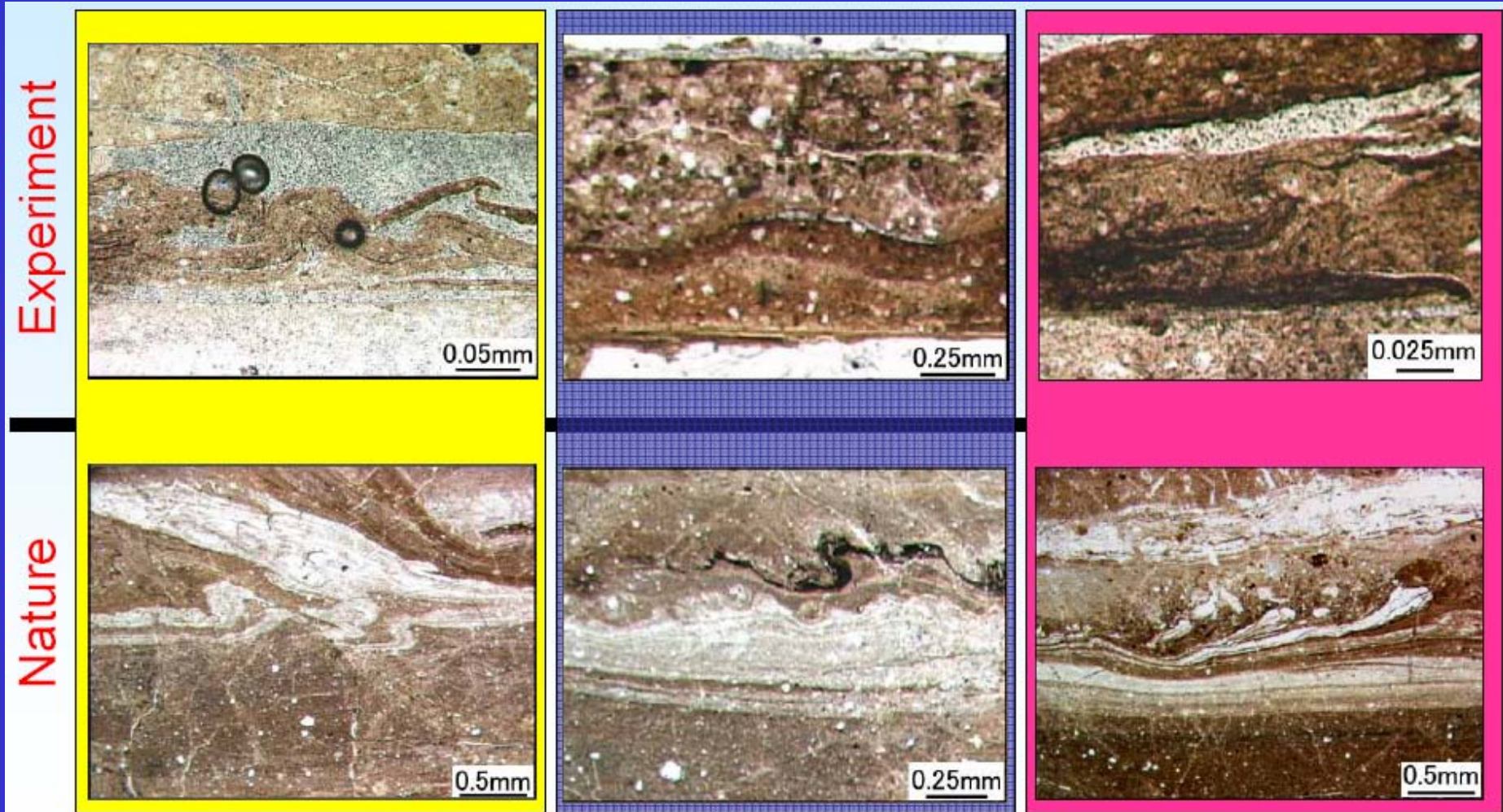
# Gouge sample assembly before the experiment



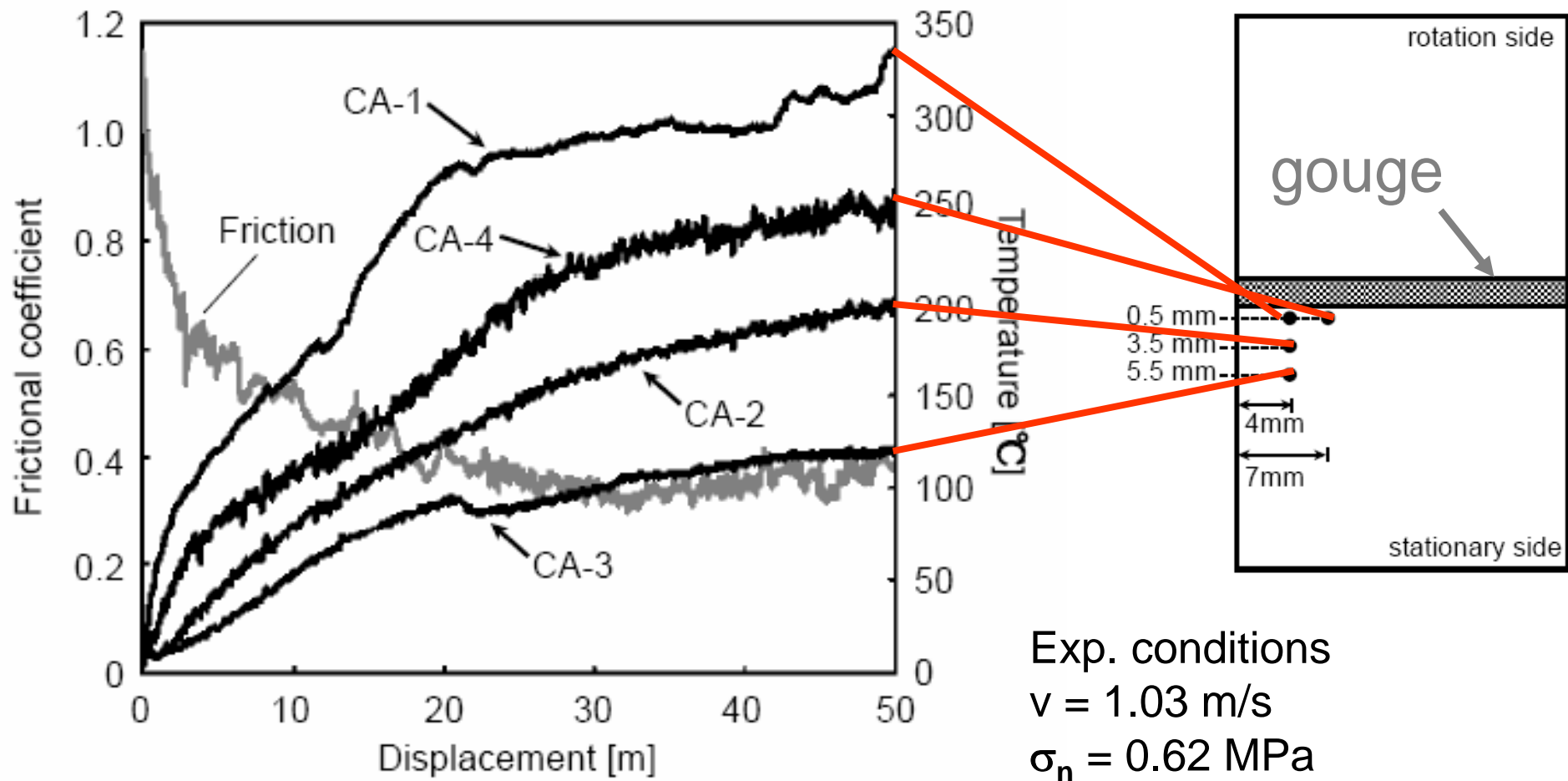
Courtesy of Mizoguchi



# Natural and experimental fabric are very similar (under the optical microscope)



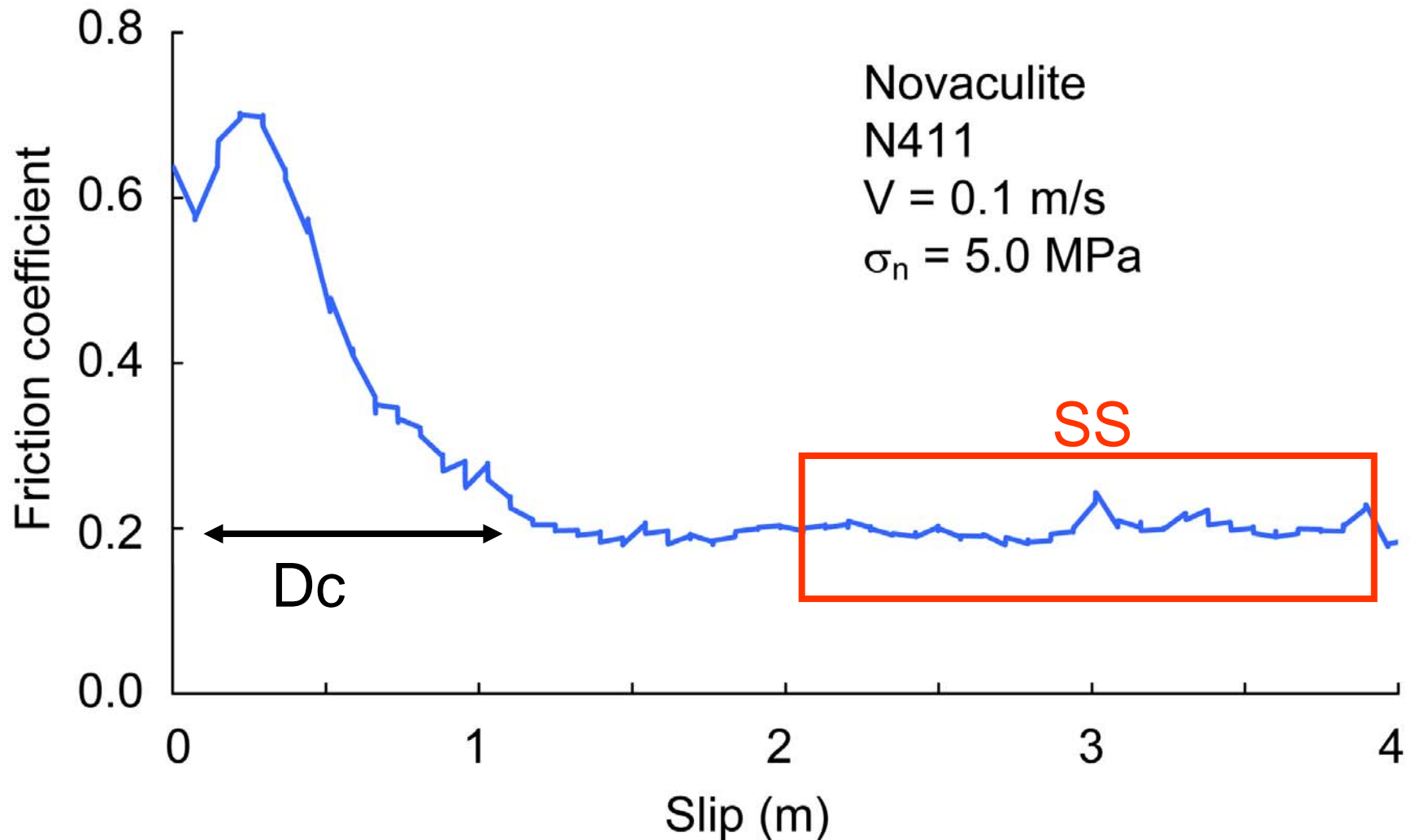
# $\mu$ and T are low during slip: GOUGE-RELATED WEAKENING



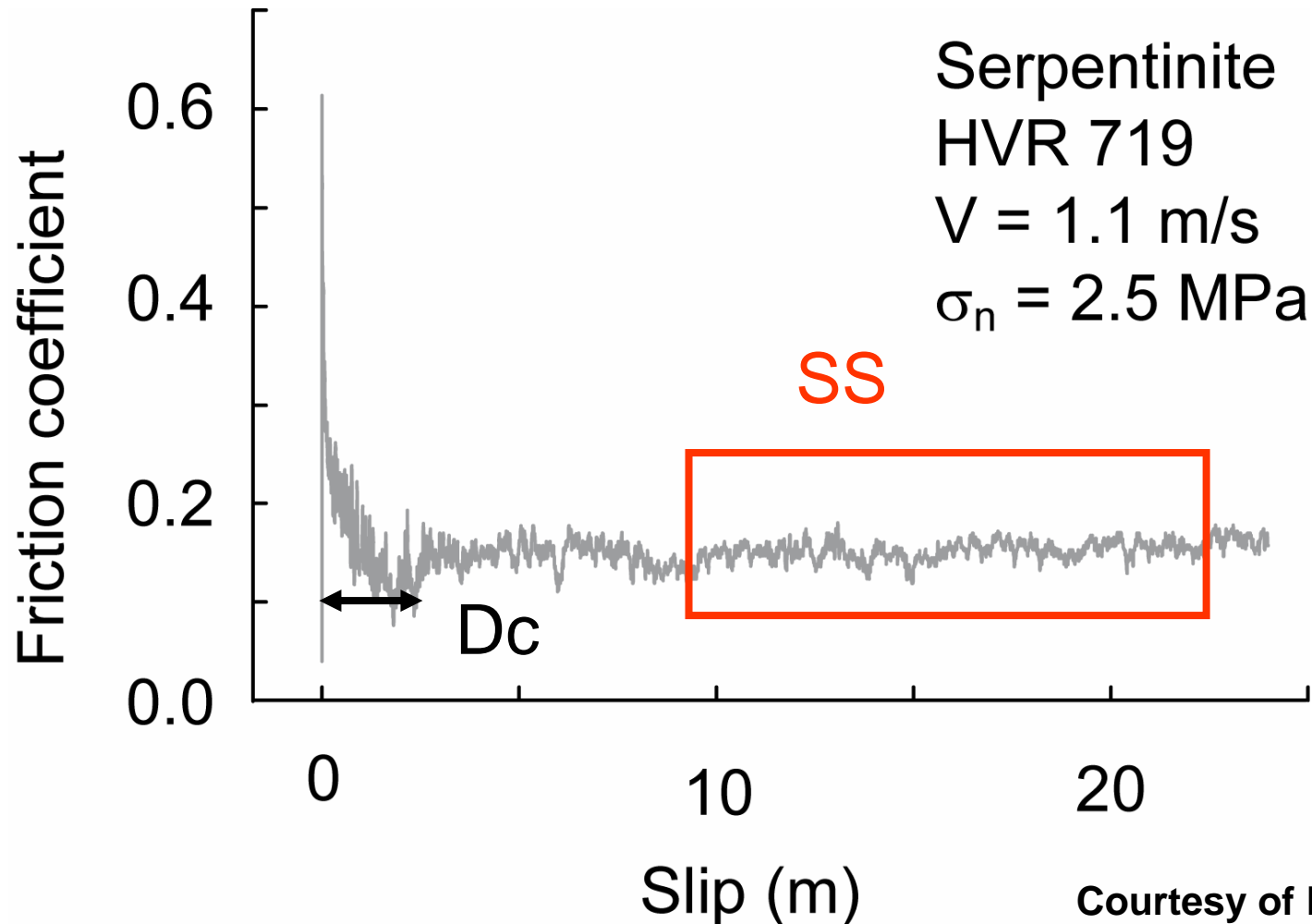


Summarizing....

# Friction during silica gel lubrication: $\mu$ at steady state is $\sim 0.2$

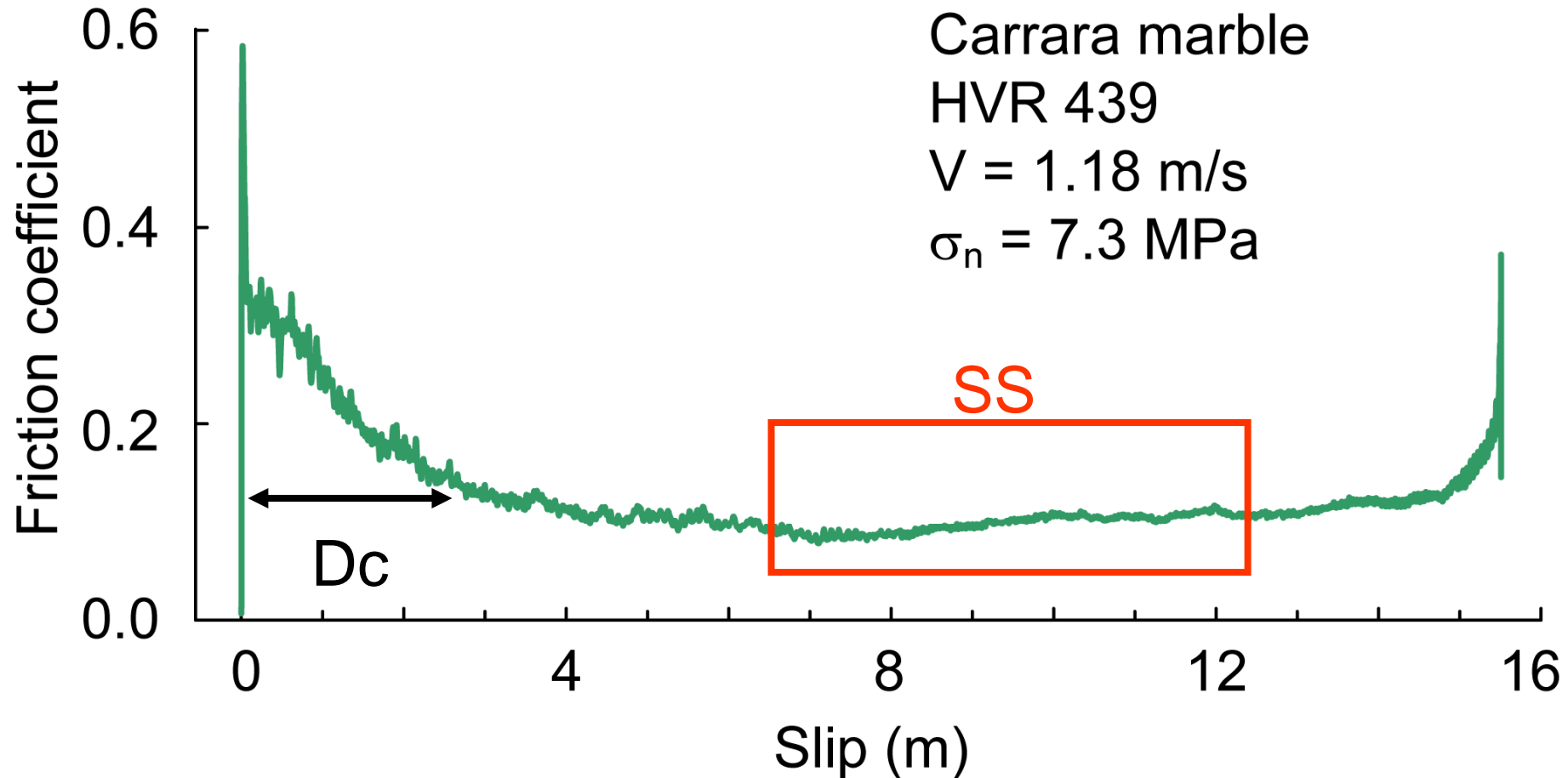


# Friction during flash heating and dehydration: $\mu$ at steady state is $\sim 0.15$

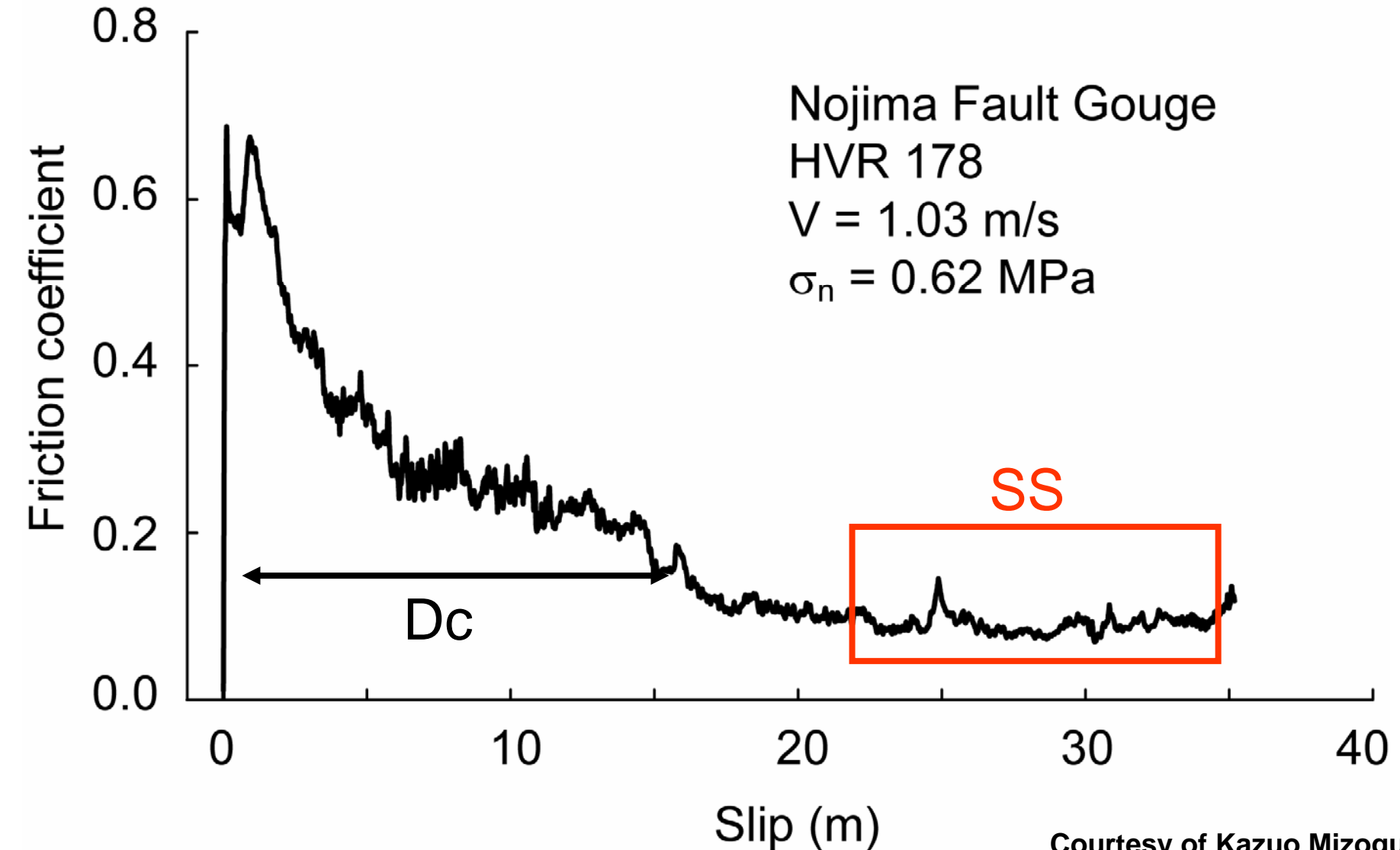


Courtesy of Hirose-san

# Friction during thermal decomposition: $\mu$ at steady state is $\sim 0.1$



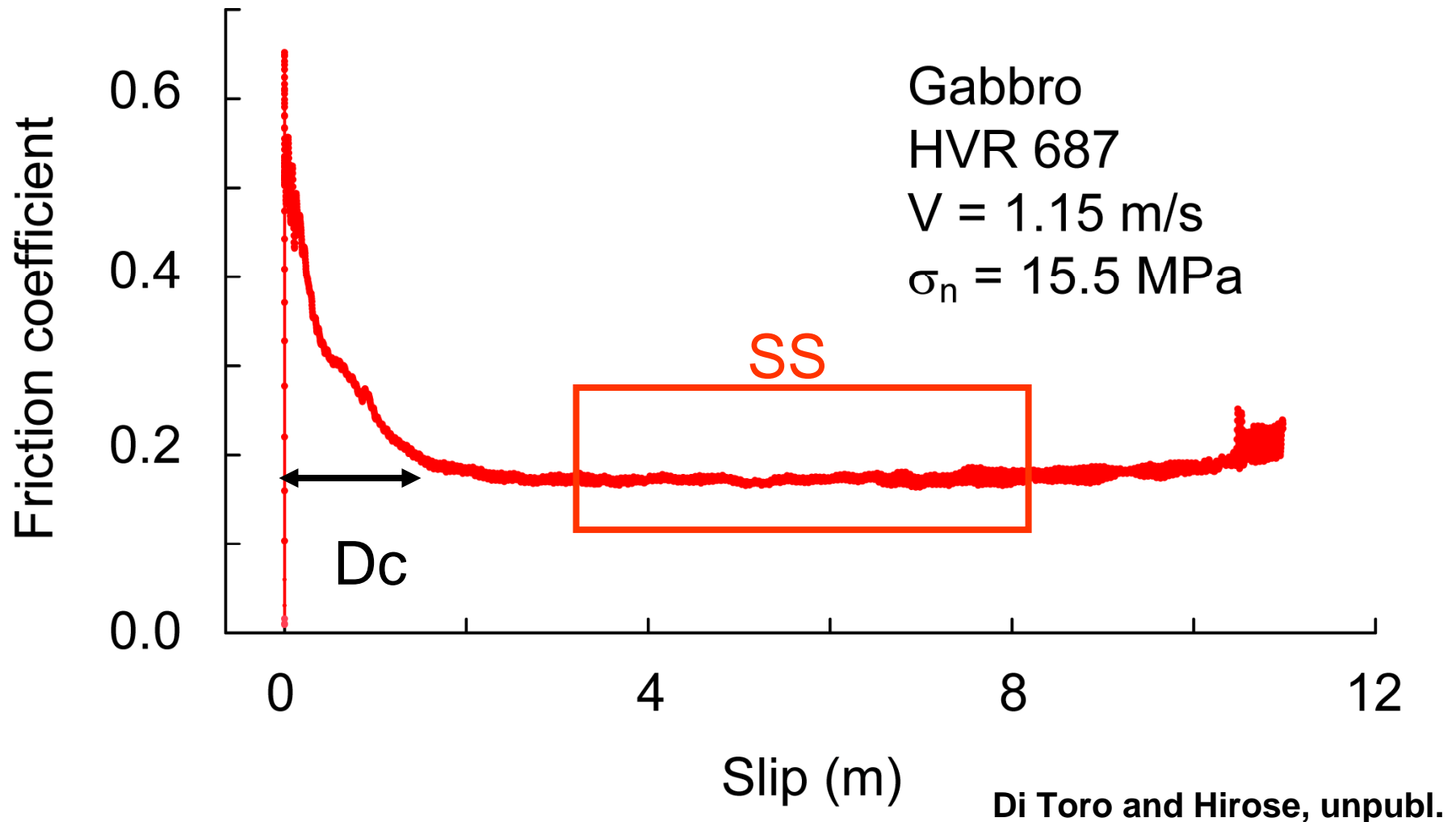
# Friction in the presence of gouge: $\mu$ at steady state is $\sim 0.1$



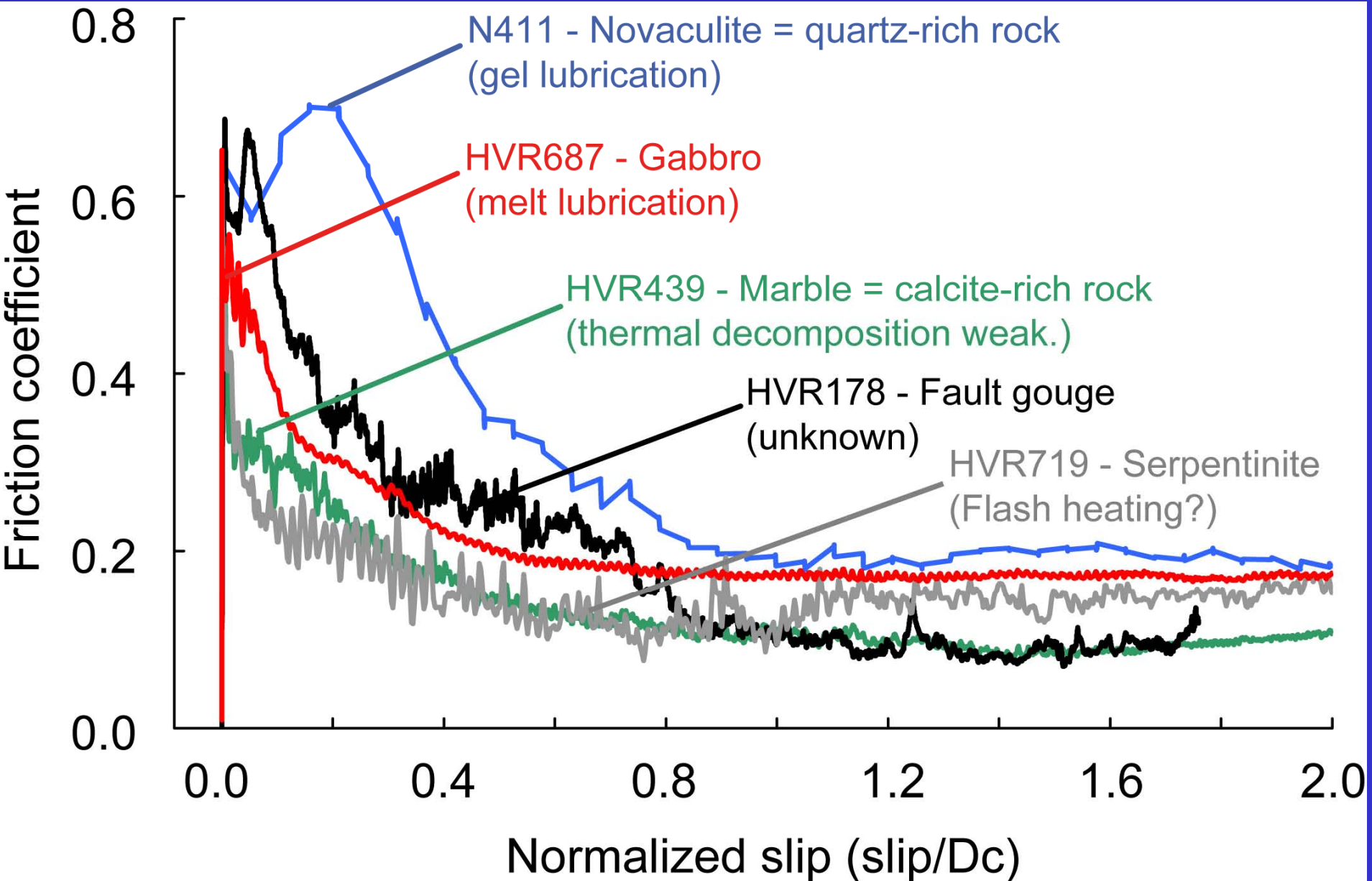


# Friction during melt lubrication:

$\mu$  at steady state is  $\sim 0.2$



# HVRFE = low friction at seismic slip rates



# Outline

## 1. Rock friction

## 2. High-velocity rock friction experiments (HVRFE)

- 2a. Silica gel lubrication


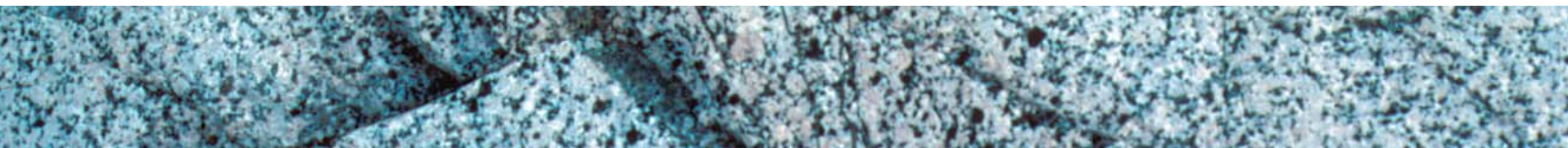
- 2b. Flash heating and dehydration weakening

- 2c. Thermal decomposition weakening

- 2d. Gouge-related weakening

## **3. Extrapolation of experimental data to seismic slip: the case for melt lubrication**

# Extrapolation of experimental data to seismic slip: melt lubrication

- 
- 1) Pseudotachylytes (solidified seismic melts) are unambiguously recognized as EQ scars (Cowan, JSG, 1999).
  - 2) Pseudotachylytes allow to determine dynamic fault strength from exhumed faults (Di Toro et al., Tectonophysics, 2005)
  - 3) Experimental solidified melts products are almost identical to natural pseudotachylytes (e.g., Spray, Geology, 1995).
  - 4) Theoretical analysis is simpler (!?) than for any other weakening mechanism (Fialko and Khazan, JGR, 2005).
- 



PST-bearing  
faults  
exhumed  
from 10 km  
depth.

(Adamello,  
Italy)

[*Di Toro and  
Pennacchioni, JSG,  
2004*]





# Collected samples of the host rock

tonalite



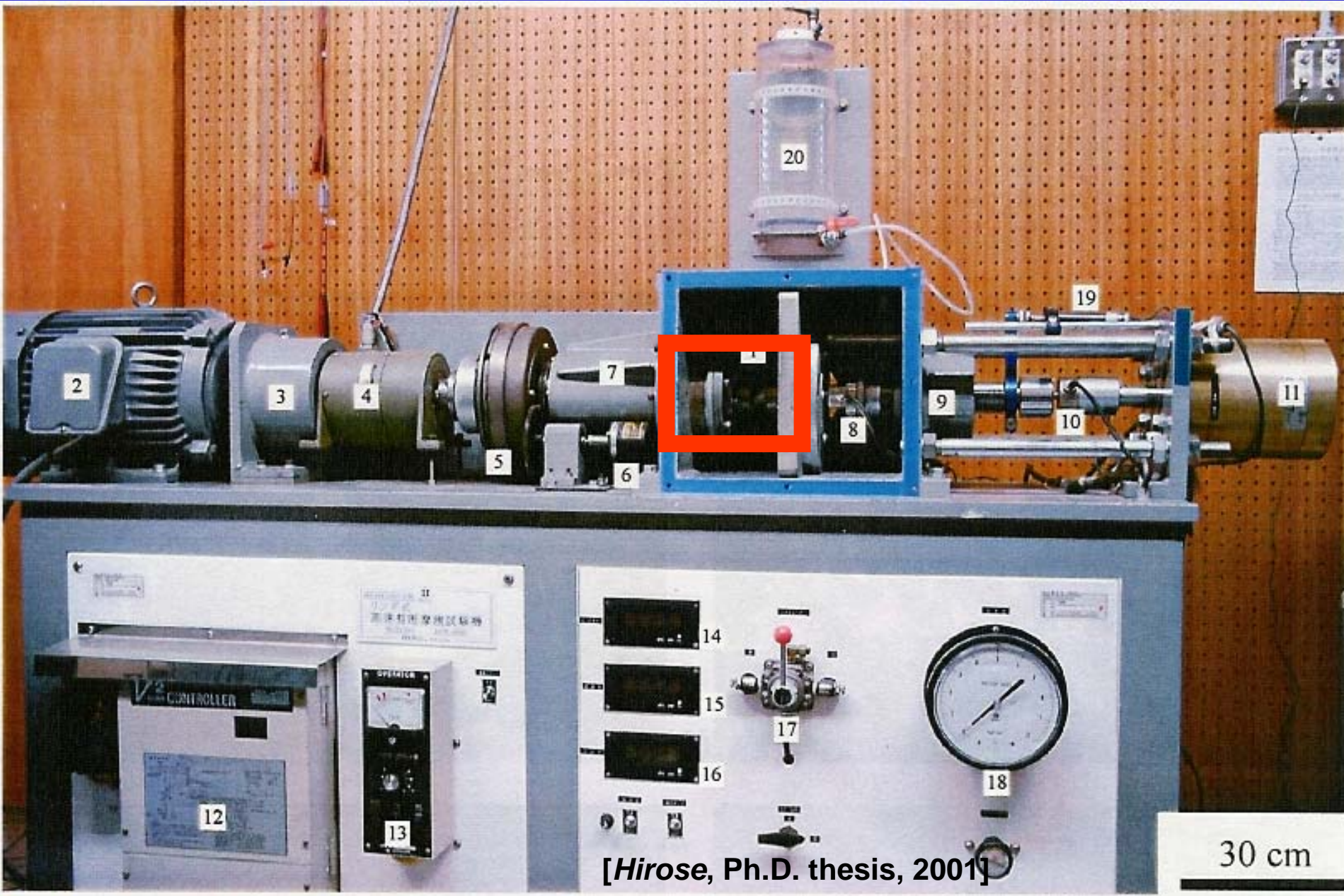
tonalite



...prepared samples...



# ...run experiments



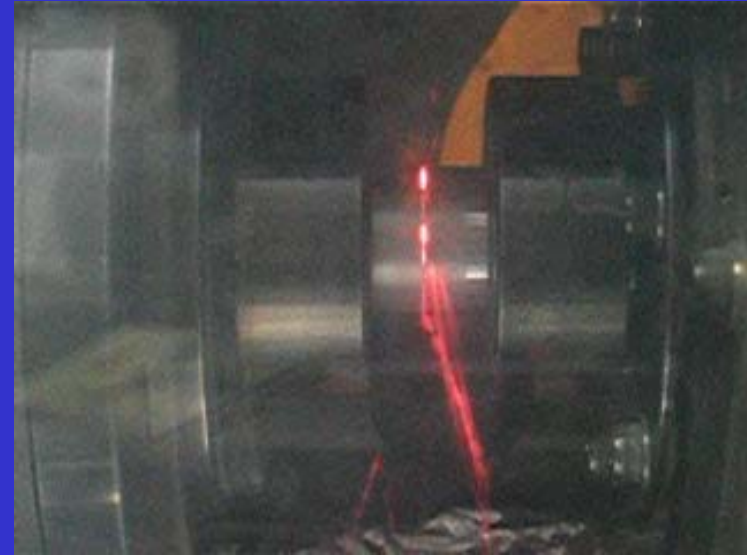


**Tonalite,  $v = 1.3$  m/s,  $\sigma_n = 20$  MPa**



20 mm

# Melt extrusion in nature and experiments



$V < 15\%$

$V > 85\%$

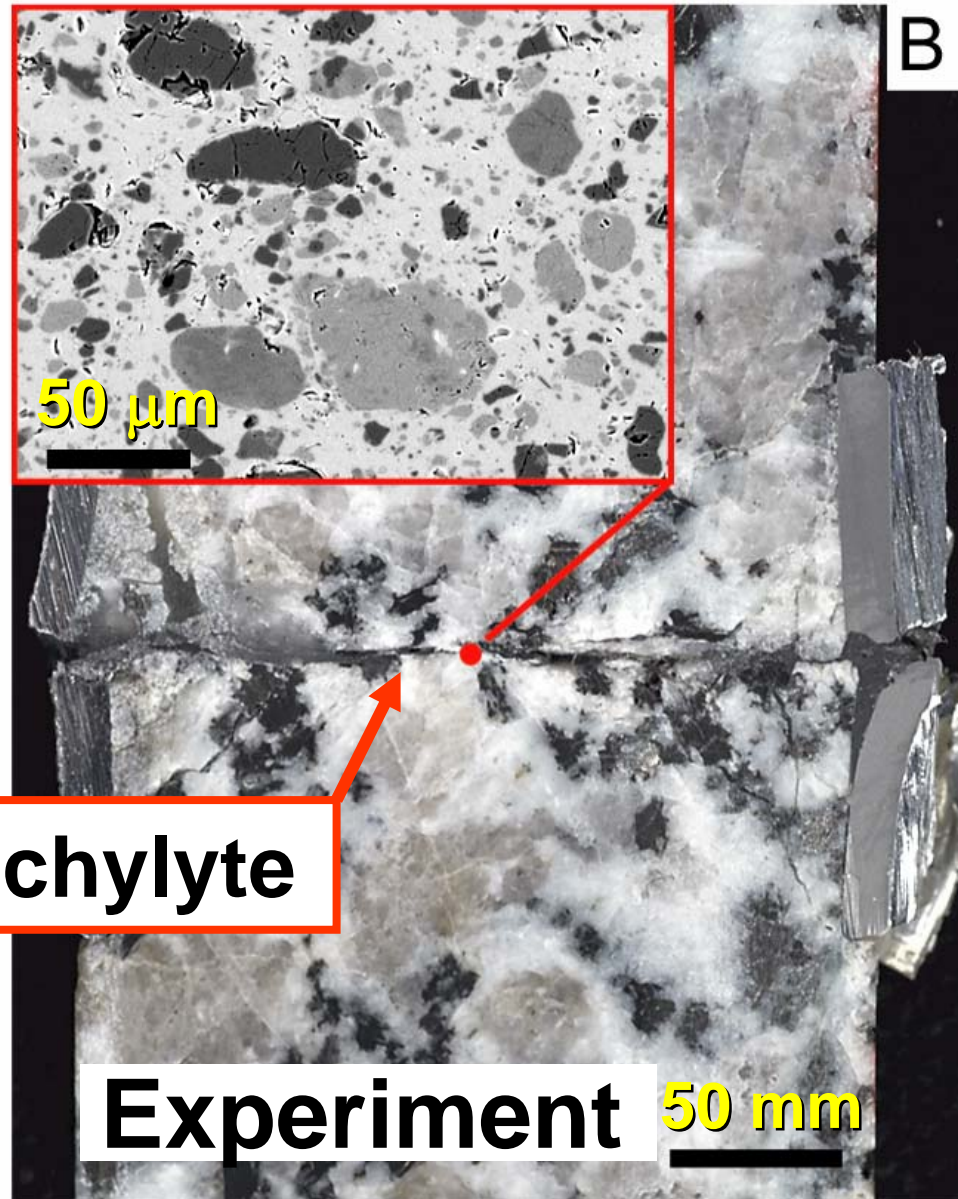
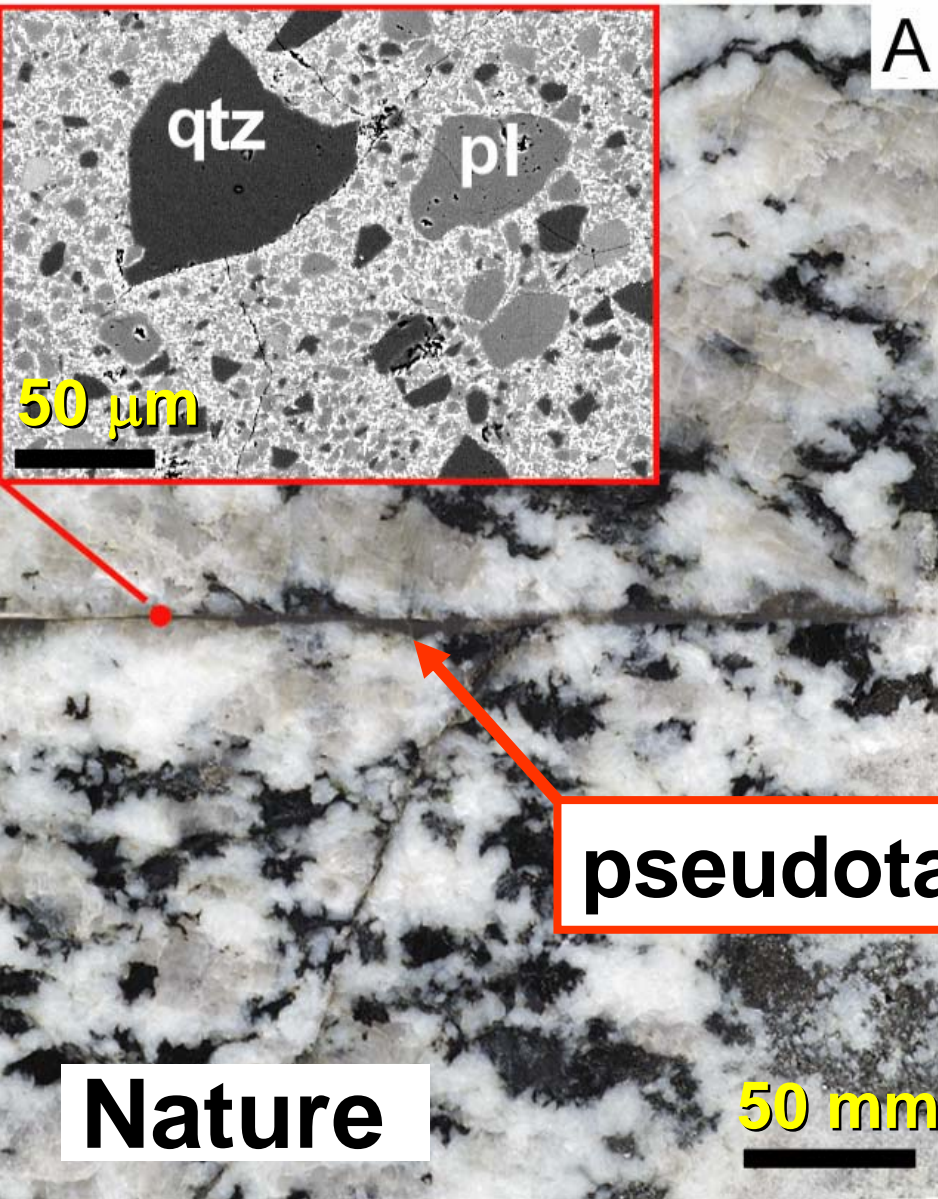
Nature



Experiment



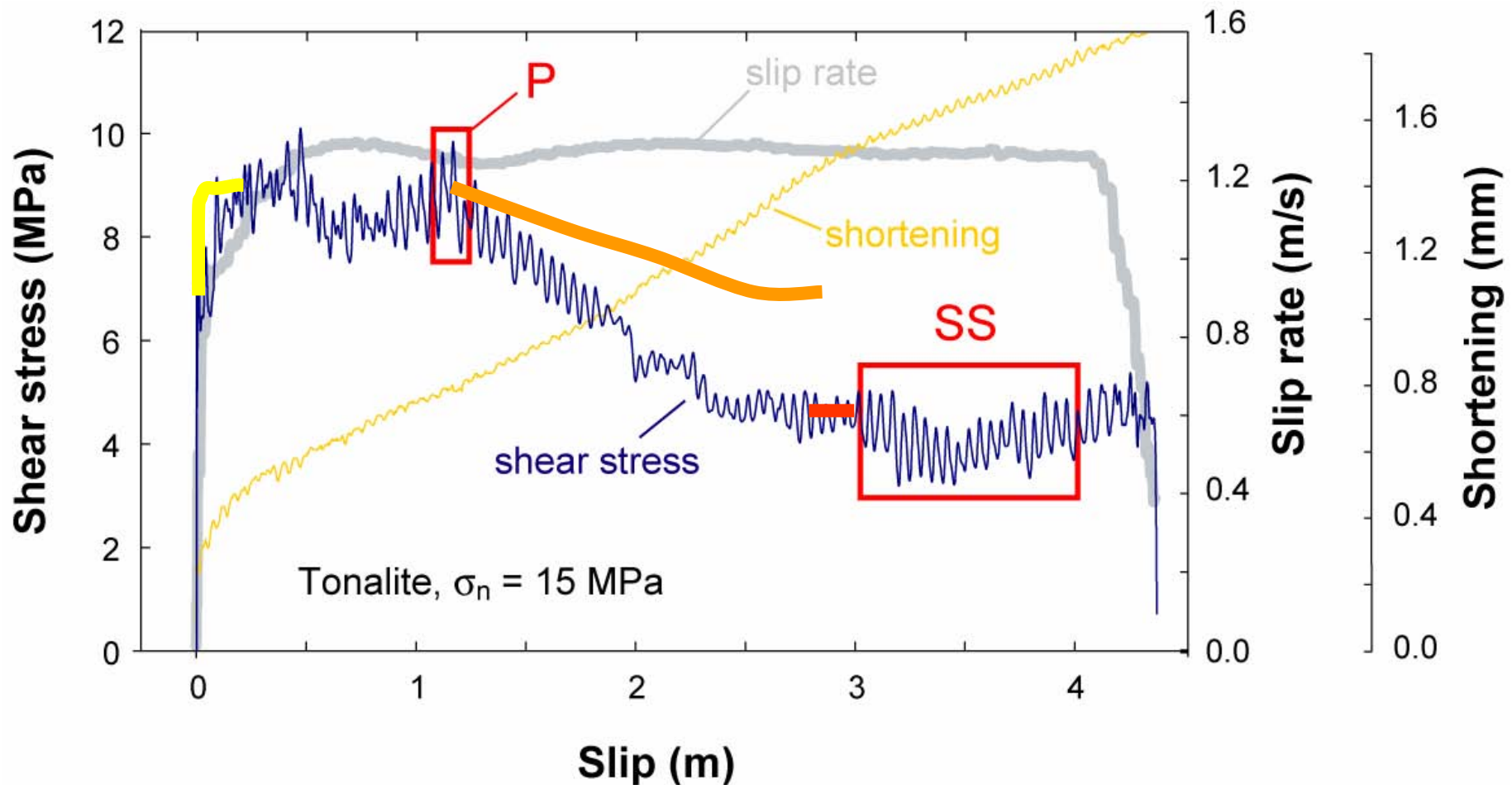
# Natural and experimental microstructures are very similar (also under SEM)





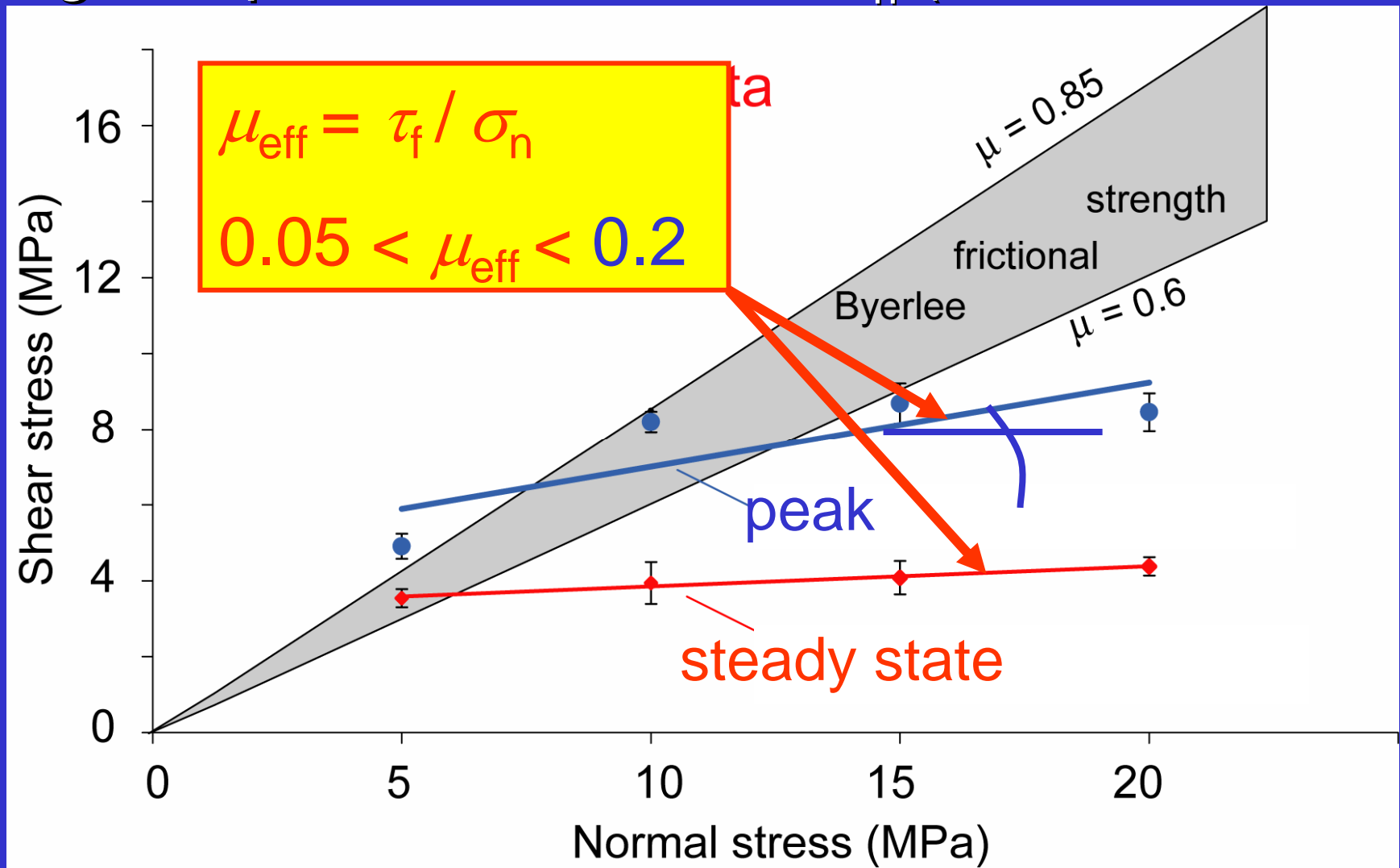
Traction evolution:

1. **strengthening** stage
2. **transient** stage
3. **steady state** stage

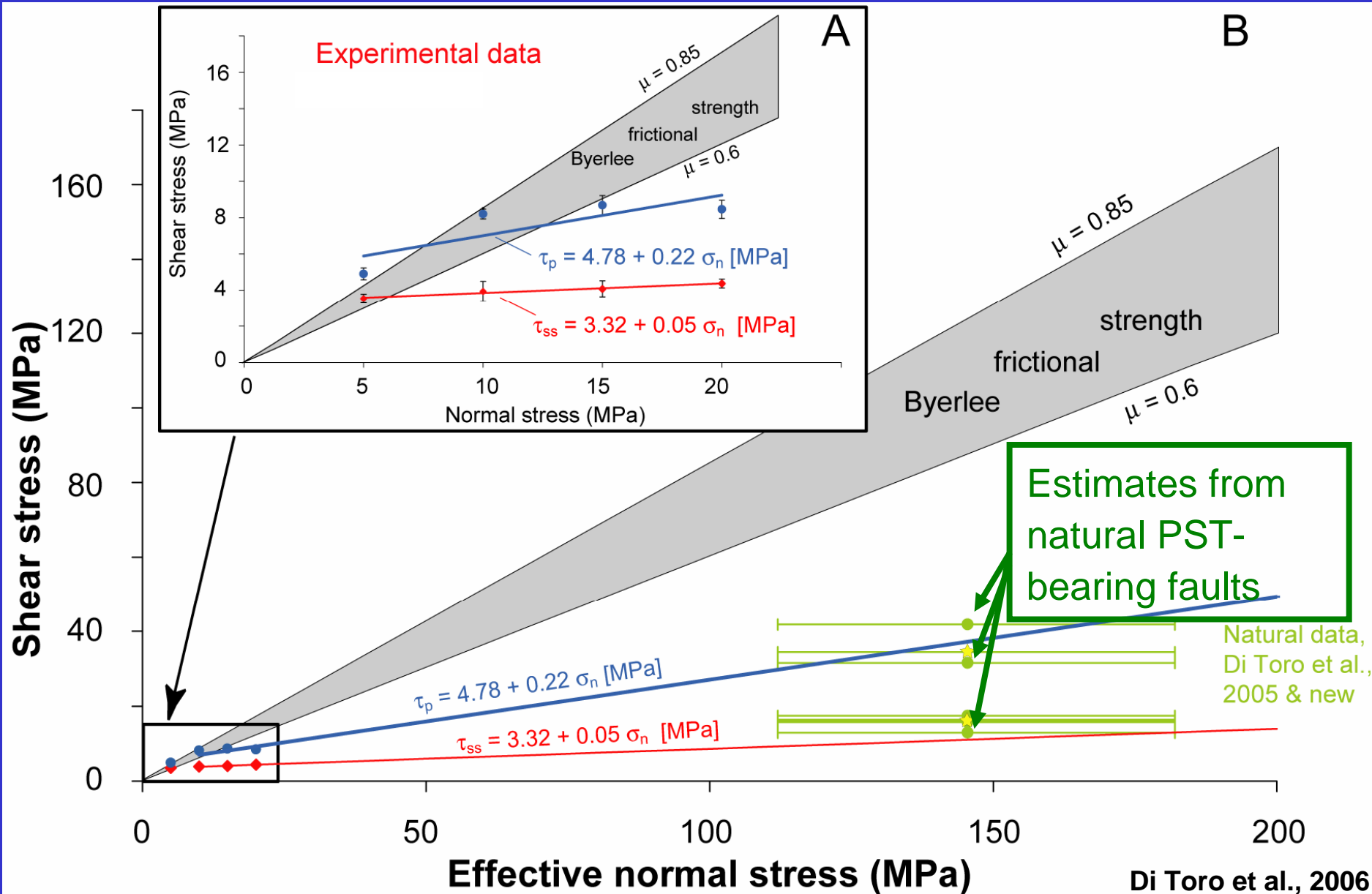


By performing several exp. with increasing  $\sigma_n$

- **low strength** in the presence of melt
- slight dependence of  $\tau$  with  $\sigma_n$  (**melt lubrication**)



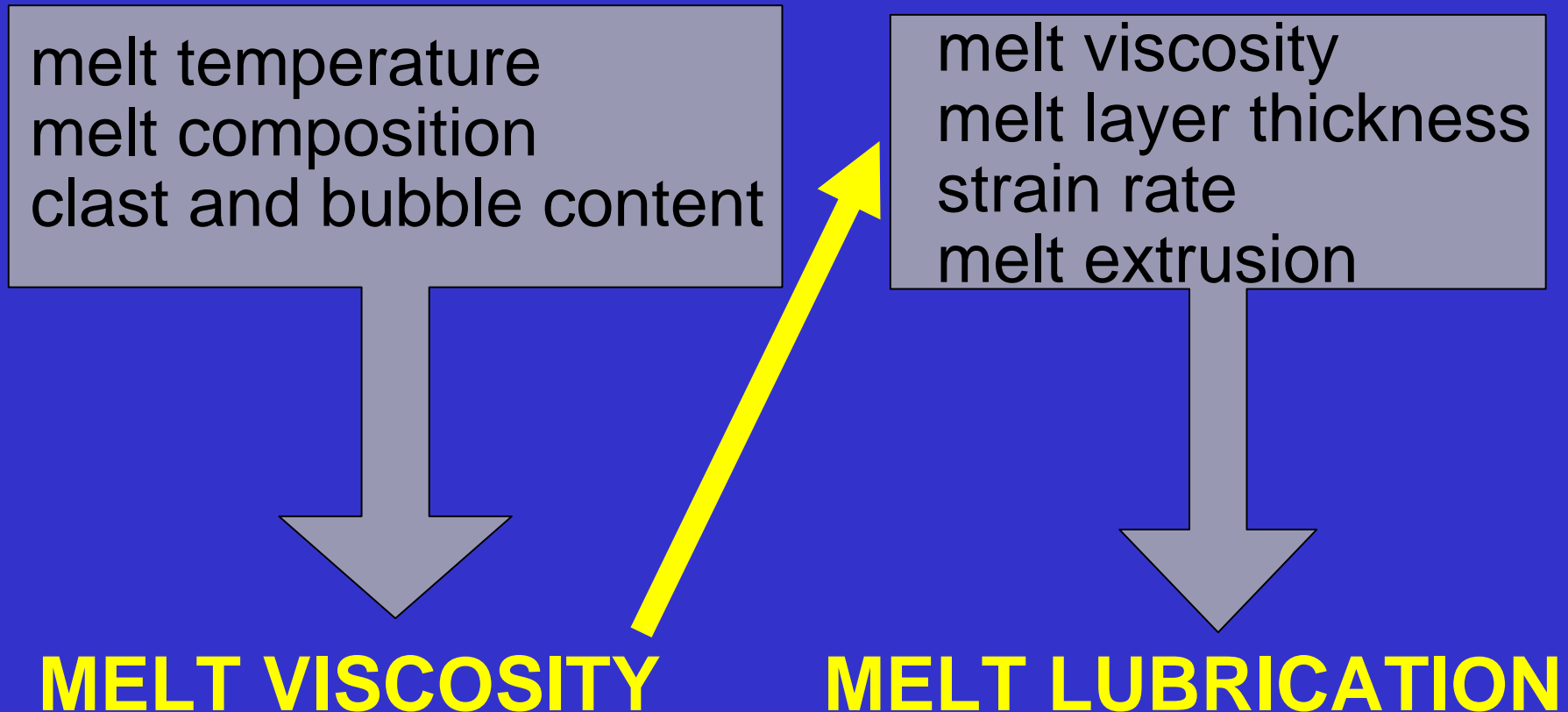
# Melt lubrication in experiments and nature



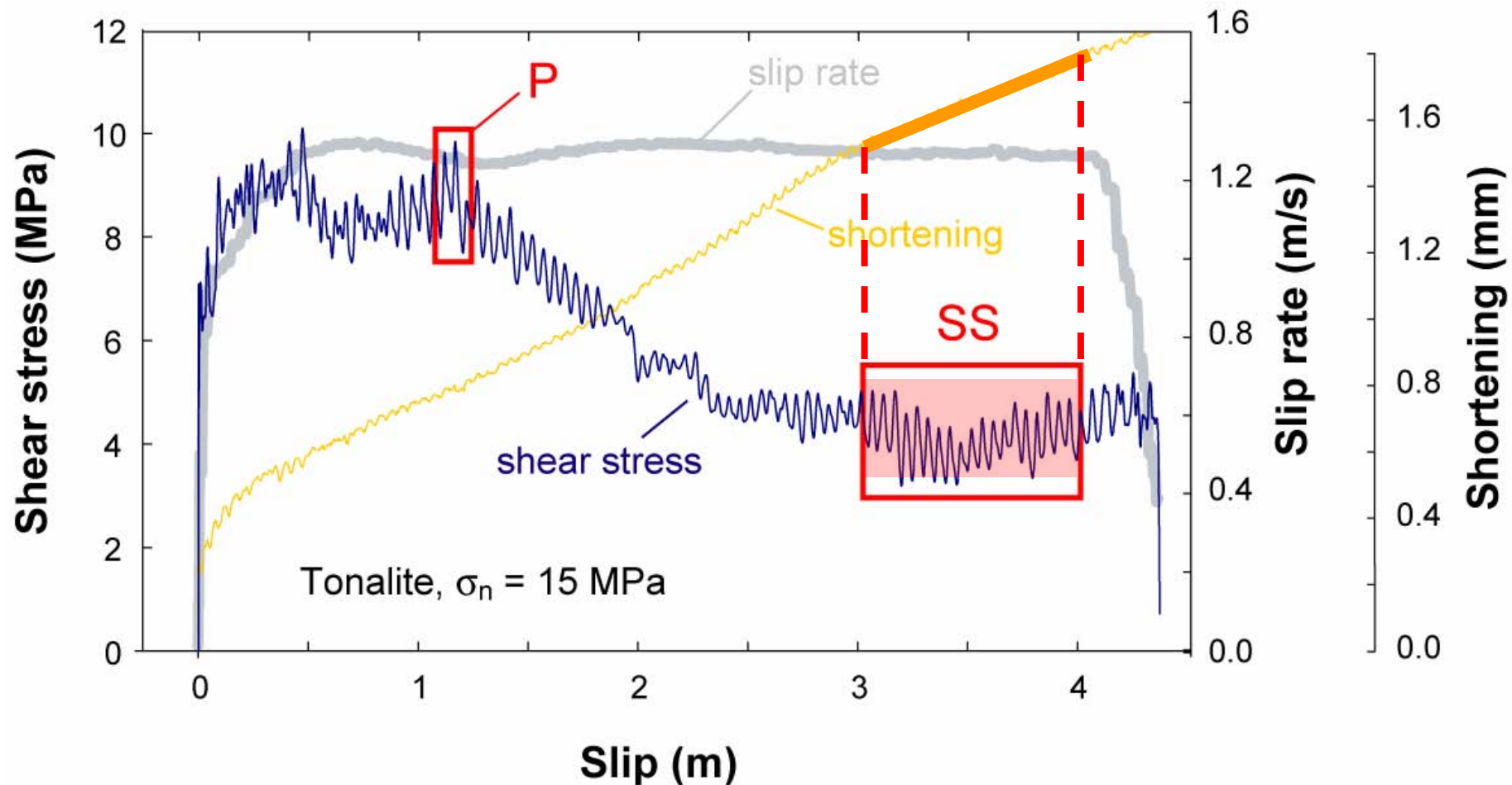
# This is a poor extrapolation

The **effective friction coefficient** does not fit the “physics”: no solid friction here.

**Melt lubrication is the result of**



A **constitutive equation** for melt lubrication.  
Let's focus on the **steady state** stage.  
Here the **shortening rate** is constant.



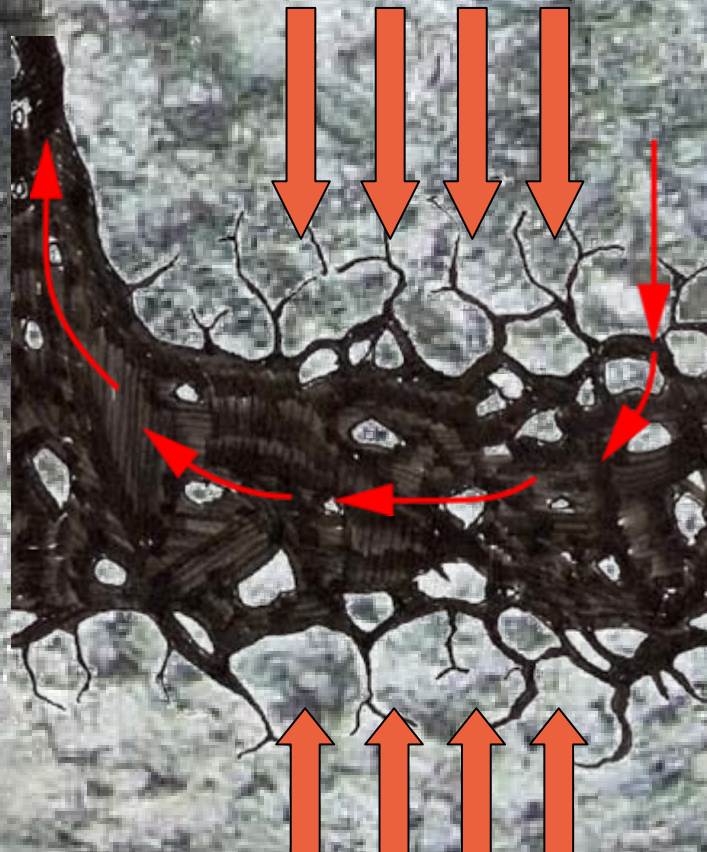


# Modelling steady-state: a complex world



**melt thickness is constant** (Hirose and Shimamoto, 2005)

**melting-, shortening-, melt extrusion-rate = cst**

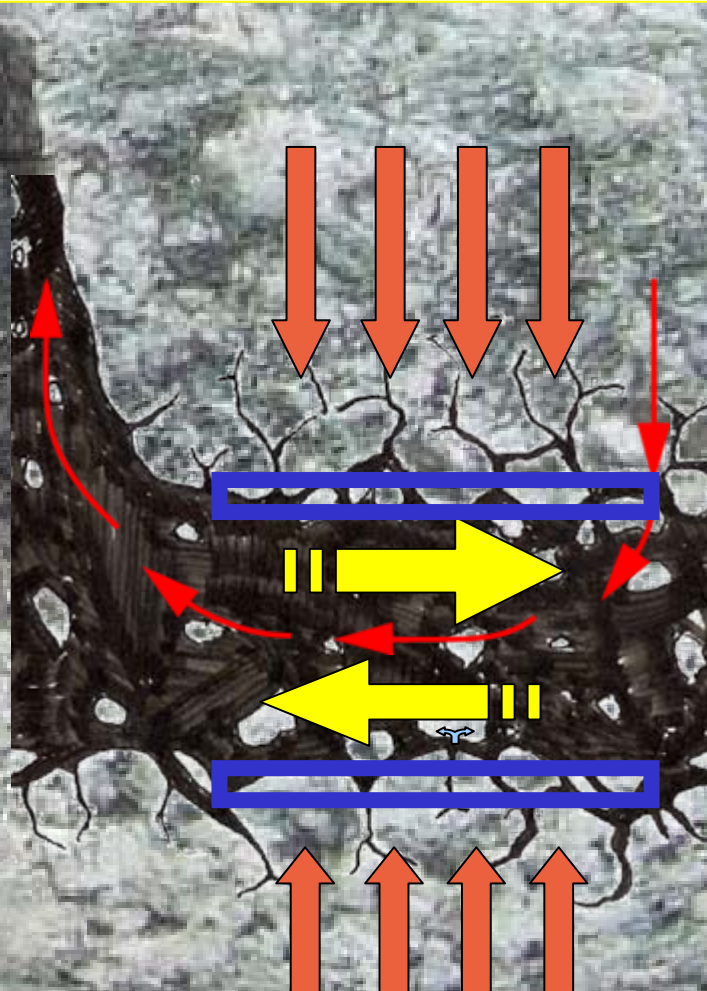


**melt thickness is constant** (Hirose and Shimamoto, 2005)

**melting-, shortening-, melt extrusion rate = cst.**

**heat produced by viscous flow & shear heating**

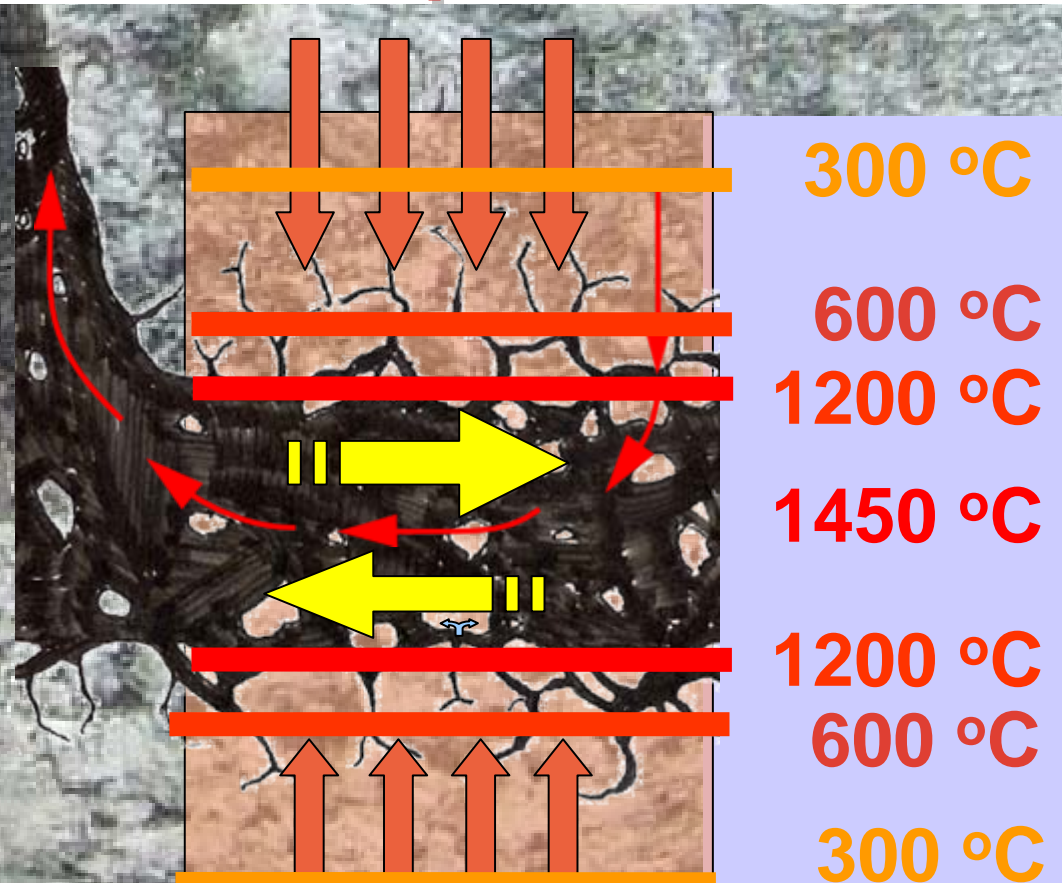
**latent heat of fusion = heat loss by melt extr.**





**melt thickness is constant** (Hirose and Shimamoto, 2005)

**Melting-, shortening-, melt extrusion-rate = cst**  
**heat produced by viscous flow & shear heating**  
**latent heat of fusion = heat loss by melt extr.**  
**isotherms are fixed in space and time**



## System of **five coupled equations**:

- 1) Melt/solid interface: Stefan problem
- 2) Solid host rock: heat diffusion
- 3) Melt layer: shear heating
- 4) Extrusion: viscous flow and cooling
- 5) Hydrodynamic pressure



The solution is:

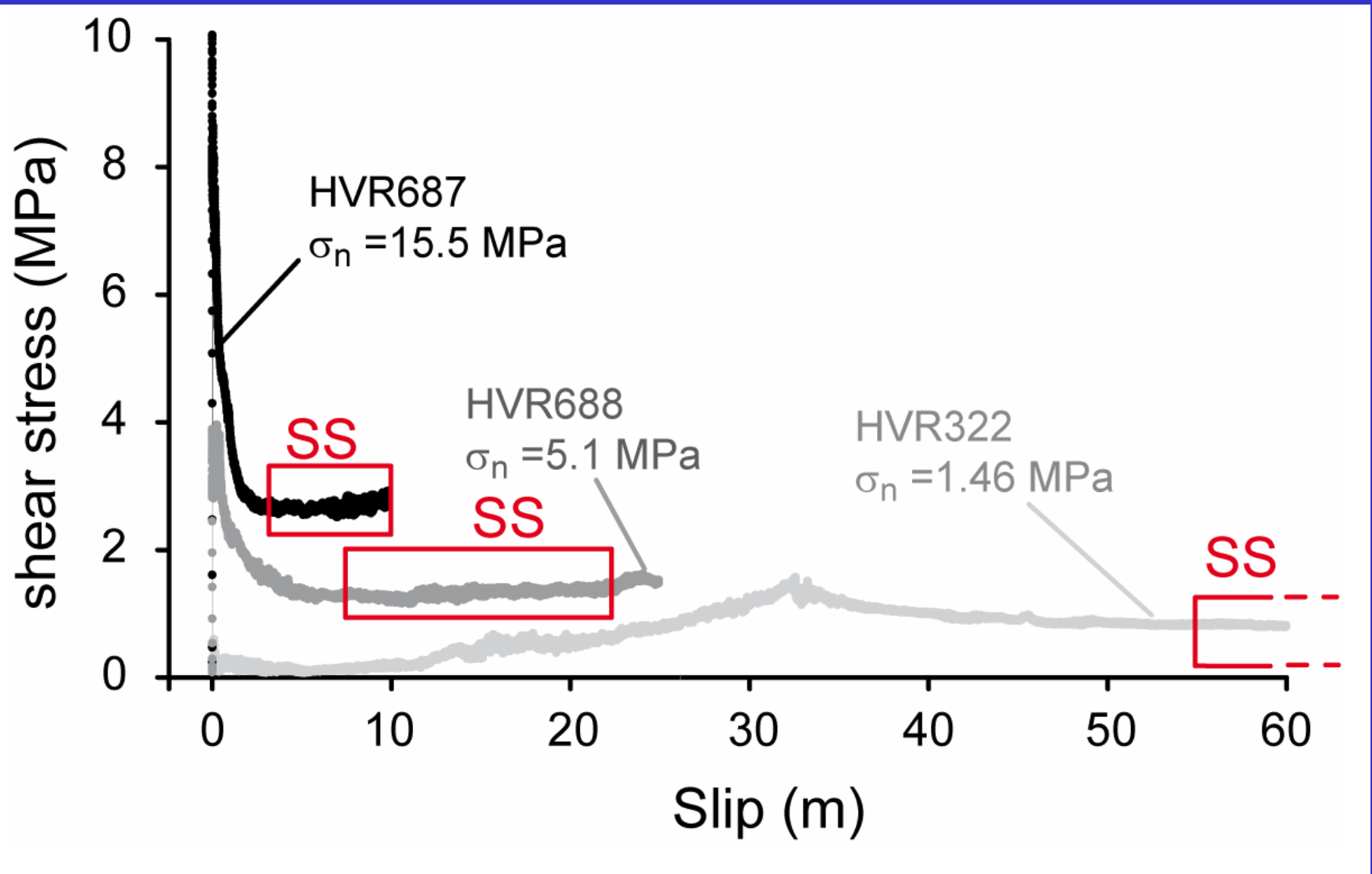
$$\tau_{ss} = \Theta^{3/4} \sigma_n^{1/4} \sqrt{\frac{\kappa}{R V}}$$

- $\Theta$  normalizing factor with stress units
- $\kappa$  thermal diffusivity
- $R$  melt escaping distance
- $V$  slip rate

It should work for lubrication in rock, ice, etc.

We performed experiments to test the equation (Nielsen et al., JGR, accept.)

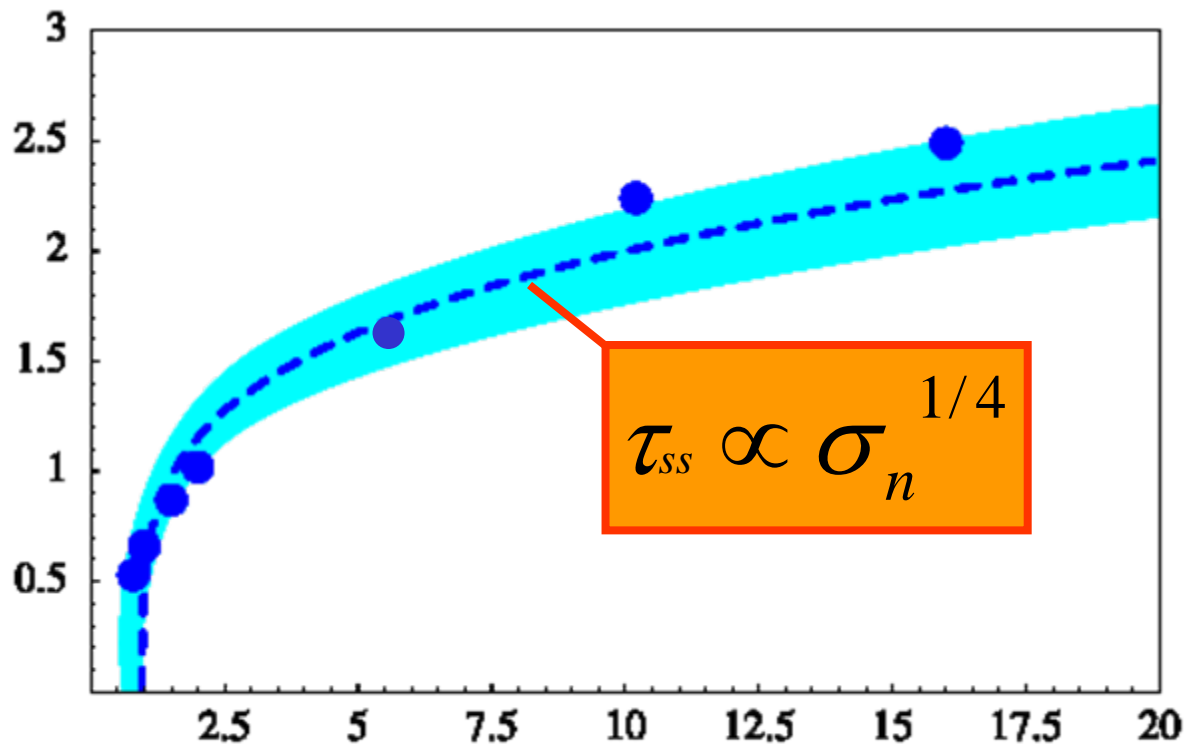
By varying the normal stress....



...the solution fits the shear stress dependence with normal stress.

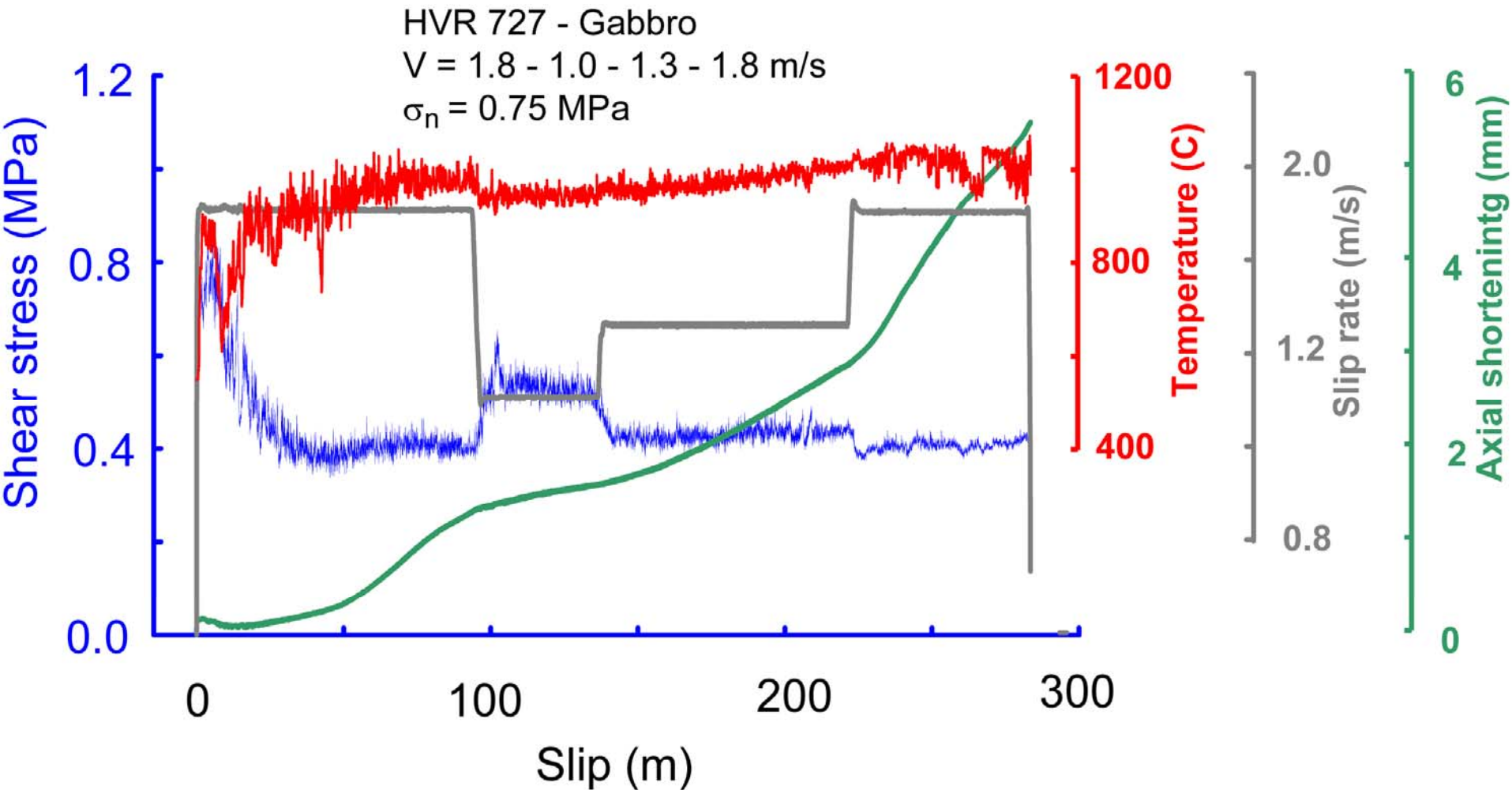
$$\tau_{ss} = \Theta^{3/4} \sigma_n^{1/4} \sqrt{\frac{\kappa}{R V}}$$

Steady  
state  
shear  
stress  
(MPa)



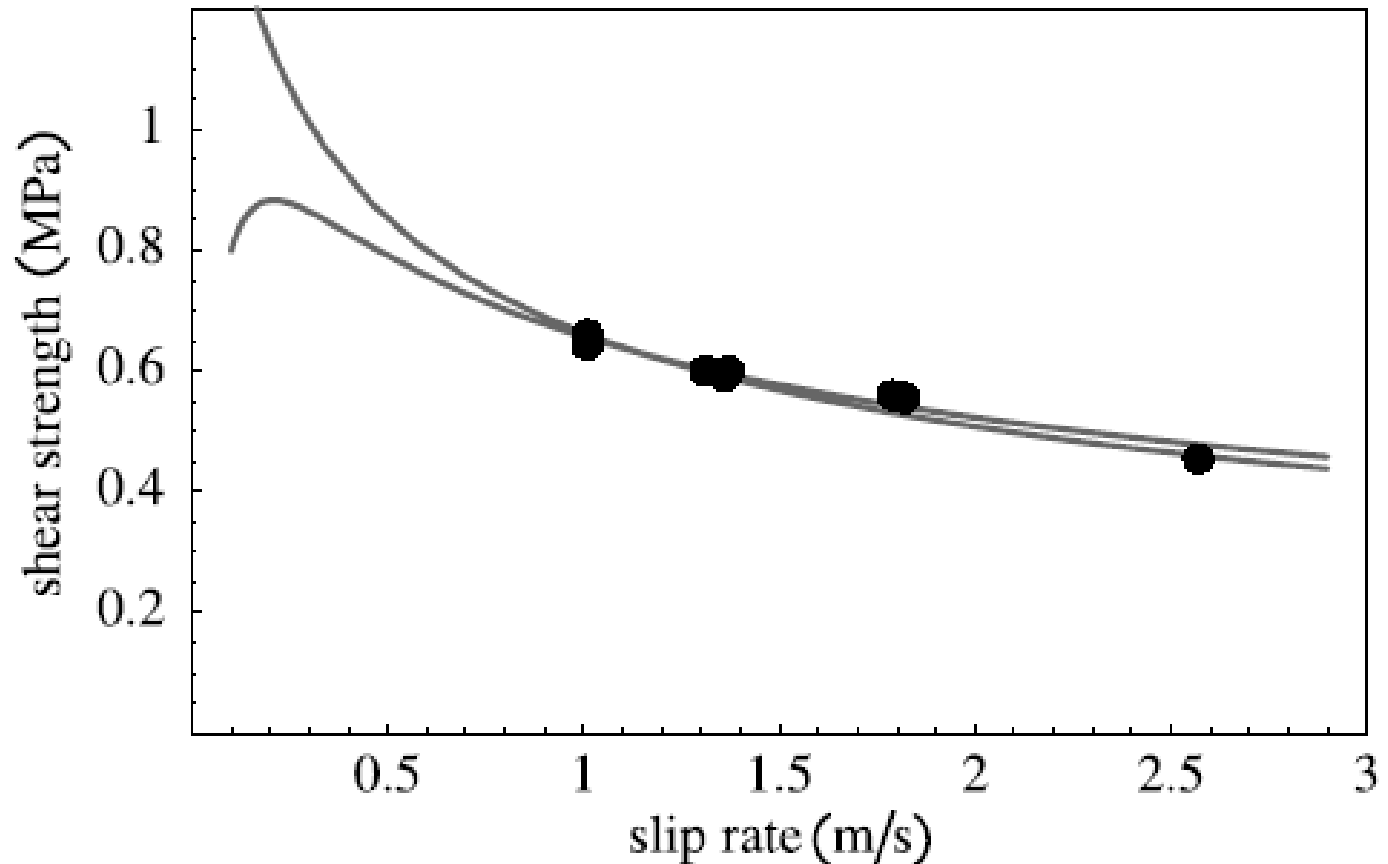
Normal stress (MPa)

By varying the slip rate  $V$ ....



..the solution fits the shear stress dependence with slip rate.

$$\tau_{ss} = \Theta^{3/4} \sigma_n^{1/4} \sqrt{\frac{\kappa}{R \circledast V}}$$



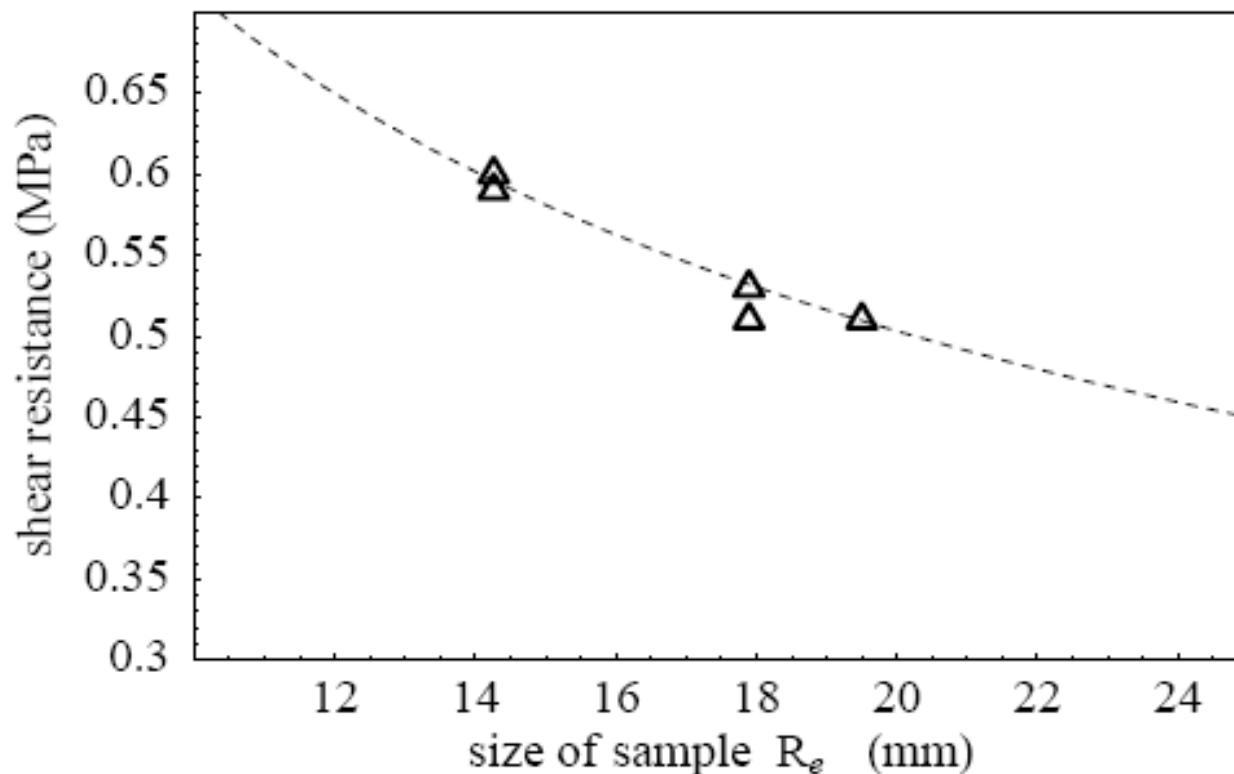


By varying the sample size (i.e., melt escaping dist.)



... the solution fits the shear stress dependence with the melt escaping distance.

$$\tau_{ss} = \Theta^{3/4} \sigma_n^{1/4} \sqrt{\frac{\kappa}{RV}}$$

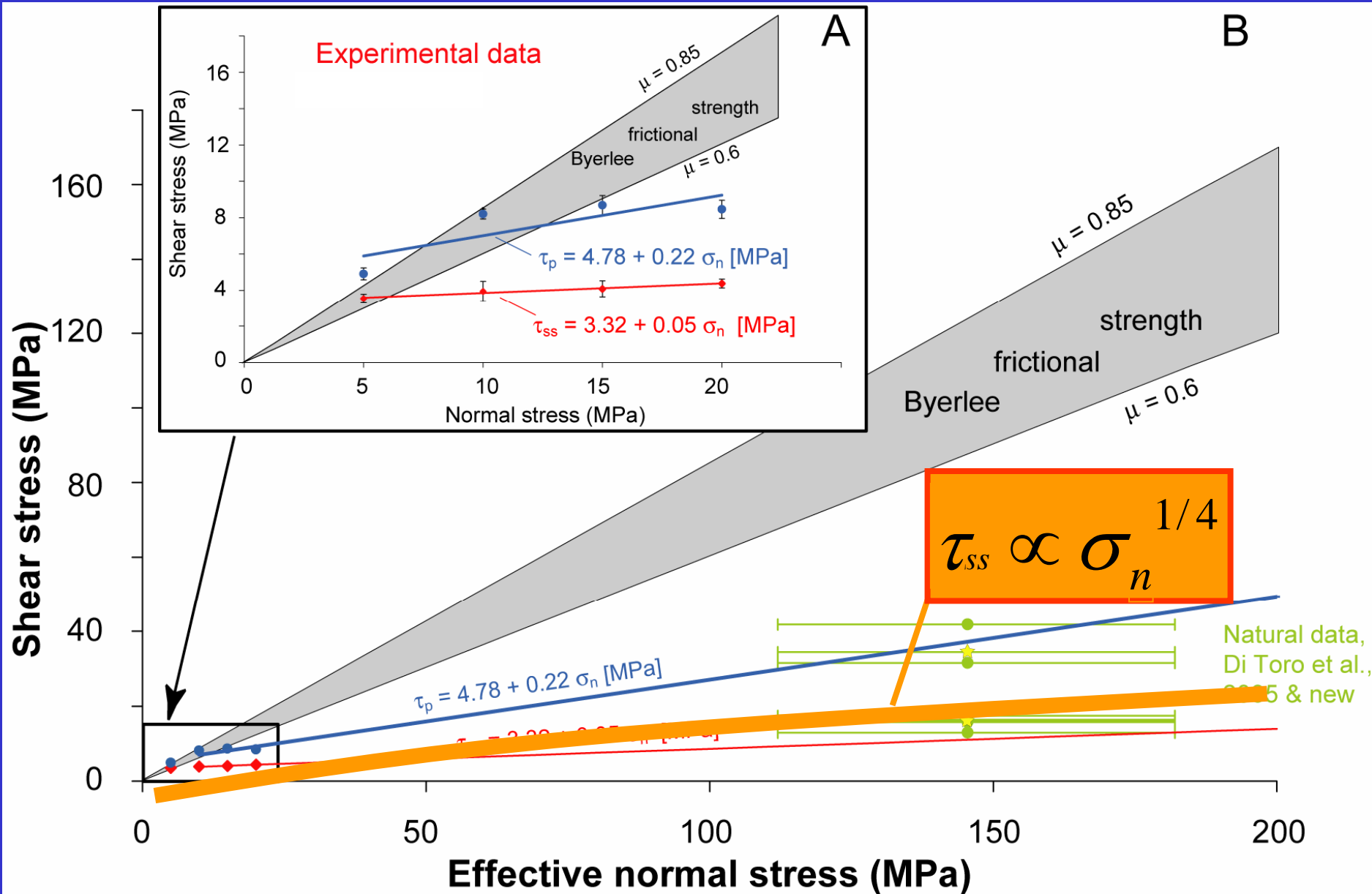


$$\tau_{ss} = \Theta^{3/4} \sigma_n^{1/4} \sqrt{\frac{\kappa}{R V}}$$

It seems that the solution for melt lubrication works.

Let's apply the Eq. to natural conditions

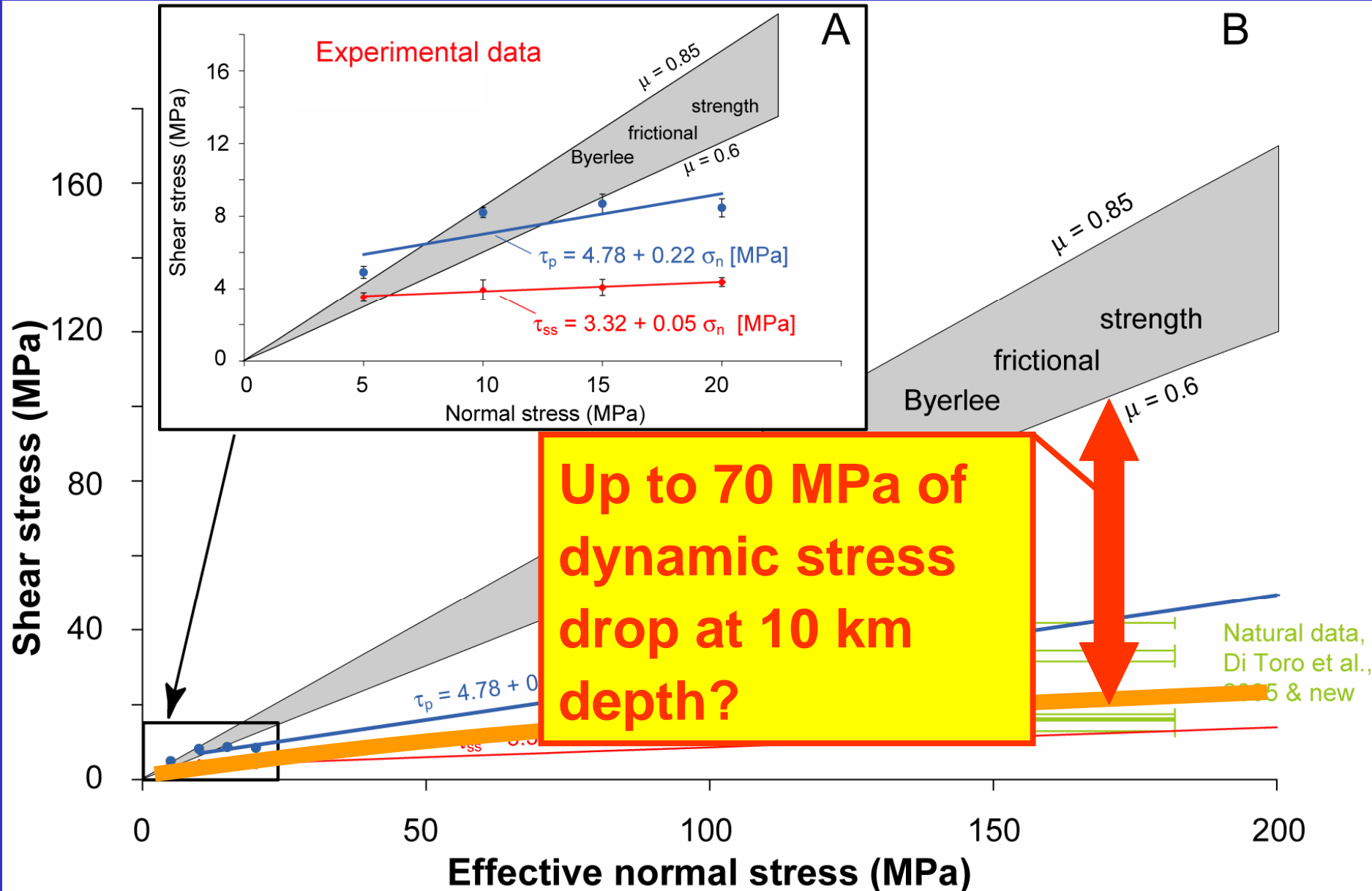
# Melt lubrication in experiments, nature and theory



.....problems.....



# Large dynamic stress drops



But seismic stress drops are expected to be low ( $< 30$  MPa) in the upper crust.

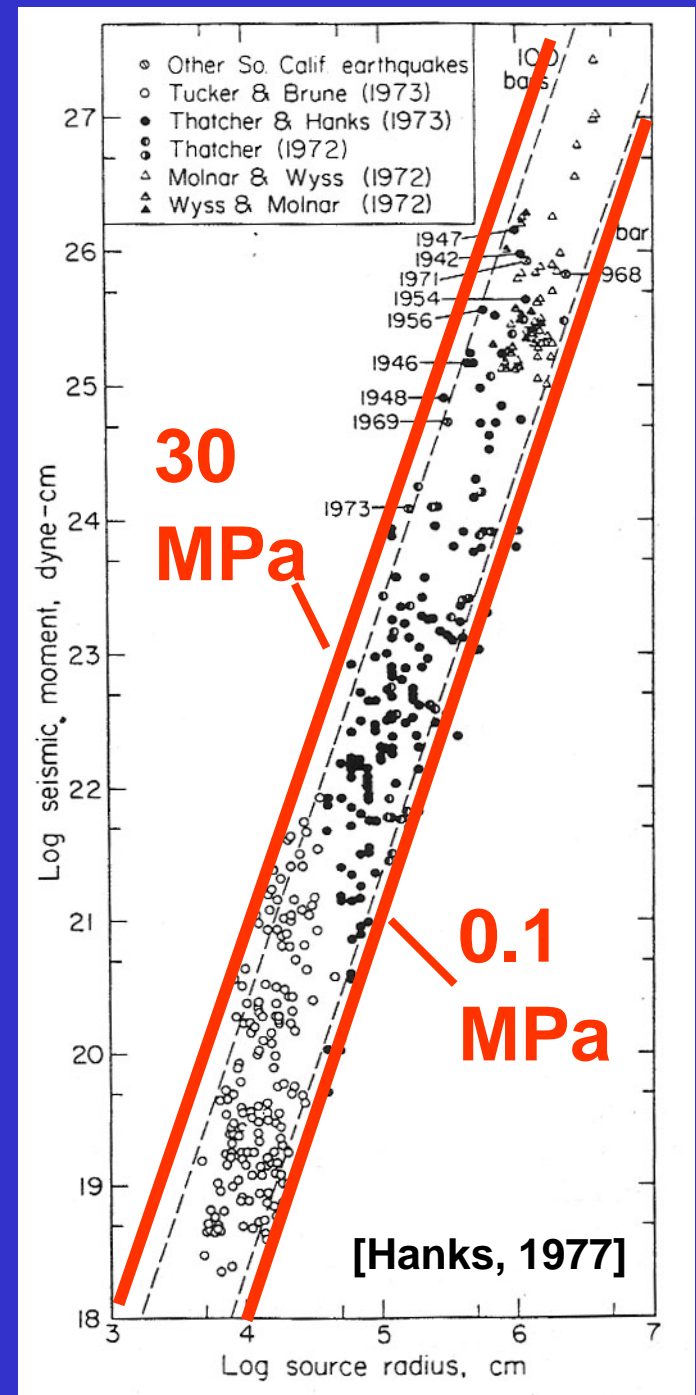
Possible answers:

~~3a) Someone is wrong.~~

3b) Dynamic stress drops ⌚  
static stress drops.

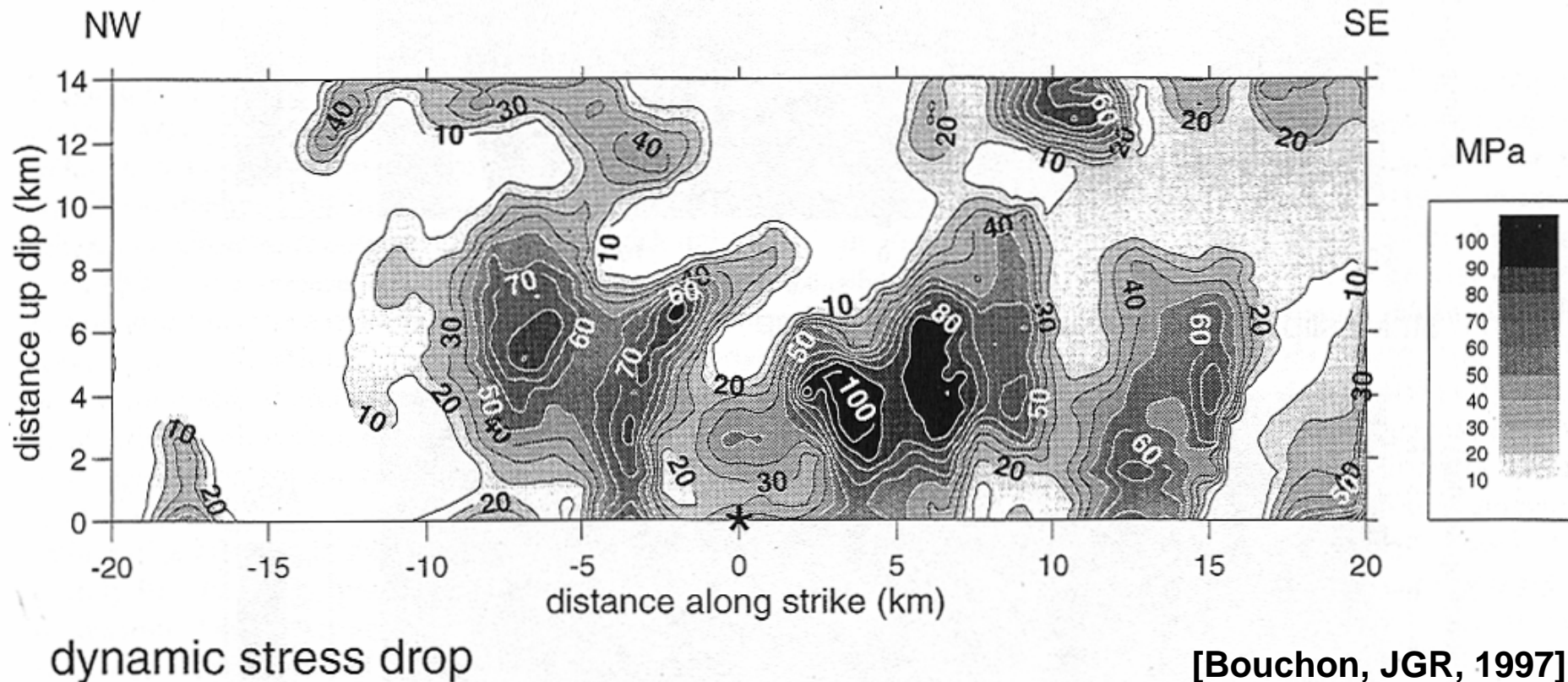
3c) Fault roughness

3d) Shear stress dependence  
with slip rate.



### 3b) Dynamic stress drops ⌚ static stress drops.

Bouchon (1997) estimated local dynamic stress drop as large as 100 MPa during the Loma Prieta (SAF) earthquake 1989,  $M_L = 6.9$





### 3c) Fault roughness

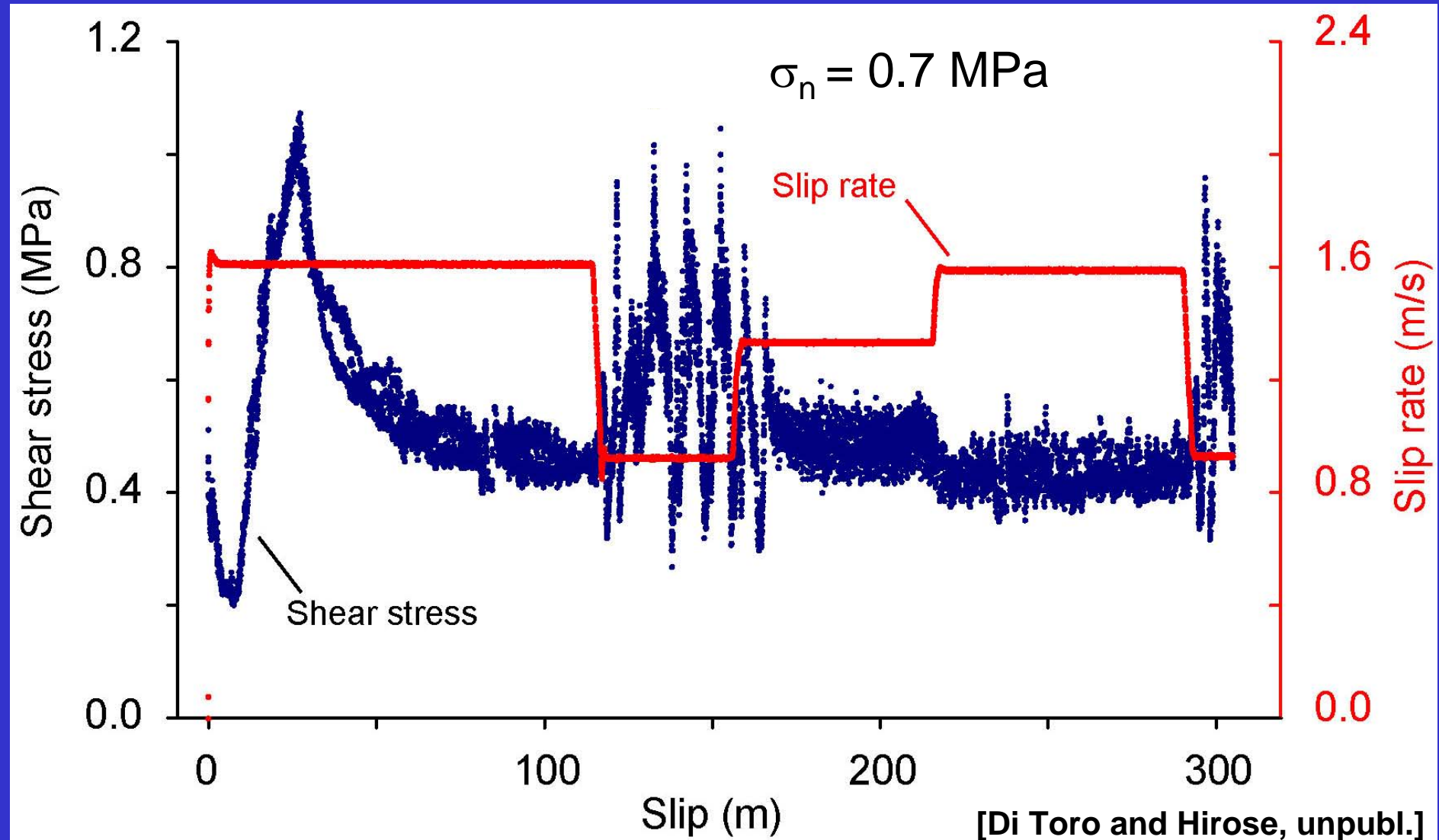


Natural faults are not as smooth as experimental sliding surfaces.

Bumps impede the smooth sliding typical of HVRFE

### 3d) Shear stress dependence for critical $v$

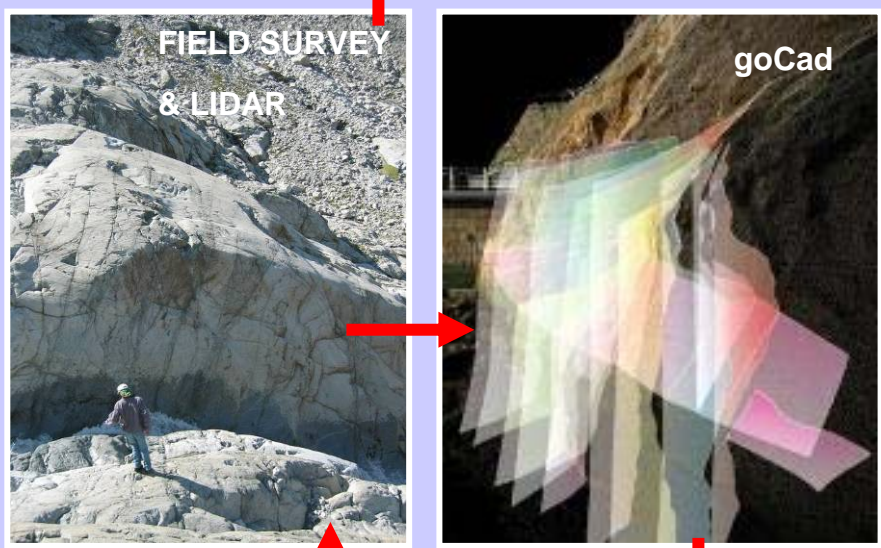
Example for melt lubrication (gabbro)



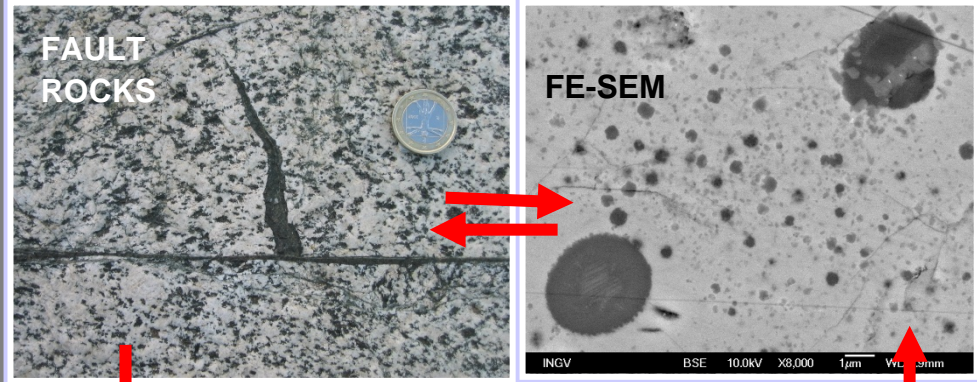


To extrapolate experimental  
results to natural conditions,  
maybe we should link....

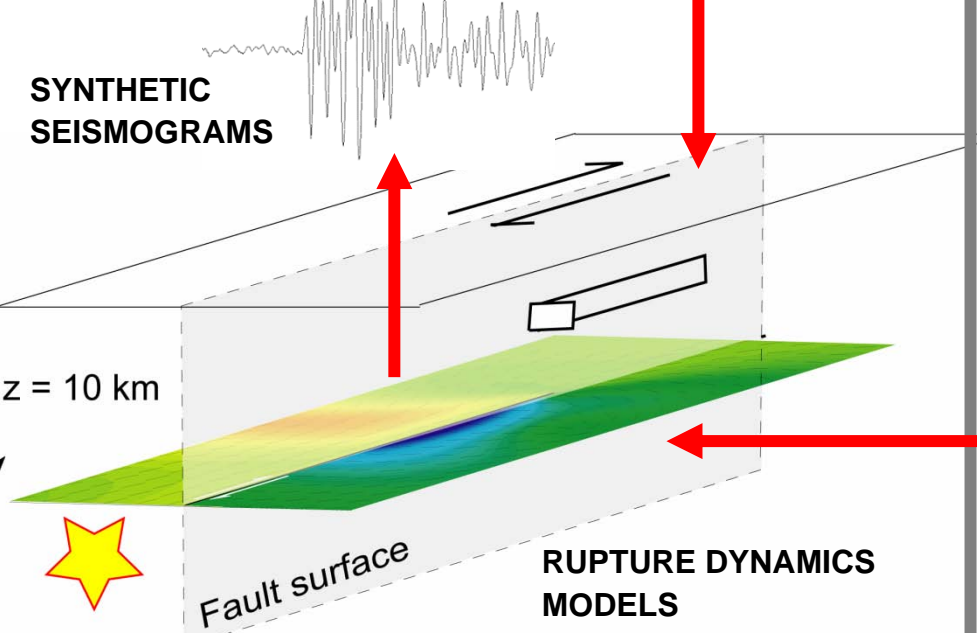
**FIELD STUDIES**



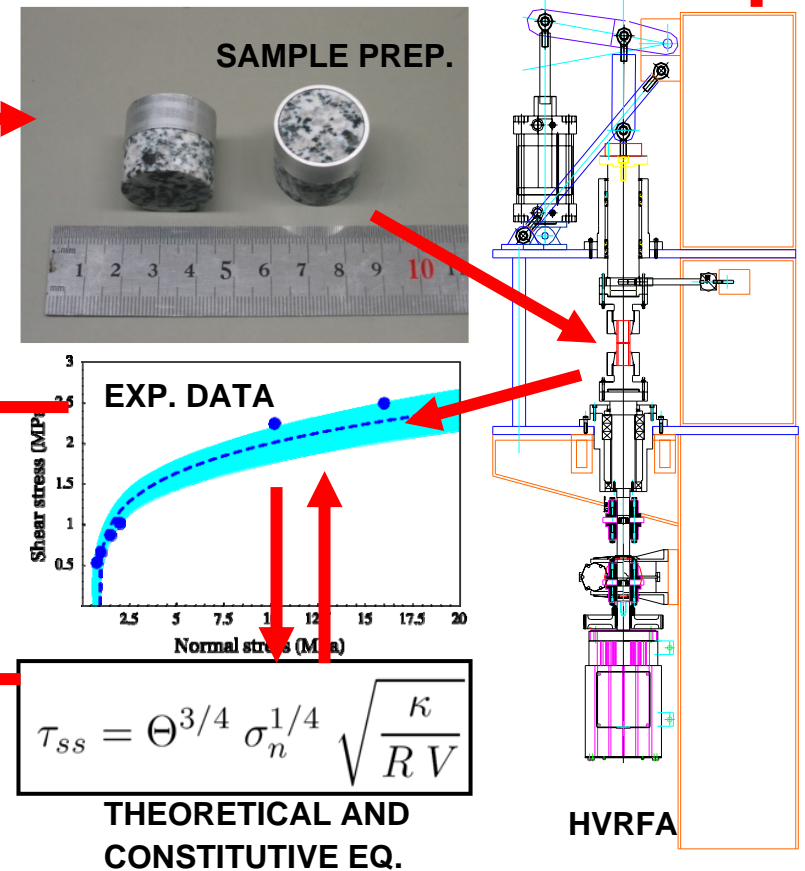
**MICROSTRUCTURAL ANALYSIS**



**MODELING**



**EXPERIMENTS & THEORY**



# Conclusions

- 1) Rocks have low  $\mu$  at seismic slip rates.
- 2) In some cases, experimental fault products are identical to natural ones.
- 3) HVRFE allow the determination of new rock friction constitutive equations.
- 4) Extrapolation of experimentally-derived results to dynamic rupture models is not trivial.

*“Go my sons, buy stout shoes, climb the mountains, search the valleys, the deserts, the sea shores, and the deep recess of the earth. Look for the various kinds of minerals, note their characters and mark their origin.*

*Lastly, buy coal, build furnaces, observe and experiment without ceasing, for in this way and in no other will you arrive at knowledge of the nature and properties of things”.*

*Marco Aurelio Severino, naturalist (1580-1656)*





# Main experimental results for $v < 10$ mm/s and $d < 1$ cm

- $\mu$  is 0.60 - 0.85 [*Byerlee*, 1978]
- $\mu$  varies of few % for small changes in slip rate
- $\mu$  is a function of sliding speed: rate- and state-dependent friction law (Dieterich-Ruina law)
- $D_c$  is tens to hundreds of microns max.

**NIED 2007**

**Designed by  
Mizoguchi &  
Shimamoto**

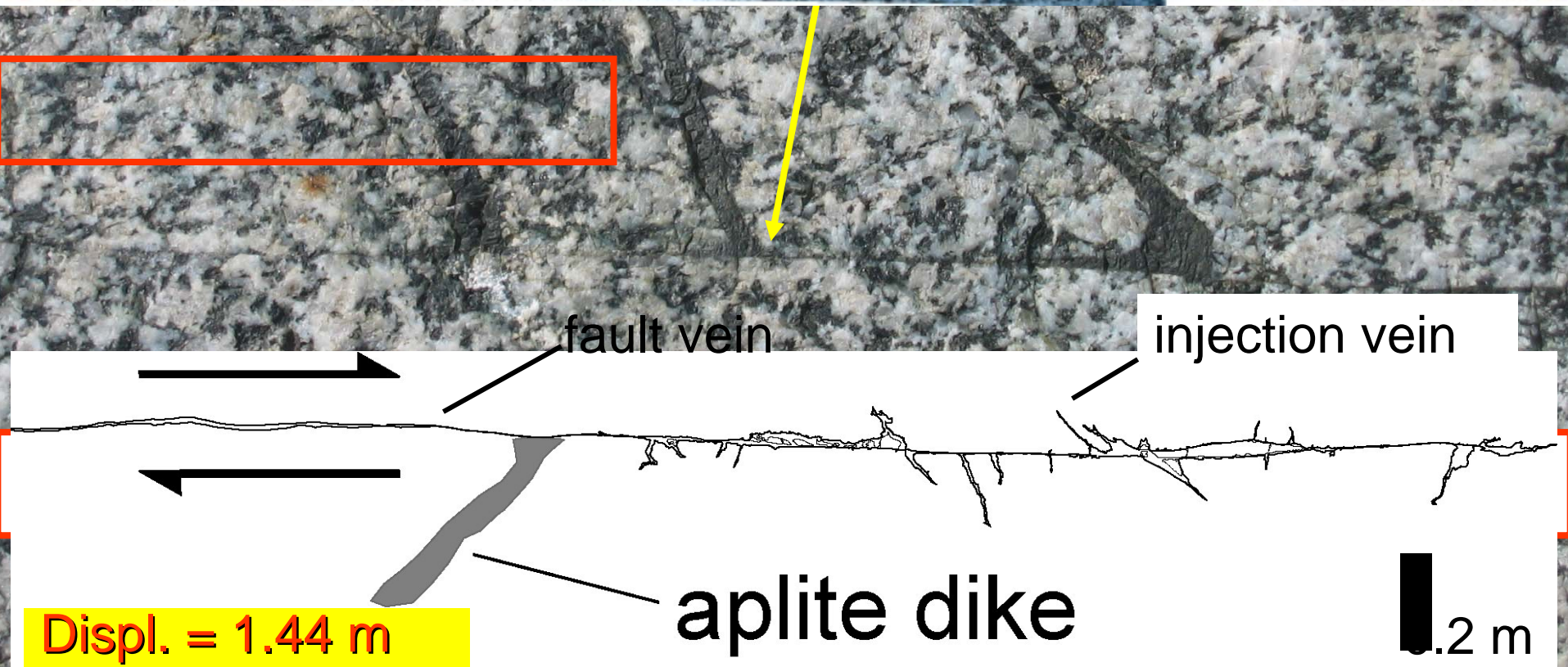
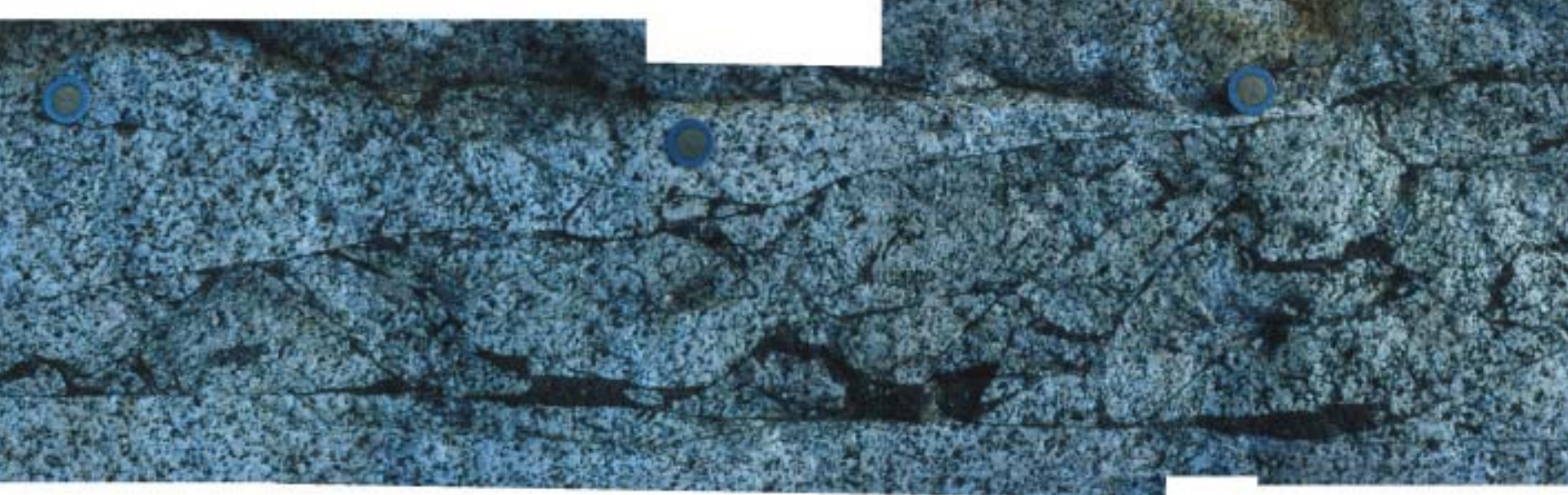
$$\sigma_n < 20 \text{ MPa}$$

$$v = 0.1 \text{ } \mu\text{m/s} - 10 \text{ m/s}$$

$$d = \text{infinite}$$

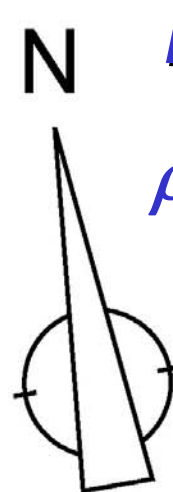
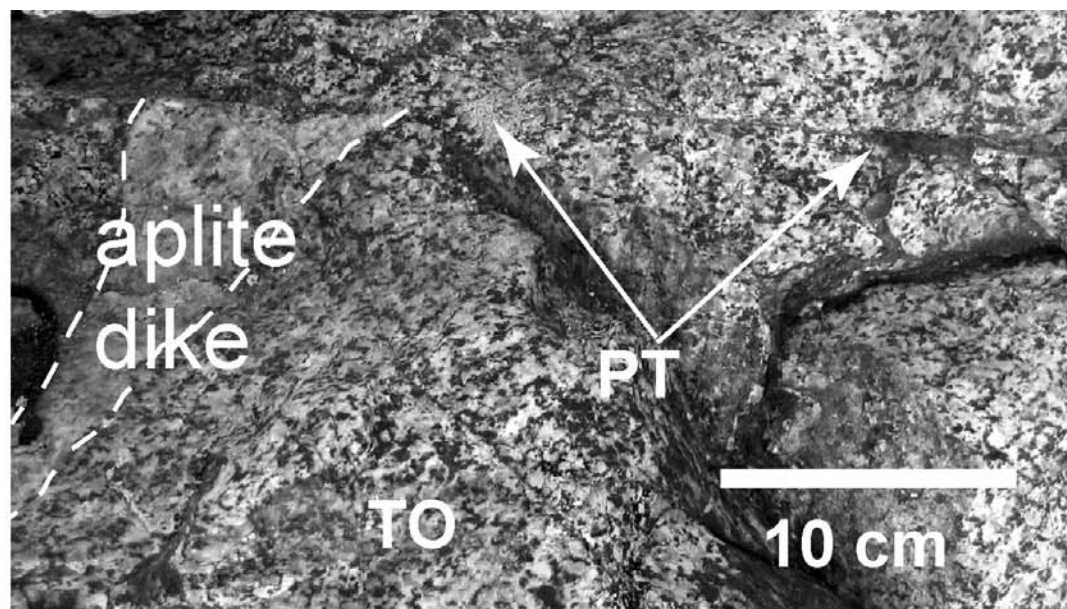






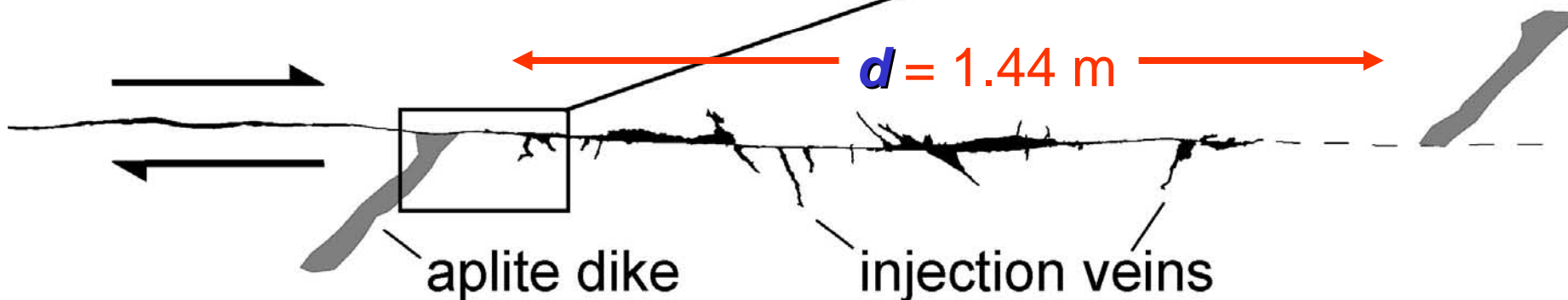


# Determination of average dynamic shear stress



$$E^* \approx 1.7 \text{ MJ/kg}$$

$$\rho = 2700 \text{ kg m}^{-3}$$



$$t = \text{area (PT)} / \text{fault length segment} = 5.9 \text{ mm}$$

$$\tau_{av} \approx (t / d) E^* \rho = 18.4 \text{ MPa}$$



# Estimate of $\tau_{av}$ from PT-bearing faults:

$$\tau_{av} \approx (t / d) E^* \rho \quad \text{in Pa}$$

[mod. from *Sibson*, 1975]

- $\tau_{av}$  average dynamic shear stress in Pa
- $t$  average pseudotachylite thickness in m
- $d$  coseismic fault displacement in m
- $E^*$  energy to heat and melt 1 kg of rock (1.7 MJ kg<sup>-1</sup>)
- $\rho$  rock density 2700 kg m<sup>-3</sup>

Main assumption:

All work done in faulting is converted to heat –fracture surface energy is negligible [Pittarello et al., S33-xxx]

# Energy $E$ to heat and melt a volume of rock

$$E = E_{\text{melt}} + E_{\text{heat}}$$

$$E = [c_{\text{pm}}(T) \Delta T + H] v_{\text{m}} / v_{\text{pt}} + [c_{\text{pcl}}(T) \Delta T] (v_{\text{pt}} - v_{\text{m}}) / v_{\text{pt}}$$

$H$

latent heat of fusion ( $\text{J kg}^{-1}$ )

$$\Delta T = T_{\text{melt}} - T_{\text{hr}}$$

temperature difference between host rock and PT (K)

$c_{\text{pm}}$

specific heat for friction-induced melt ( $\text{kJ K}^{-1} \text{mol}^{-1}$ )

$c_{\text{pcl}}$

specific heat for clasts ( $\text{kJ K}^{-1} \text{mol}^{-1}$ )

$v_{\text{m}} / v_{\text{pt}}$

matrix content

$(v_{\text{pt}} - v_{\text{m}}) / v_{\text{pt}}$

clast content

$$\text{if: } c_{\text{pm}}(T) \approx c_{\text{pcl}}(T)$$

$$E = [(v_{\text{m}} / v_{\text{pt}}) H + c_p(T) \Delta T] \quad \text{in J/kg}$$

Melted rock mass

$$M = \rho A t$$

$$Q = E M = [(v_{\text{m}} / v_{\text{pt}}) H + c_p(T) \Delta T] \rho A t \quad \text{in J}$$

$$W_f = \tau d A = Q$$

$$\tau d A = [(v_{\text{m}} / v_{\text{pt}}) H + c_p(T) \Delta T] \rho A t$$

$t$  = thickness

$d$  = displacement

$$\tau = \rho E (t / d) \quad \text{in Pa}$$

Temperature increase ca. 1200 °C

$$\tau_f \approx (t / d) \rho E^*$$

$$E^* = \gamma H + c_p (T_m - T_{hr}) \quad \text{in J/kg}$$

$$T_{\text{host rock}} = 250\text{-}300 \text{ }^{\circ}\text{C}$$

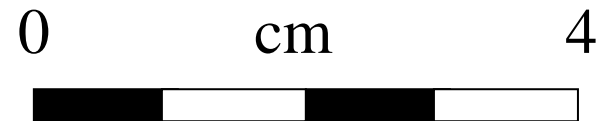
$$T_{\text{melt}} = 1400\text{-}1500 \text{ }^{\circ}\text{C}$$

Tonalite

PT [

Tonalite

[Di Toro and Pennacchioni, JSG, 2004]





# Pseudotachylyte in thin section

PT matrix is 80% in volume:  $\gamma = 0.8$

[Di Toro and Pennacchioni, JSG, 2004]

$$\tau_f \approx (t / d) \rho E^*$$

$$E^* = \gamma H + c_p (T_m - T_{hr}) \quad \text{in J/kg}$$

pseudotachylyte  
matrix

survivor  
clasts

**Heat exchanged**

$$E^* = 1.7 \cdot 10^6 \text{ J/kg}$$

300  $\mu\text{m}$



Di Toro & Pennacchioni, Tectonophysics, 2005



550 m

**Gole Larghe Fault  
(Italian Southern Alps)**

Lobbia Glacier

**Seismic source  
3D architecture**

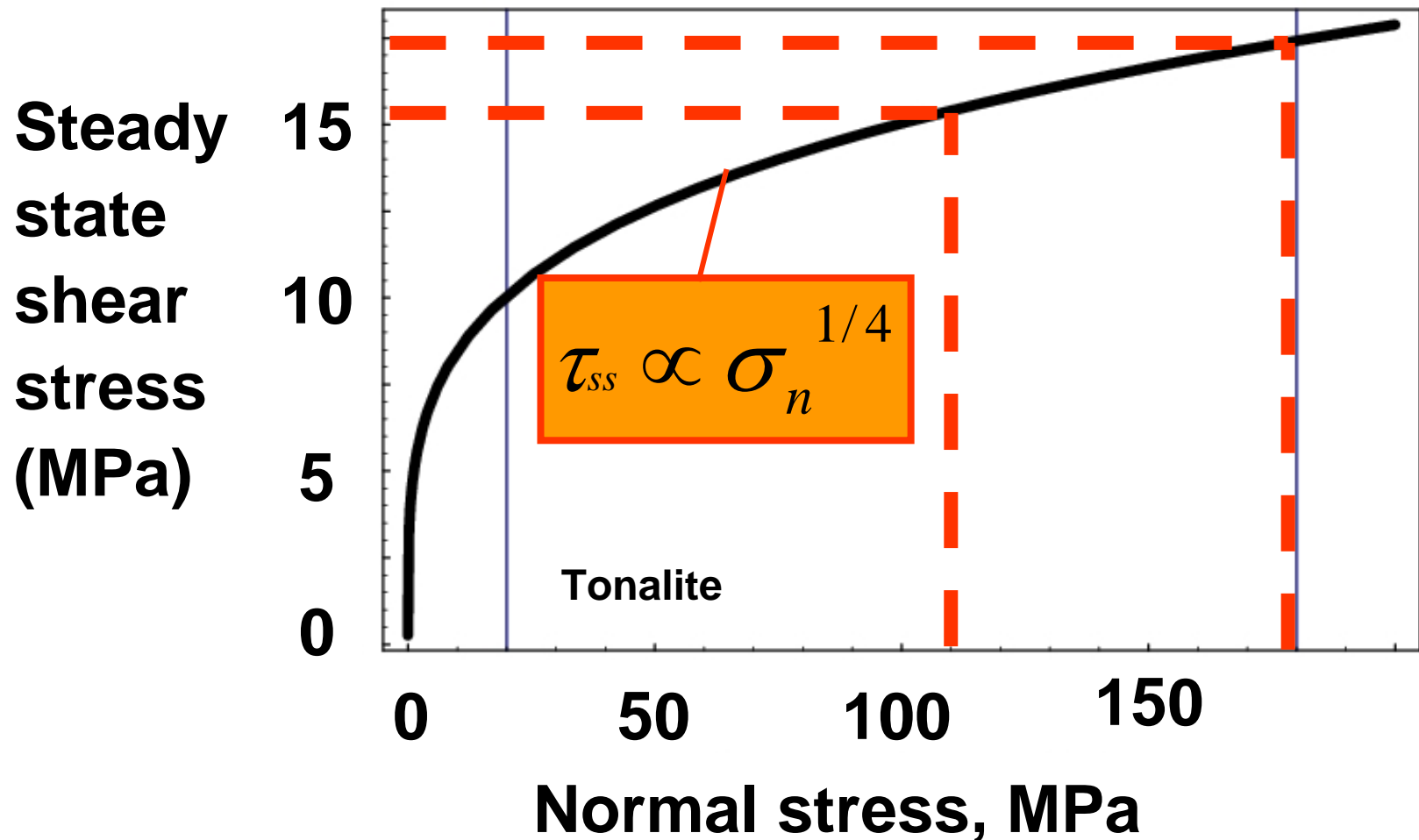




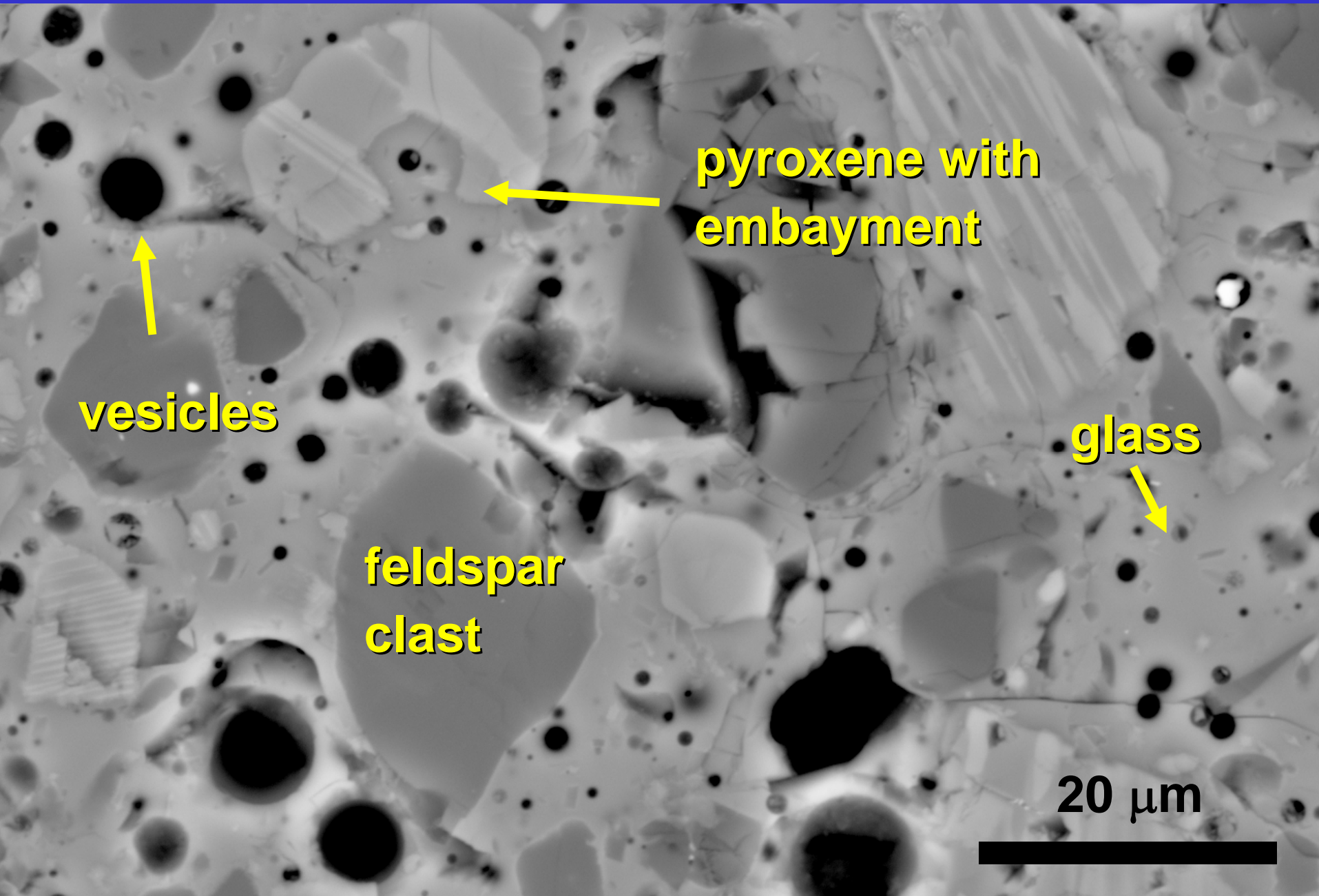
# Estimate for $\tau_{ss}$ at 10km depth ~ **16 MPa**

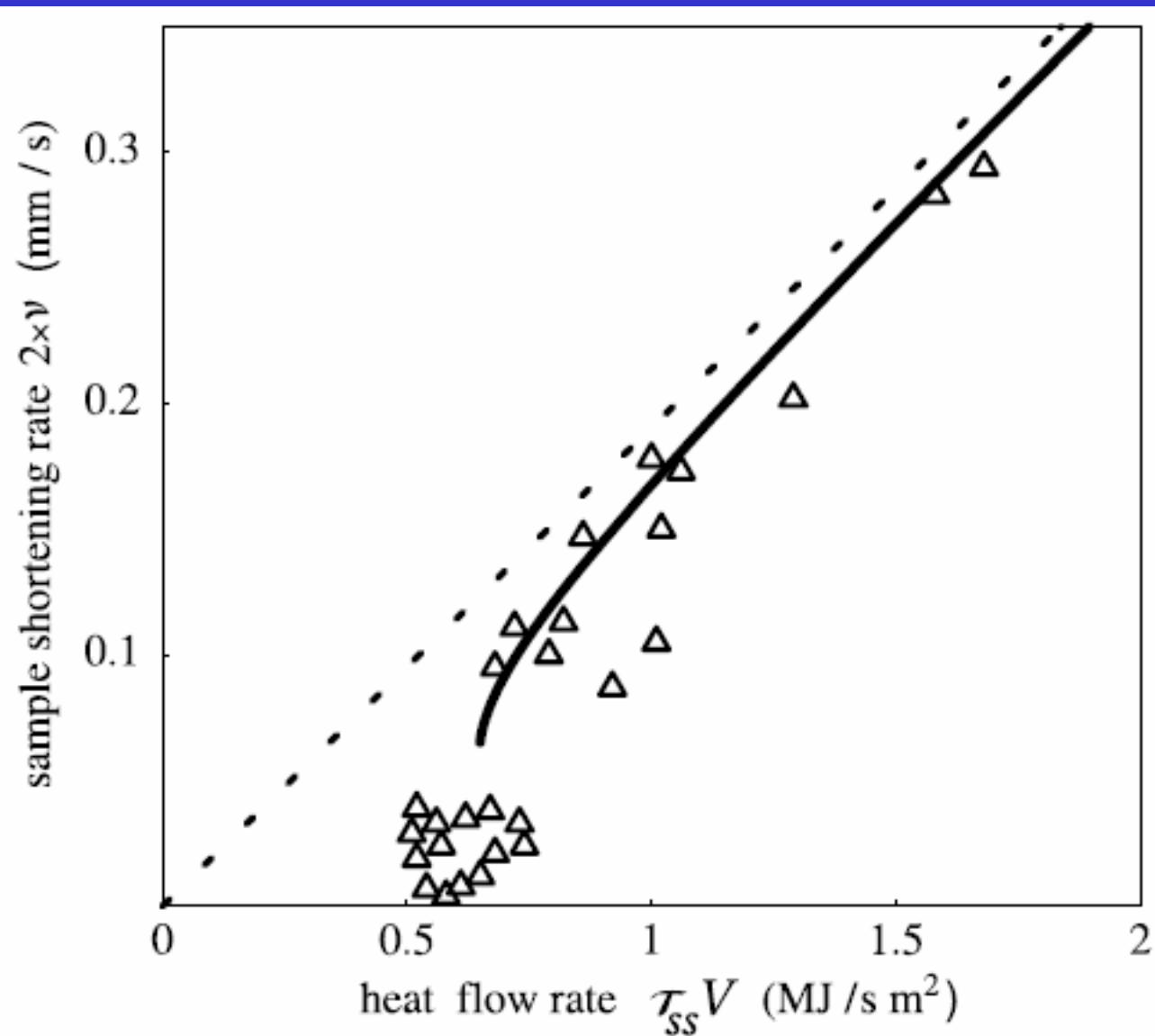
$\tau_{ss} \sim 15\text{-}17.5$  MPa

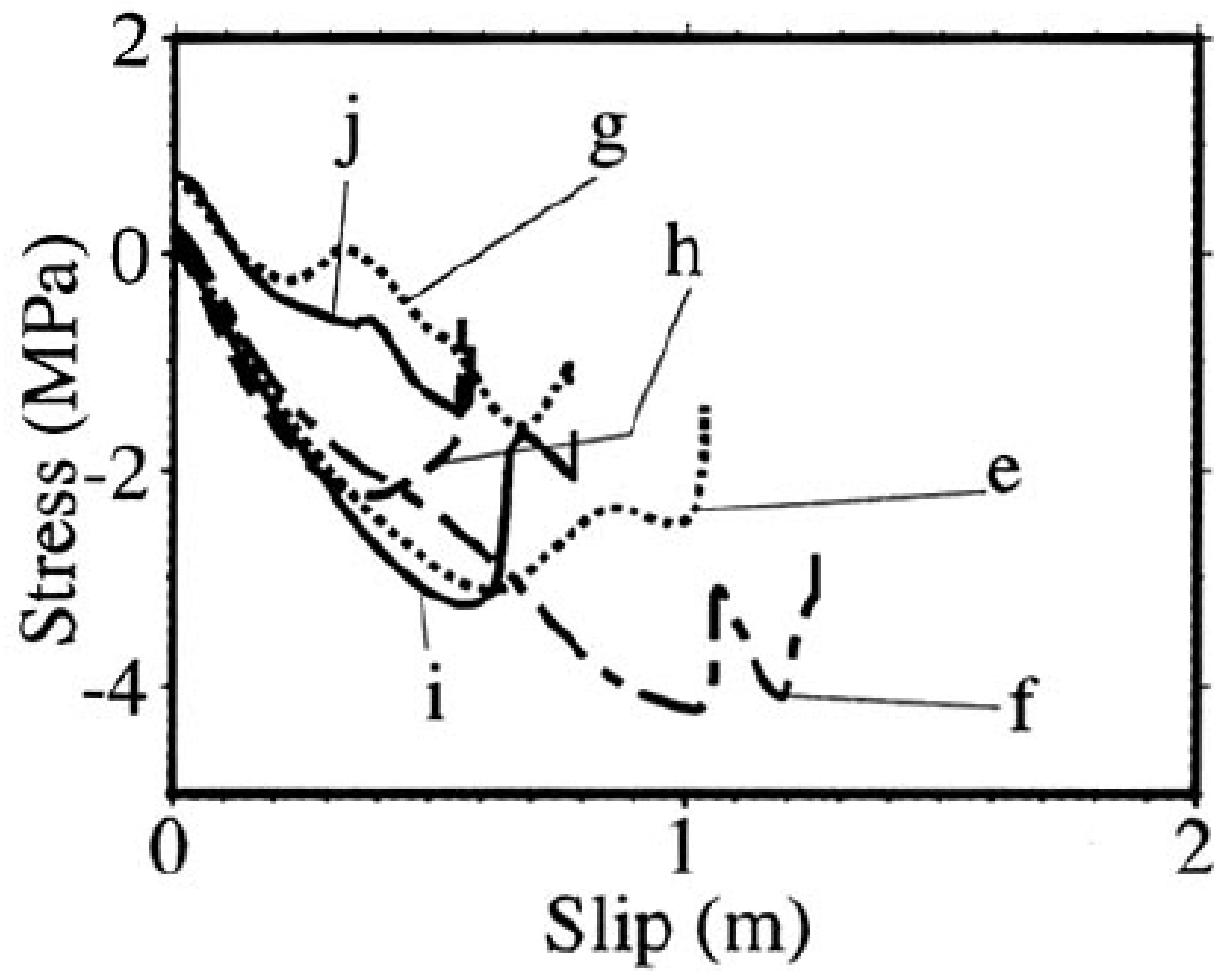
For  $\sigma_n \sim 150$  MPa and  $V = 1$  m/s



# SEM image of the slipping zone after the exp.









**We determined displ.  $d$  from separations**

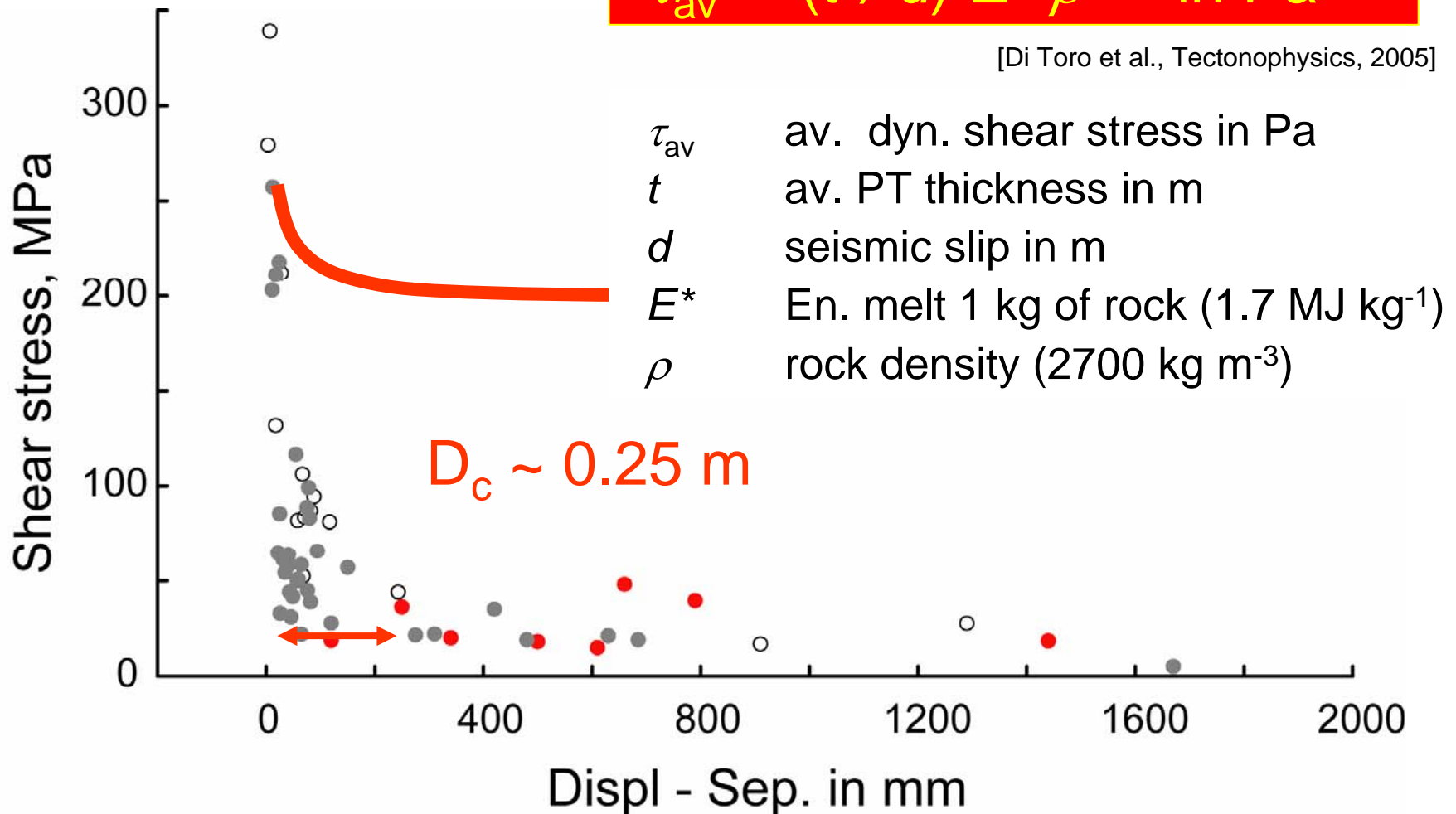




# Slip weakening distance in the presence of melt

$$\tau_{av} \approx (t / d) E^* \rho \quad \text{in Pa}$$

[Di Toro et al., Tectonophysics, 2005]



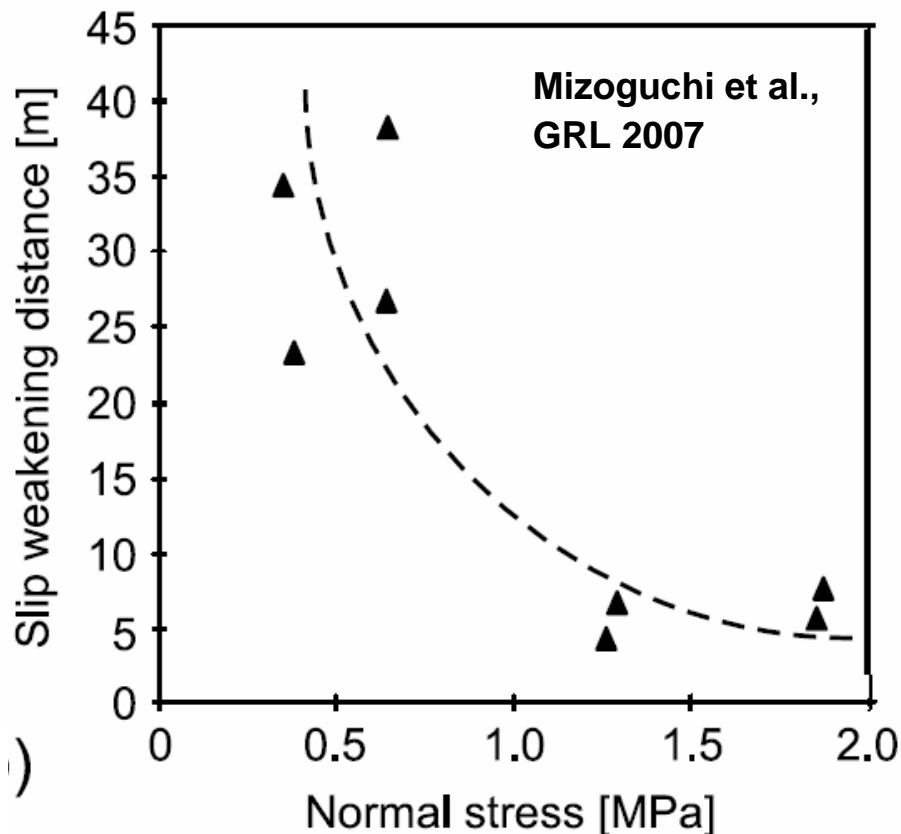
**$D_c$  of 0.25 m is consistent with estimates from independent theoretical analyses** (see also Di Toro et al., S33A-0220 and Nielsen et al., S33B-0238)

$$D_c = 8 \kappa [\rho [H + c_p (T_m - T_{hr})] / \tau]^2 / V$$

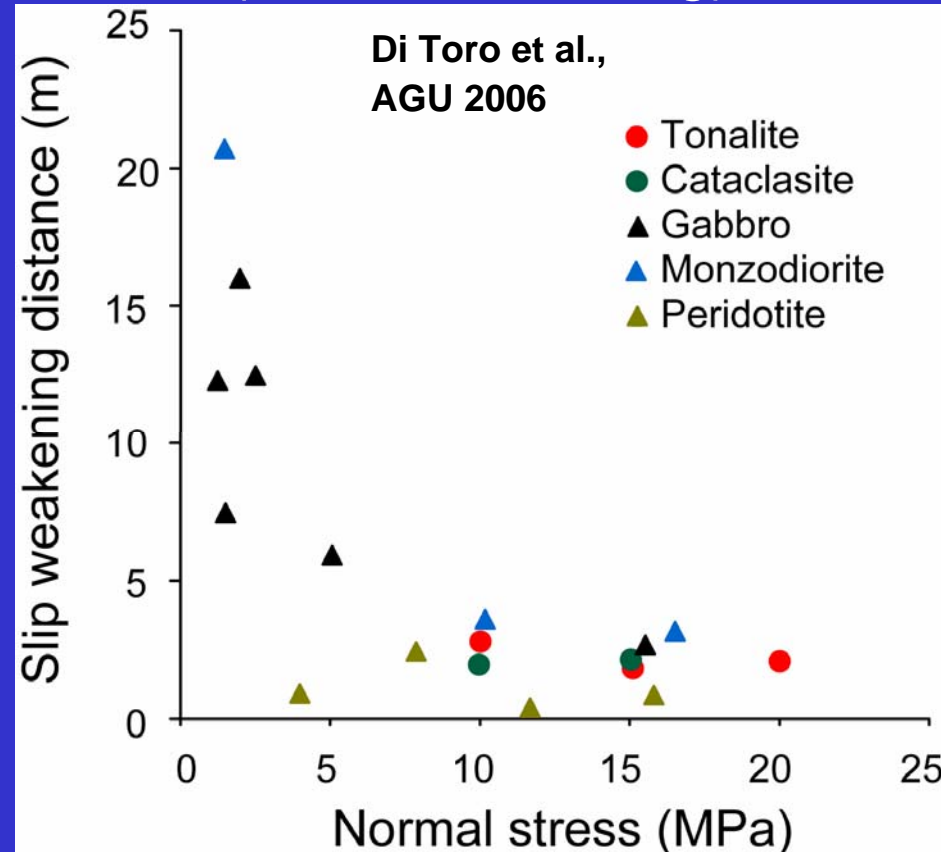
$\kappa$	thermal diffusivity ( $1.8 \cdot 10^{-6} \text{ m}^2 \text{ s}^{-1}$ )
$\rho$	rock density ( $2700 \text{ kg m}^{-3}$ )
$H$	latent heat of fusion ( $3.3 \cdot 10^5 \text{ J kg}^{-1}$ )
$c_p$	specific heat ( $1180 \text{ J kg}^{-1} \text{ K}^{-1}$ )
$T_m$	melt temp. ( $\sim 1450 \text{ }^\circ\text{C}$ )
$T_{hr}$	host rock temp. ( $\sim 250 \text{ }^\circ\text{C}$ )
$\tau$	shear stress (22 MPa)
$V$	slip rate ( $1 \text{ m s}^{-1}$ )

How can we extrapolate HVRFE to nature?  
Dc decreases with increasing normal stress  
towards seismically inferred Dc (~1 m)

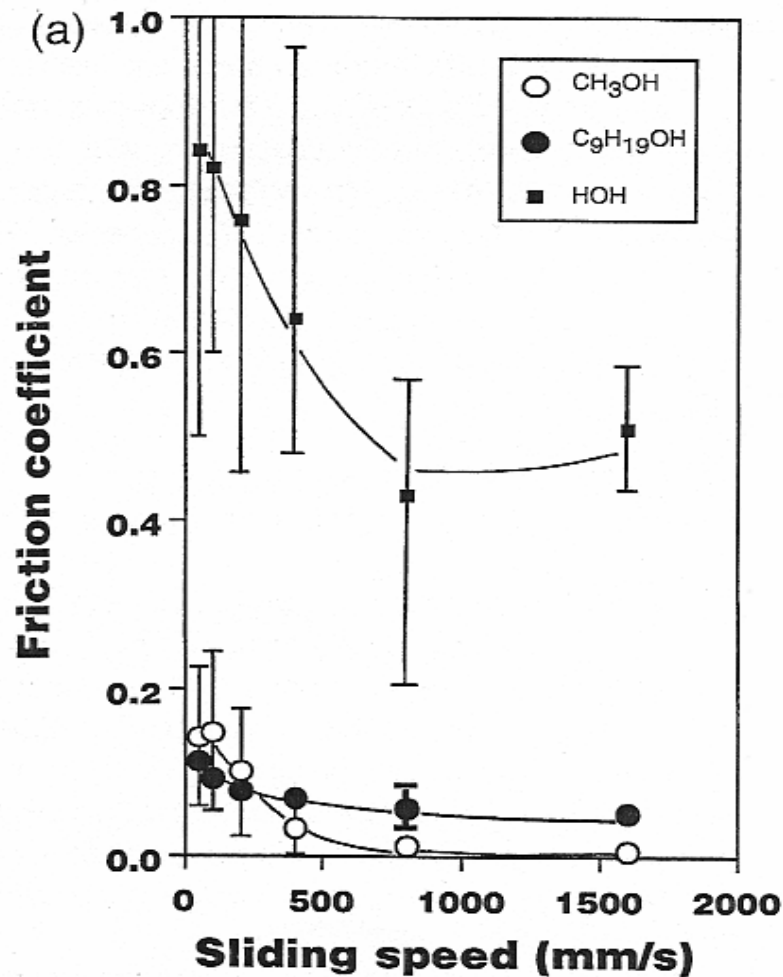
Non-cohesive rocks  
(Nojima Fault Gouge)



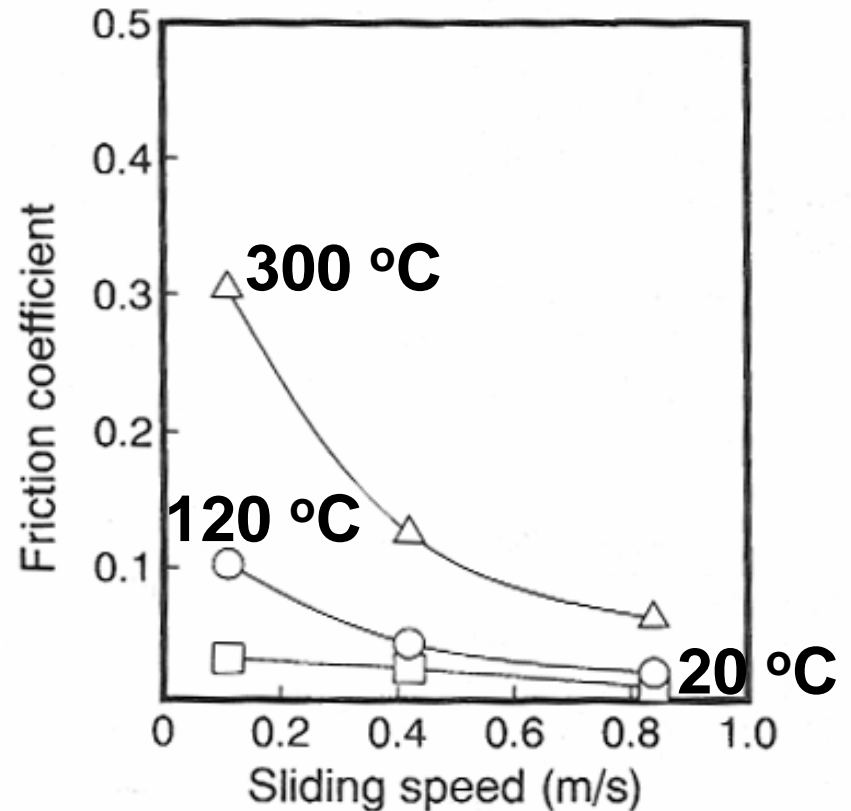
Cohesive rocks  
(frictional melting)



# Tribochemical reactions: velocity weakening in Si-bearing compounds



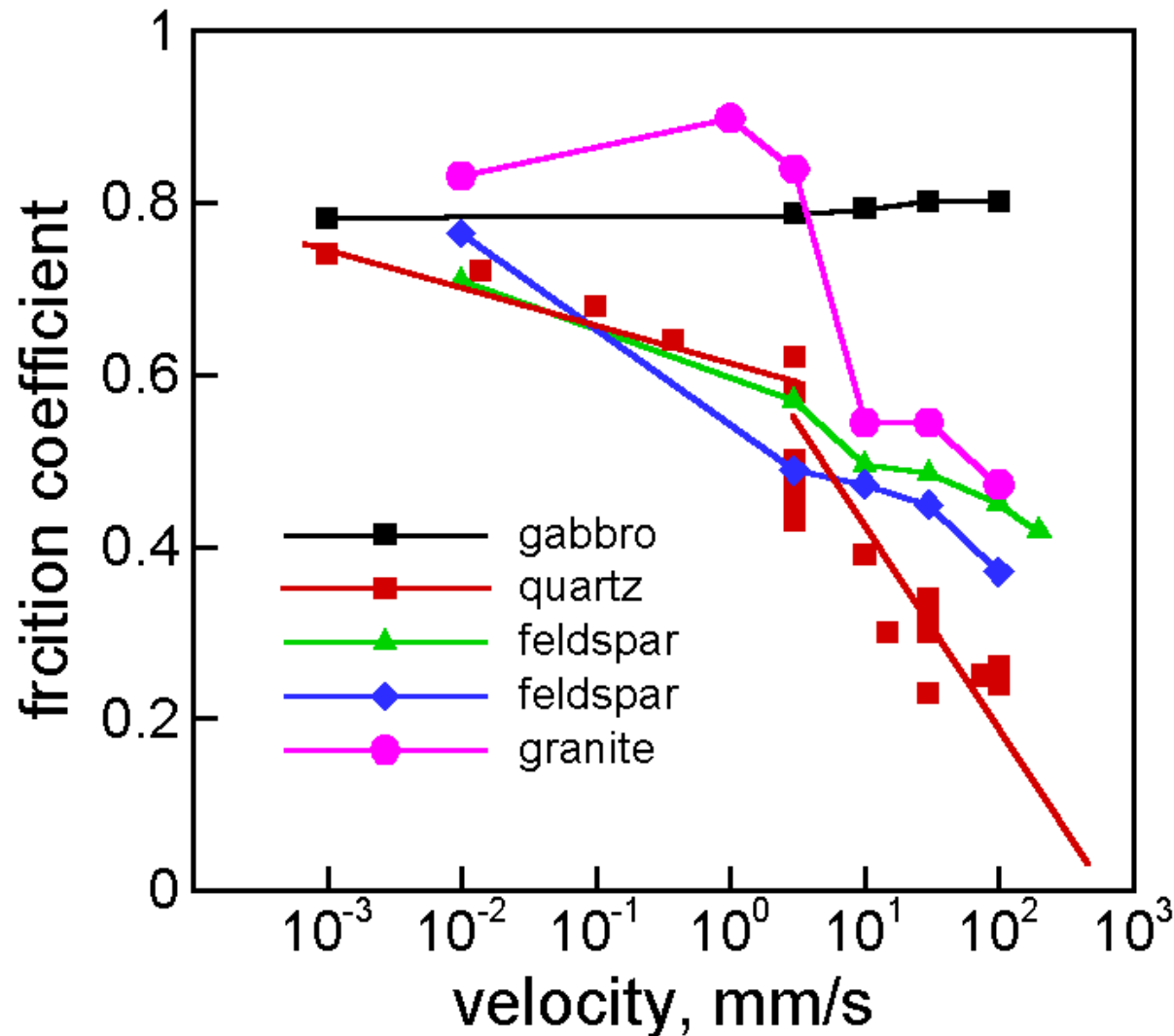
Si<sub>3</sub>N<sub>4</sub> in H<sub>2</sub>O and alcohol  
(Hibi & Enomoto, 1999, Wear)



SiC in H<sub>2</sub>O  
(Kitaoka et al., 1994,  
J. Am.Ceram. Soc.)

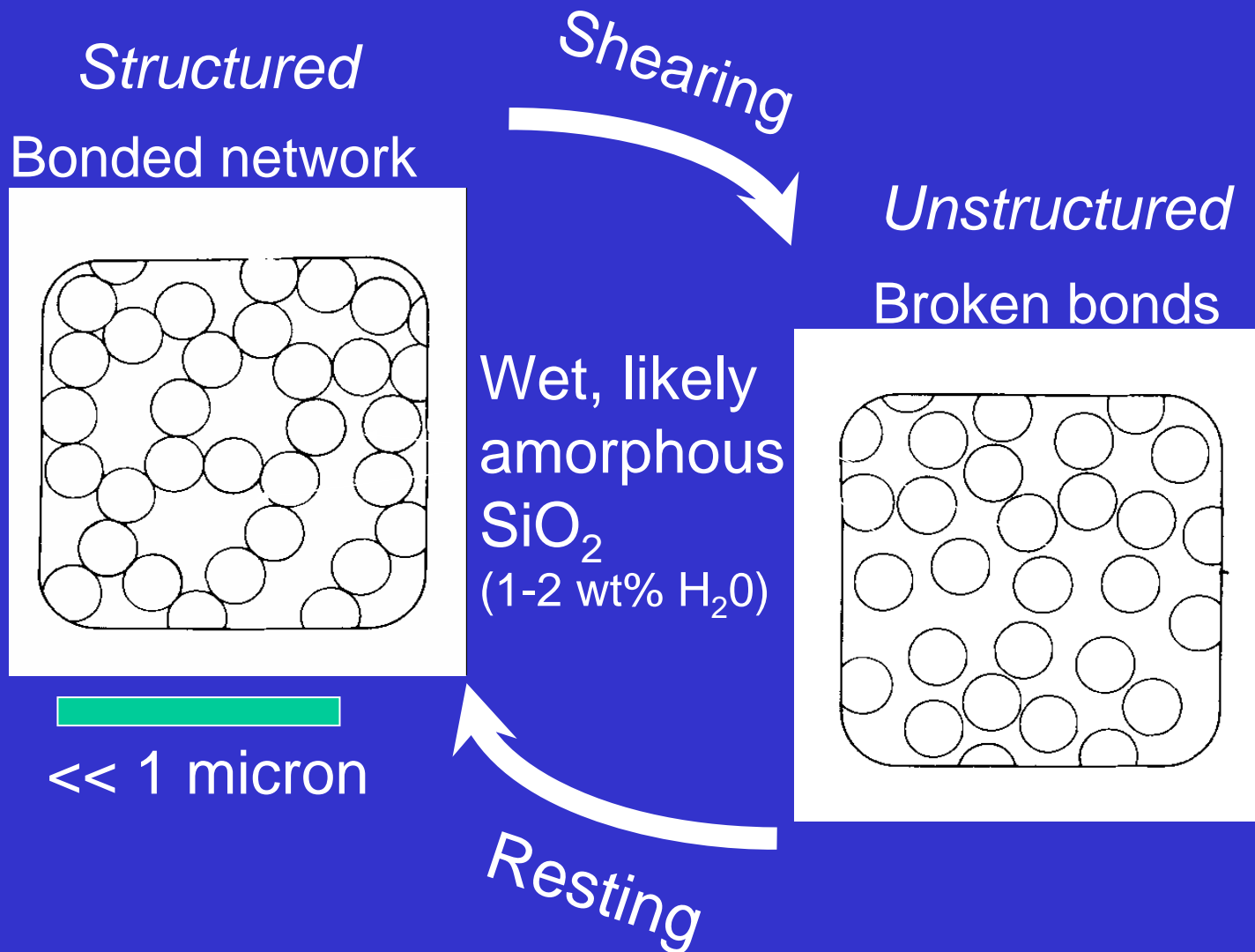


# Many crustal rocks weaken at high slip rates



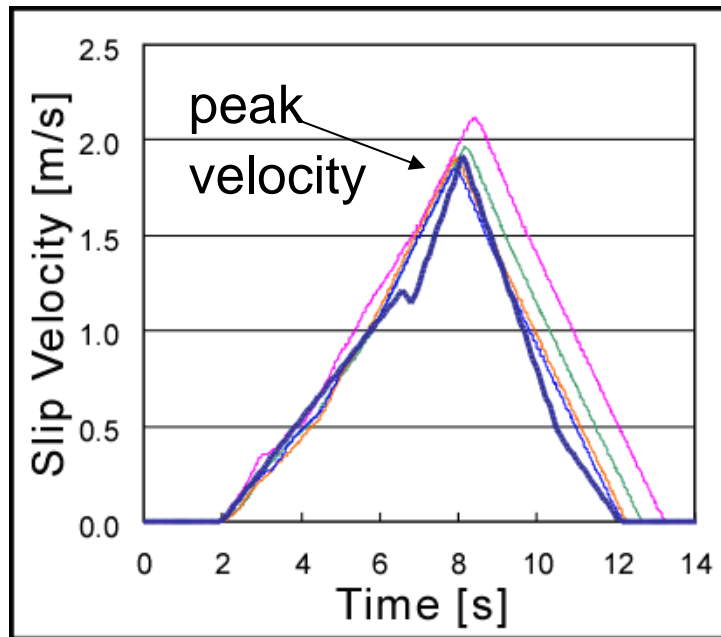
[Roig Silva et al., AGU 2004]

# Thixotropy of silica gel



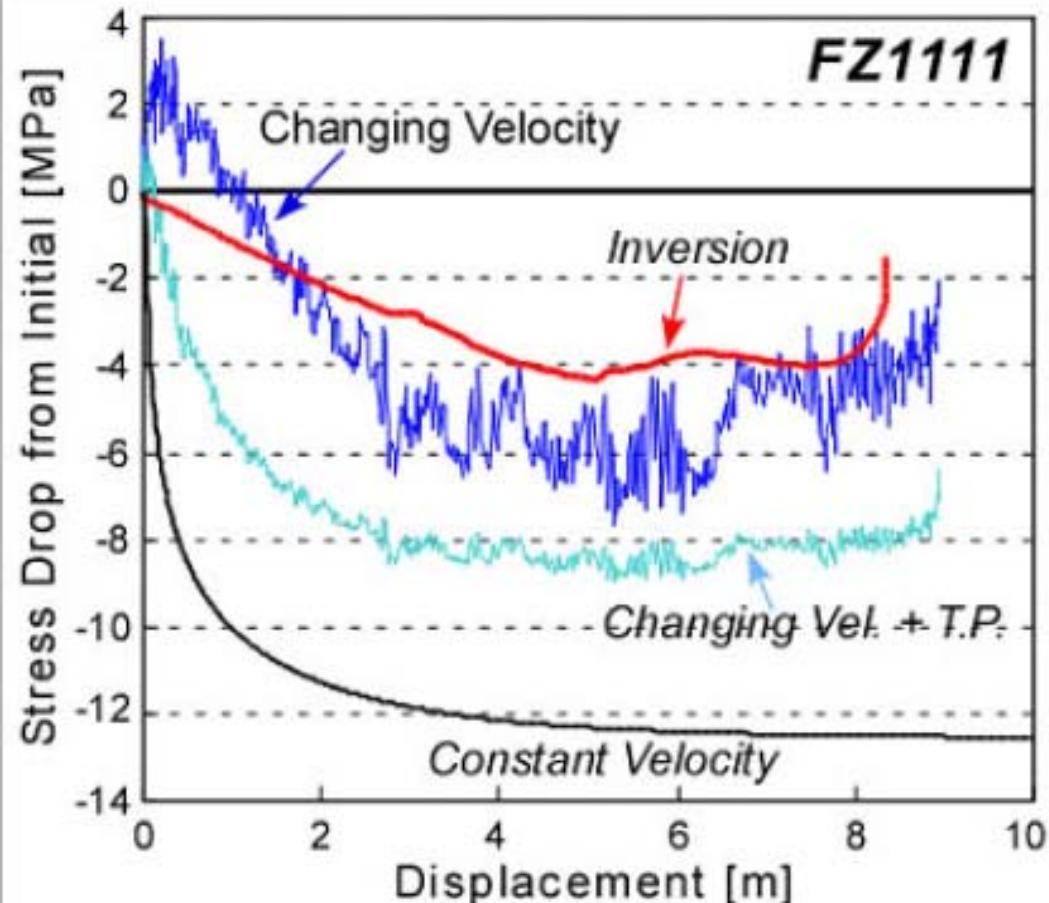
Stress drops determined by reproducing inversion-derived particle vel. (Chi-Chi 1999 EQ, Ma et al.) are smaller than those obtained at constant slip rate (1 m/s).

### Inversion-Derived Particle Vel.



Sone et al., AGU 2005

### Normal Stress: 0.6 MPa Clayey Fault Gouge



# Slip rate and shear stress determination in solid specimens: equivalent slip velocity

$$v_e = \frac{4\pi R r_2}{3}$$

$R$  = rotary speed

$r_2$  = outer sample radius

$$\tau = \frac{3 M}{2\pi r_2^3}$$

$M$  = torque

Cylindrical and hollow shaped specimens yield very similar results.

As aluminum melts at 650 °C, the external aluminum outer ring sustains the sample during initial sliding only.